

DS90C387, DS90CF388 Dual Pixel LVDS Display Interface (LDI)-SVGA/QXGA

Check for Samples: [DS90C387](#), [DS90CF388](#)

FEATURES

- Complies with OpenLDI Specification for Digital Display Interfaces
- 32.5 to 112/170MHz Clock Support for DS90C387, 40 to 112MHz Clock Support for DS90CF388
- Supports SVGA through QXGA Panel Resolutions
- Drives Long, Low Cost Cables
- Up to 5.38Gbps Bandwidth
- Pre-Emphasis Reduces Cable Loading Effects
- DC Balance Data Transmission Provided by Transmitter Reduces ISI Distortion
- Cable Deskew of +/-1 LVDS Data Bit Time (up to 80 MHz Clock Rate) of Pair-to-Pair Skew at Receiver Inputs; Intra-Pair Skew Tolerance of 300ps
- Dual Pixel Architecture Supports Interface to GUI and Timing Controller; Optional Single Pixel Transmitter Inputs Support Single Pixel GUI Interface
- Transmitter Rejects Cycle-to-Cycle Jitter
- 5V Tolerant on Data and Control Input Pins
- Programmable Transmitter Data and Control Strobe Select (Rising or Falling Edge Strobe)
- Backward Compatible Configuration Select with FPD-Link
- Optional Second LVDS Clock for Backward Compatibility w/ FPD-Link
- Support for Two Additional User-Defined Control Signals in DC Balanced Mode
- Compatible with ANSI/TIA/EIA-644-1995 LVDS Standard

DESCRIPTION

The DS90C387/DS90CF388 transmitter/receiver pair is designed to support dual pixel data transmission between Host and Flat Panel Display up to QXGA resolutions. The transmitter converts 48 bits (Dual Pixel 24-bit color) of CMOS/TTL data into 8 LVDS (Low Voltage Differential Signalling) data streams. Control signals (VSYNC, HSYNC, DE and two user-defined signals) are sent during blanking intervals. At a maximum dual pixel rate of 112MHz, LVDS data line speed is 672Mbps, providing a total throughput of 5.38Gbps (672 Megabytes per second). Two other modes are also supported. 24-bit color data (single pixel) can be clocked into the transmitter at a maximum rate of 170MHz. In this mode, the transmitter provides single-to-dual pixel conversion, and the output LVDS clock rate is 85MHz maximum. The third mode provides inter-operability with FPD-Link devices.

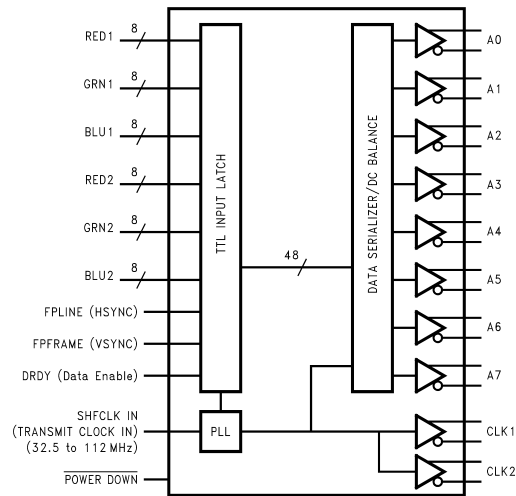
The LDI chipset is improved over prior generations of FPD-Link devices and offers higher bandwidth support and longer cable drive with three areas of enhancement. To increase bandwidth, the maximum pixel clock rate is increased to 112 (170) MHz and 8 serialized LVDS outputs are provided. Cable drive is enhanced with a user selectable pre-emphasis feature that provides additional output current during transitions to counteract cable loading effects. DC balancing on a cycle-to-cycle basis, is also provided to reduce ISI (Inter-Symbol Interference). With pre-emphasis and DC balancing, a low distortion eye-pattern is provided at the receiver end of the cable. A cable deskew capability has been added to deskew long cables of pair-to-pair skew of up to +/-1 LVDS data bit time (up to 80 MHz Clock Rate). These three enhancements allow cables 5+ meters in length to be driven. This chipset is an ideal means to solve EMI and cable size problems for high-resolution flat panel applications. It provides a reliable interface based on LVDS technology that delivers the bandwidth needed for high-resolution panels while maximizing bit times, and keeping clock rates low to reduce EMI and shielding requirements. For more details, please refer to [Applications Information](#).



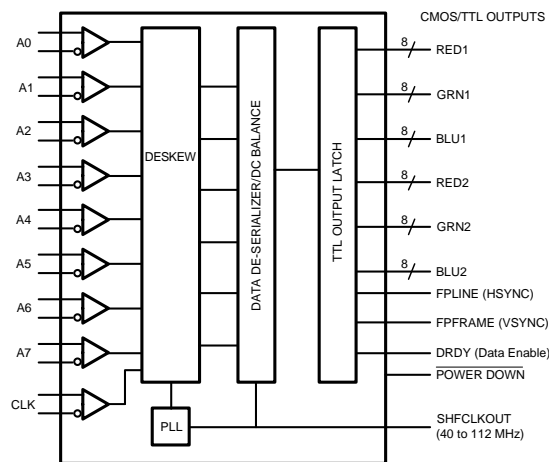
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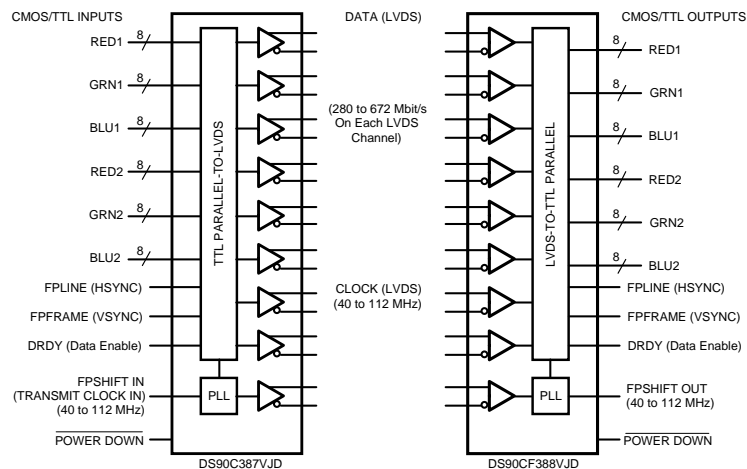
Transmitter Block Diagram



Receiver Block Diagram



Generalized Block Diagram





These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

Absolute Maximum Ratings⁽¹⁾⁽²⁾

| | | | |
|--|-----------|------------------------------|-----------------------|
| Supply Voltage (V_{CC}) | | -0.3V to +4V | |
| CMOS/TTL Input Voltage | | -0.3V to +5.5V | |
| CMOS/TTL Output Voltage | | -0.3V to ($V_{CC} + 0.3V$) | |
| LVDS Receiver Input Voltage | | -0.3V to +3.6V | |
| LVDS Driver Output Voltage | | -0.3V to +3.6V | |
| LVDS Output Short Circuit Duration | | Continuous | |
| Junction Temperature | | +150°C | |
| Storage Temperature | | -65°C to +150°C | |
| Lead Temperature (Soldering, 4 seconds) | | +260°C | |
| Maximum Package Power Dissipation Capacity at 25°C, 100 TQFP Package | | DS90C387 | 2.8W |
| | | DS90CF388 | 2.8W |
| Package Derating | | DS90C387 | 18.2mW/°C above +25°C |
| | | DS90CF388 | 18.2mW/°C above +25°C |
| ESD Rating | DS90C387 | HBM, 1.5kΩ, 100pF | > 6 kV |
| | | EIAJ, 0Ω, 200pF | > 300 V |
| | DS90CF388 | HBM, 1.5kΩ, 100pF | > 2 kV |
| | | EIAJ, 0Ω, 200pF | > 200 V |

- (1) "Absolute Maximum Ratings" are those values beyond which the safety of the device cannot be ensured. They are not meant to imply that the device should be operated at these limits. The tables of "Electrical Characteristics" specify conditions for device operation.
- (2) If Military/Aerospace specified devices are required, please contact the Texas Instruments Sales Office/ Distributors for availability and specifications.

Recommended Operating Conditions

| | Min | Nom | Max | Unit |
|--|-----|-----|-----|-------------------|
| Supply Voltage (V_{CC}) | 3.0 | 3.3 | 3.6 | V |
| Operating Free Air Temperature (T_A) | -10 | +25 | +70 | °C |
| Receiver Input Range | 0 | | 2.4 | V |
| Supply Noise Voltage (V_{CC}) | | | 100 | mV _{p-p} |

Electrical Characteristics⁽¹⁾

Over recommended operating supply and temperature ranges unless otherwise specified.

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit |
|---|------------------------------|-----------------------------------|-----|-------|------|------|
| CMOS/TTL DC SPECIFICATIONS (Tx inputs, Rx outputs, control inputs and outputs) | | | | | | |
| V_{IH} | High Level Input Voltage | | 2.0 | | 5.0 | V |
| V_{IL} | Low Level Input Voltage | | GND | | 0.8 | V |
| V_{OH} | High Level Output Voltage | $I_{OH} = -0.4$ mA | 2.7 | 2.9 | | V |
| | | $I_{OH} = -2$ mA | 2.7 | 2.85 | | V |
| V_{OL} | Low Level Output Voltage | $I_{OL} = 2$ mA | | 0.1 | 0.3 | V |
| V_{CL} | Input Clamp Voltage | $I_{CL} = -18$ mA | | -0.79 | -1.5 | V |
| I_{IN} | Input Current | $V_{IN} = 0.4V, 2.5V$ or V_{CC} | | +1.8 | +15 | μA |
| | | $V_{IN} = GND$ | -15 | 0 | | μA |
| I_{OS} | Output Short Circuit Current | $V_{OUT} = 0V$ | | | -120 | mA |

- (1) Current into device pins is defined as positive. Current out of device pins is defined as negative. Voltages are referenced to ground unless otherwise specified (except V_{OD} and ΔV_{OD}).

Electrical Characteristics⁽¹⁾ (continued)

Over recommended operating supply and temperature ranges unless otherwise specified.

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit | |
|--|--|--|------------------------|---------|----------|---------|----|
| LVDS DRIVER DC SPECIFICATIONS | | | | | | | |
| V_{OD} | Differential Output Voltage | $R_L = 100\Omega$ | 250 | 345 | 450 | mV | |
| ΔV_{OD} | Change in V_{OD} between Complimentary Output States | | | | 35 | mV | |
| V_{OS} | Offset Voltage | | 1.125 | 1.25 | 1.375 | V | |
| ΔV_{OS} | Change in V_{OS} between Complimentary Output States | | | | 35 | mV | |
| I_{OS} | Output Short Circuit Current | $V_{OUT} = 0V, R_L = 100\Omega$ | | -3.5 | -10 | mA | |
| I_{OZ} | Output TRI-STATE Current | $\overline{PD} = 0V, V_{OUT} = 0V \text{ or } V_{CC}$ | | ± 1 | ± 10 | μA | |
| LVDS RECEIVER DC SPECIFICATIONS | | | | | | | |
| V_{TH} | Differential Input High Threshold | $V_{CM} = +1.2V$ | | | +100 | mV | |
| V_{TL} | Differential Input Low Threshold | | -100 | | | mV | |
| I_{IN} | Input Current | $V_{IN} = +2.4V, V_{CC} = 3.6V$ | | | ± 10 | μA | |
| | | $V_{IN} = 0V, V_{CC} = 3.6V$ | | | ± 10 | μA | |
| TRANSMITTER SUPPLY CURRENT | | | | | | | |
| ICCTW | Transmitter Supply Current, Worst Case | $R_L = 100\Omega, C_L = 5 \text{ pF}$, Worst Case Pattern (Figure 1 and Figure 3), DUAL=High (48-bit RGB), BAL=High (enabled) | $f = 32.5 \text{ MHz}$ | | 91.4 | 140 | mA |
| | | | $f = 65 \text{ MHz}$ | | 106 | 160 | mA |
| | | | $f = 85 \text{ MHz}$ | | 135 | 183 | mA |
| | | | $f = 112 \text{ MHz}$ | | 155 | 210 | mA |
| ICCTG | Transmitter Supply Current, 16 Grayscale | $R_L = 100\Omega, C_L = 5 \text{ pF}$, 16 Grayscale Pattern (Figure 2 and Figure 3), DUAL=High (48-bit RGB), BAL=High (enabled) | $f = 32.5 \text{ MHz}$ | | 62.6 | 120 | mA |
| | | | $f = 65 \text{ MHz}$ | | 84.4 | 130 | mA |
| | | | $f = 85 \text{ MHz}$ | | 89.0 | 145 | mA |
| | | | $f = 112 \text{ MHz}$ | | 94.5 | 155 | mA |
| ICCTZ | Transmitter Supply Current, Power Down | $\overline{PD} = \text{Low}$ Driver Outputs in TRI-STATE under Powerdown Mode | | 4.8 | 50 | μA | |

Electrical Characteristics⁽¹⁾ (continued)

Over recommended operating supply and temperature ranges unless otherwise specified.

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit | |
|--------------------------------|--|---|-------------|-----|-----|---------|----|
| RECEIVER SUPPLY CURRENT | | | | | | | |
| ICCRW | Receiver Supply Current, Worst Case | $C_L = 8$ pF, Worst Case Pattern (Figure 1 and Figure 4), DUAL (48-bit RGB), BAL=High (enabled) | f = 40MHz | | 125 | 160 | mA |
| | | | f = 65 MHz | | 200 | 250 | mA |
| | | | f = 85 MHz | | 240 | 275 | mA |
| | | | f = 112 MHz | | 250 | 300 | mA |
| ICCRG | Receiver Support Current, 16 Grayscale | $C_L = 8$ pF, 16 Grayscale Pattern (Figure 2 and Figure 4), DUAL (48-bit RGB), BAL=High (enabled) | f = 40MHz | | 60 | 95 | mA |
| | | | f = 65 MHz | | 95 | 125 | mA |
| | | | f = 85 MHz | | 115 | 150 | mA |
| | | | f = 112 MHz | | 150 | 270 | mA |
| ICCRZ | Receiver Supply Current, Power Down | \overline{PD} = Low Receiver Outputs stay low during Powerdown mode | | 255 | 300 | μ A | |

Recommended Transmitter Input Characteristics

Over recommended operating supply and temperature ranges unless otherwise specified.

| Symbol | Parameter | Min | Typ | Max | Unit | |
|--------|-------------------------------------|-----------------|-------|-------|-------|----|
| TCIT | TxCLK IN Transition Time (Figure 5) | DUAL=Gnd or Vcc | 1.0 | 2.0 | 3.0 | ns |
| | | DUAL=1/2Vcc | 1.0 | 1.5 | 1.7 | ns |
| TCIP | TxCLK IN Period (Figure 6) | DUAL=Gnd or Vcc | 8.928 | T | 30.77 | ns |
| | | DUAL=1/2Vcc | 5.88 | | 15.38 | ns |
| TCIH | TxCLK in High Time (Figure 6) | 0.35T | 0.5T | 0.65T | ns | |
| TCIL | TxCLK in Low Time (Figure 6) | 0.35T | 0.5T | 0.65T | ns | |
| TXIT | TxIN Transition Time | 1.5 | | 6.0 | ns | |

Transmitter Switching Characteristics

Over recommended operating supply and temperature ranges unless otherwise specified.

| Symbol | Parameter | Min | Typ | Max | Unit | |
|--------|--|-------------------|------|----------|------|----|
| LLHT | LVDS Low-to-High Transition Time (Figure 3), PRE = 0.75V (disabled) | | 0.14 | 0.7 | ns | |
| | | | 0.11 | 0.6 | ns | |
| LHLT | LVDS High-to-Low Transition Time (Figure 3), PRE = 0.75V (disabled) | | 0.16 | 0.8 | ns | |
| | | | 0.11 | 0.7 | ns | |
| TBIT | Transmitter Output Bit Width | DUAL=Gnd or Vcc | | 1/7 TCIP | ns | |
| | | DUAL=1/2Vcc | | 2/7 TCIP | ns | |
| TPPOS | Transmitter Pulse Positions - Normalized | f = 33 to 70 MHz | -250 | 0 | +250 | ps |
| | | f = 70 to 112 MHz | -200 | 0 | +200 | ps |
| TCCS | TxOUT Channel to Channel Skew | | 100 | | ps | |
| TSTC | TxIN Setup to TxCLK IN (Figure 6) | 2.7 | | | ns | |
| THTC | TxIN Hold to TxCLK IN (Figure 6) | 0 | | | ns | |
| TJCC | Transmitter Jitter Cycle-to-cycle (Figure 14 and Figure 15), DUAL=Vcc ⁽¹⁾ | f = 112 MHz | | 85 | 100 | ps |
| | | f = 85 MHz | | 60 | 75 | ps |
| | | f = 65 MHz | | 70 | 80 | ps |
| | | f = 56 MHz | | 100 | 120 | ps |
| | | f = 32.5 MHz | | 75 | 110 | ps |
| TPLLS | Transmitter Phase Lock Loop Set (Figure 8) | | | 10 | ms | |

(1) The limits are based on bench characterization of the device's jitter response over the power supply voltage range. Output clock jitter is measured with a cycle-to-cycle jitter of ± 3 ns applied to the input clock signal while data inputs are switching (see Figure 14 and Figure 15). A jitter event of 3ns, represents worst case jump in the clock edge from most graphics VGA chips currently available. This parameter is used when calculating system margin as described in AN-1059 (SNLA050).

Transmitter Switching Characteristics (continued)

Over recommended operating supply and temperature ranges unless otherwise specified.

| Symbol | Parameter | Min | Typ | Max | Unit |
|--------|---|-----|-----|-----|------|
| TPDD | Transmitter Powerdown Delay (Figure 10) | | | 100 | ns |

Receiver Switching Characteristics

Over recommended operating supply and temperature ranges unless otherwise specified.

| Symbol | Parameter | Min | Typ | Max | Unit |
|--------|---|-------------|------|-----|------|
| CLHT | CMOS/TTL Low-to-High Transition Time (Figure 4), Rx data out | | 1.52 | 2.0 | ns |
| | CMOS/TTL Low-to-High Transition Time (Figure 4), Rx clock out | | 0.5 | 1.0 | ns |
| CHLT | CMOS/TTL High-to-Low Transition Time (Figure 4), Rx data out | | 1.7 | 2.0 | ns |
| | CMOS/TTL High-to-Low Transition Time (Figure 4), Rx clock out | | 0.5 | 1.0 | ns |
| RCOP | RxCLK OUT Period (Figure 7) | 8.928 | T | 25 | ns |
| RCOH | RxCLK OUT High Time (Figure 7) ⁽¹⁾ | f = 112 MHz | 3.5 | | ns |
| | | f = 85 MHz | 4.5 | | ns |
| RCOL | RxCLK OUT Low Time (Figure 7) ⁽¹⁾ | f = 112 MHz | 3.5 | | ns |
| | | f = 85 MHz | 4.5 | | ns |
| RSRC | RxOUT Setup to RxCLK OUT (Figure 7) ⁽¹⁾ | f = 112 MHz | 2.4 | | ns |
| | | f = 85 MHz | 3.0 | | ns |
| RHRC | RxOUT Hold to RxCLK OUT (Figure 7) ⁽¹⁾ | f = 112 MHz | 3.4 | | ns |
| | | f = 85 MHz | 4.75 | | ns |
| RPLLS | Receiver Phase Lock Loop Set (Figure 9) | | | 10 | ms |
| RPDD | Receiver Powerdown Delay (Figure 11) | | | 1 | µs |

- (1) The Minimum and Maximum Limits are based on statistical analysis of the device performance over voltage and temperature ranges. This parameter is functionally tested on Automatic Test Equipment (ATE). ATE is limited to 85MHz. A sample of characterization parts have been bench tested to verify functional performance.

Chipset RSKM Characteristics

Over recommended operating supply and temperature ranges unless otherwise specified.^{(1) (2)}. See [Applications Information](#) for more details on this parameter and how to apply it.

| Symbol | Parameter | Min | Typ | Max | Unit |
|--------|---|-------------|-----|-----|------|
| RSKM | Receiver Skew Margin without Deskew in non-DC Balance Mode, (Figure 12), ⁽³⁾ | f = 112 MHz | 170 | | ps |
| | | f = 100 MHz | 170 | 240 | ps |
| | | f = 85MHz | 300 | 350 | ps |
| | | f = 66MHz | 300 | 350 | ps |
| RSKM | Receiver Skew Margin without Deskew in DC Balance Mode, (Figure 12) ⁽³⁾ | f = 112 MHz | 170 | | ps |
| | | f = 100 MHz | 170 | 200 | ps |
| | | f = 85 MHz | 250 | 300 | ps |
| | | f = 66 MHz | 250 | 300 | ps |
| | | f = 50MHz | 100 | 350 | ps |
| | f = 40MHz | 94 | 530 | ps | |

- (1) The Minimum and Maximum Limits are based on statistical analysis of the device performance over voltage and temperature ranges. This parameter is functionally tested on Automatic Test Equipment (ATE). ATE is limited to 85MHz. A sample of characterization parts have been bench tested to verify functional performance.
- (2) Typical values for RSKM and RSKMD are applicable for fixed V_{CC} and T_A for the Transmitter and Receiver (both are assumed to be at the same V_{CC} and T_A points).
- (3) Receiver Skew Margin (RSKM) is defined as the valid data sampling region at the receiver inputs. This margin takes into account transmitter output pulse positions (min and max) and the receiver input setup and hold time (internal data sampling window - RSPOS). This margin allows for LVDS interconnect skew, inter-symbol interference (both dependent on type/length of cable) and clock jitter. $RSKM \geq \text{cable skew (type, length)} + \text{source clock jitter (cycle to cycle, TJCC)} + \text{ISI (if any)}$. See [Applications Information](#) for more details.

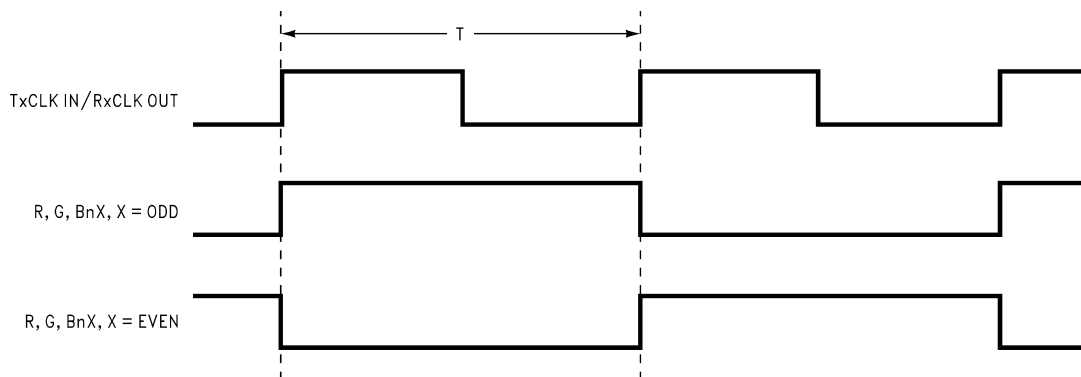
Chipset RSKM Characteristics (continued)

Over recommended operating supply and temperature ranges unless otherwise specified.^{(1) (2)} See [Applications Information](#) for more details on this parameter and how to apply it.

| Symbol | Parameter | | Min | Typ | Max | Unit |
|--------|--|------------------|----------|----------|-----|------|
| RSKMD | Receiver Skew Margin with Deskew in DC Balance, (Figure 13) ⁽⁴⁾ | f = 40 to 80 MHz | 0.25TBIT | | | ps |
| RDR | Receiver Deskew Range | f = 80 MHz | ± 1 | | | TBIT |
| RDSS | Receiver Deskew Step Size | f = 80 MHz | | 0.3 TBIT | | ns |

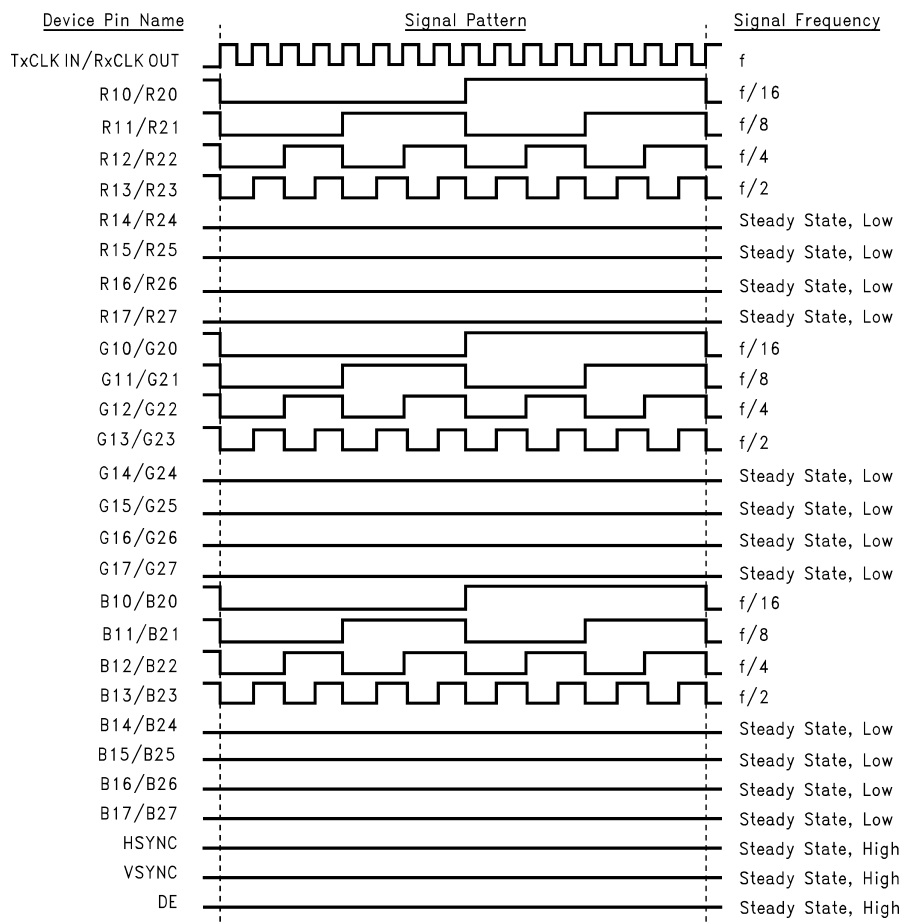
- (4) Receiver Skew Margin with Deskew (RSKMD) is defined as the valid data sampling region at the receiver inputs. The DESKEW function will constrain the receiver's sampling strobes to the middle half of the LVDS bit and removes (adjusts for) fixed interconnect skew. This margin (RSKMD) allows for inter-symbol interference (dependent on type/length of cable), Transmitter Pulse Position (TPPOS) variance, and LVDS clock jitter (TJCC). $RSKMD \geq ISI + TPPOS(\text{variance}) + \text{source clock jitter (cycle to cycle)}$. See [Applications Information](#) for more details.

AC Timing Diagrams



- A. The worst case test pattern produces a maximum toggling of digital circuits, LVDS I/O and CMOS/TTL I/O.
 B. [Figure 1](#) and [Figure 2](#) show a falling edge data strobe (TxCLK IN/RxCLK OUT).

Figure 1. "Worst Case" Test Pattern



- A. The 16 grayscale test pattern tests device power consumption for a “typical” LCD display pattern. The test pattern approximates signal switching needed to produce groups of 16 vertical stripes across the display.
- B. [Figure 1](#) and [Figure 2](#) show a falling edge data strobe (TxCLK IN/RxCLK OUT).

Figure 2. “16 Grayscale” Test Pattern

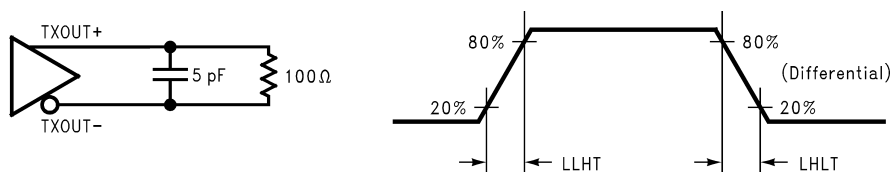


Figure 3. DS90C387 (Transmitter) LVDS Output Load and Transition Times



Figure 4. DS90CF388 (Receiver) CMOS/TTL Output Load and Transition Times

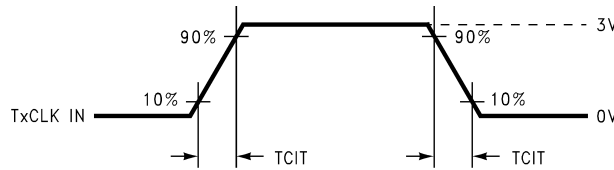


Figure 5. DS90C387 (Transmitter) Input Clock Transition Time

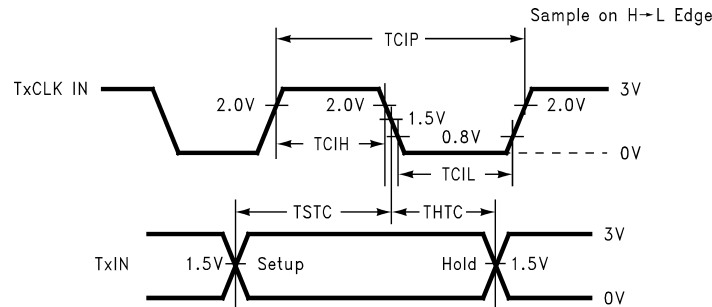


Figure 6. DS90C387 (Transmitter) Setup/Hold and High/Low Times (Falling Edge Strobe)

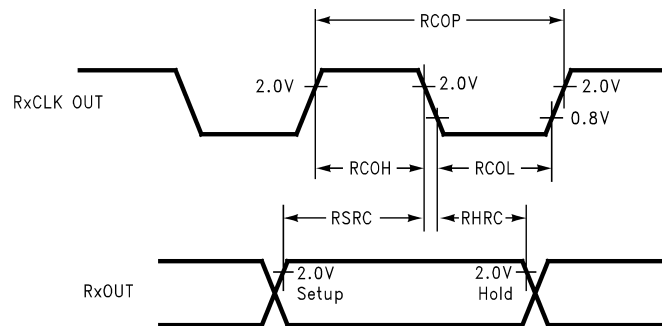


Figure 7. DS90CF388 (Receiver) Setup/Hold and High/Low Times

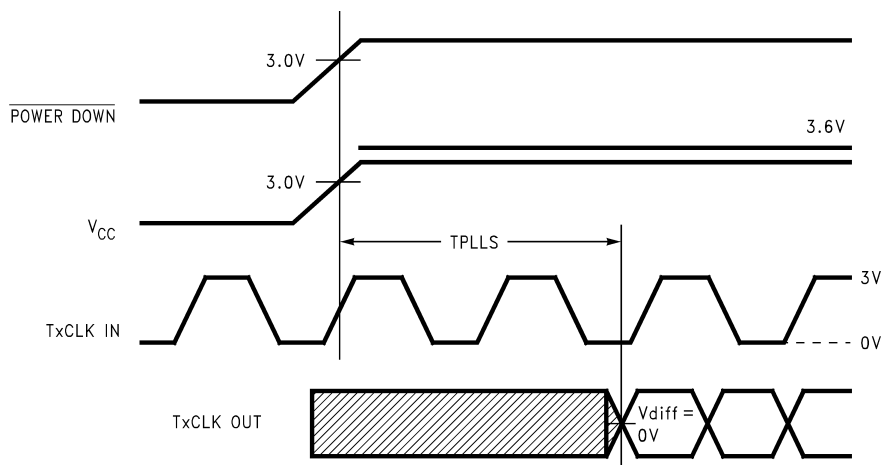


Figure 8. DS90C387 (Transmitter) Phase Lock Loop Set Time

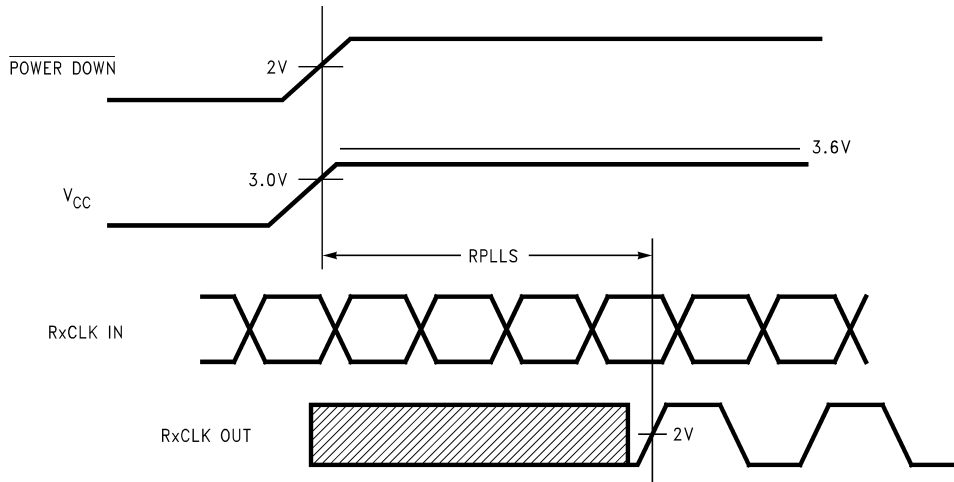


Figure 9. DS90CF388 (Receiver) Phase Lock Loop Set Time

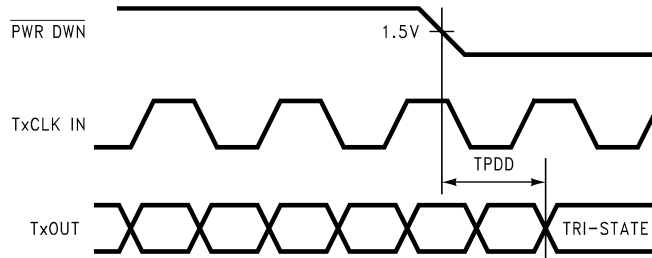


Figure 10. Transmitter Power Down Delay

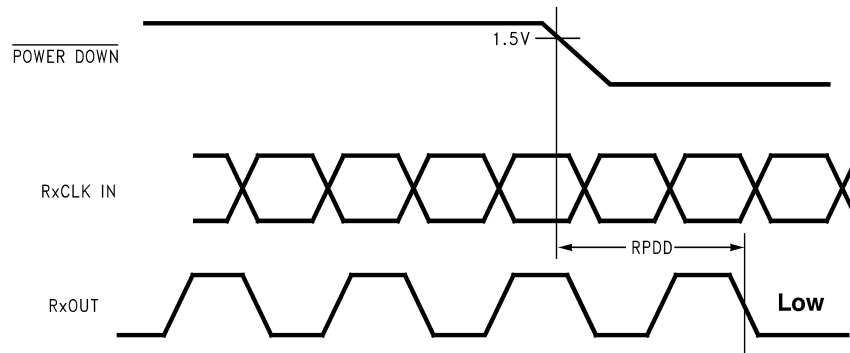
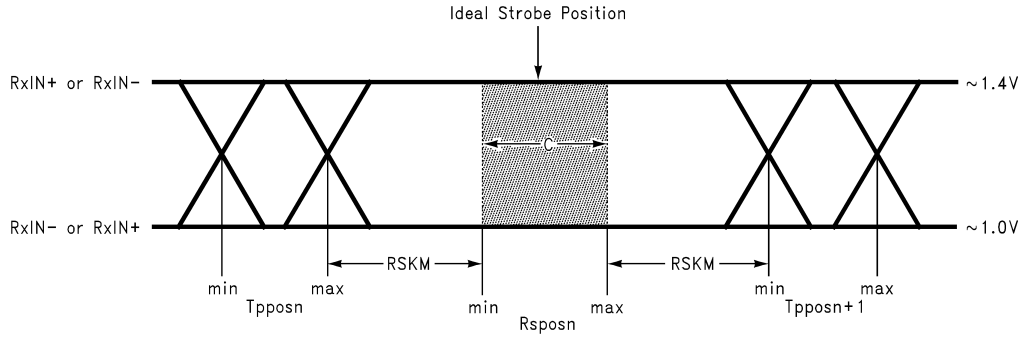
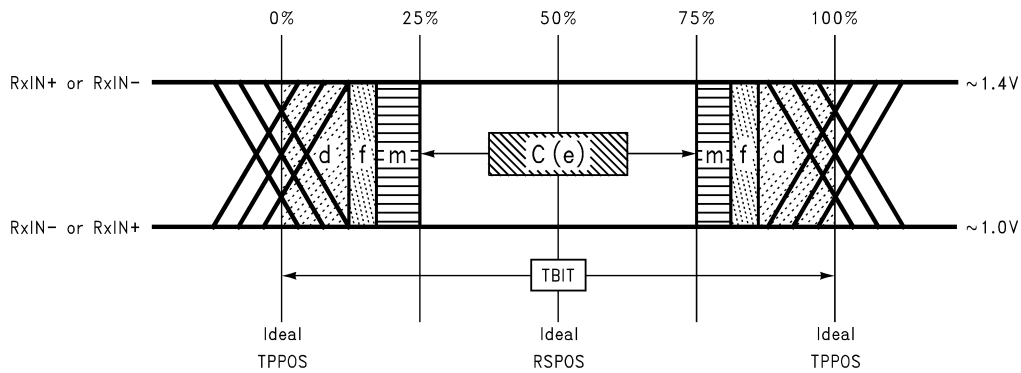


Figure 11. Receiver Power Down Delay



C — Setup and Hold Time (Internal data sampling window) defined by RSPOS (receiver input strobe position) min and max
 TPPOS — Transmitter output pulse position (min and max)
 $RSKM \geq \text{Cable Skew (type, length) + LVDS Source Clock Jitter (cycle to cycle) + ISI (Inter-symbol interference)}$
 ■ Cable Skew—typically 10 ps to 40 ps per foot, media dependent
 ■ TJCC — Cycle-to-cycle LVDS Output jitter (TJCC) is less than 100 ps (worse case estimate).
 ■ ISI is dependent on interconnect length; may be zero
 See [Applications Information](#) for more details.

Figure 12. Receiver Skew Margin



C — Setup and Hold Time (Internal data sampling window) defined by Rspes (receiver input strobe position) min and max
 $RSKMD \geq TPPOS\text{variance (d) + TJCC (output jitter)(f) + ISI (m)}$
 ■ d = TPPOS — Transmitter output pulse position (min and max)
 ■ f = TJCC — Cycle-to-cycle LVDS Output jitter (TJCC) is less than 100 ps (worse case estimate).
 ■ m = extra margin - assigned to ISI in long cable applications
 See [Applications Information](#) for more details.

Figure 13. Receiver Skew Margin (RSKMD) with DESKEW

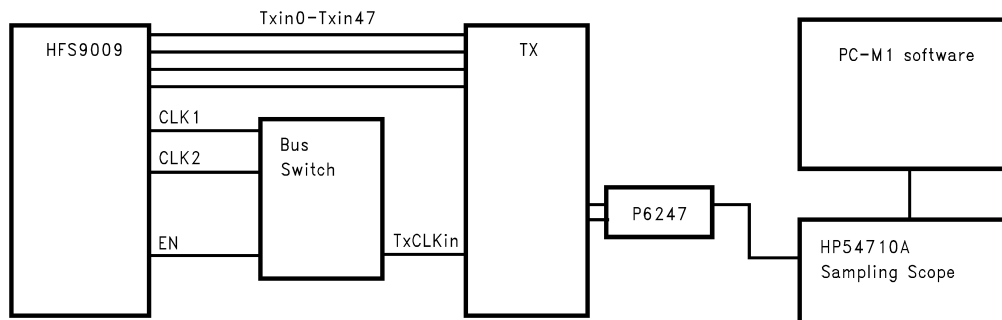


Figure 14. TJCC Test Setup - DS90C387

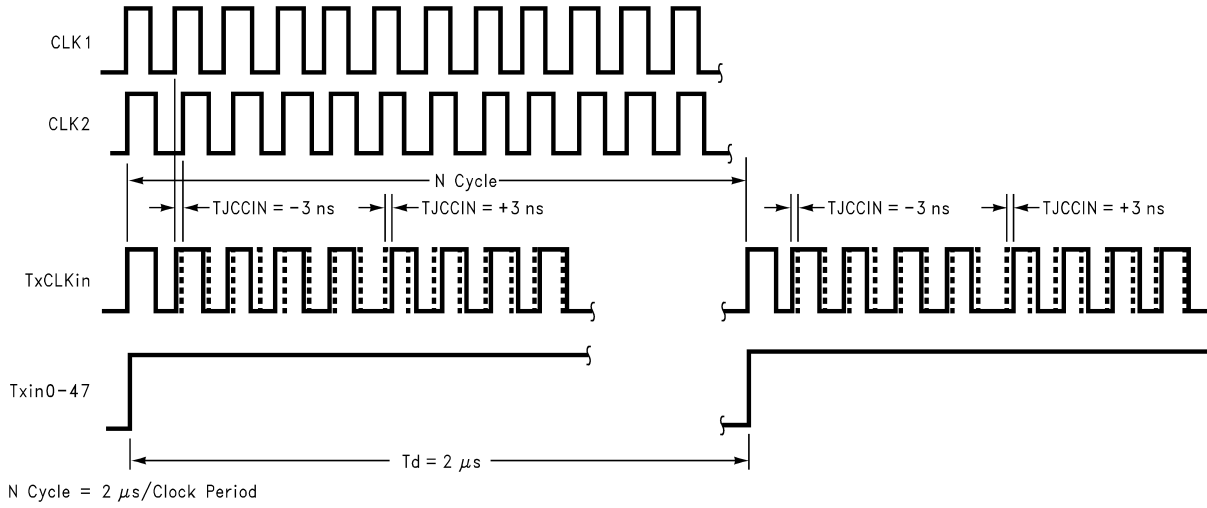


Figure 15. Timing Diagram of the Input Cycle-to-Cycle Clock Jitter

DS90C387 PIN DESCRIPTIONS — FPD LINK TRANSMITTER

| Pin Name | I/O | No. | Description |
|------------------------------|-----|-----|--|
| Rn, Gn, Bn, DE, HSYNC, VSYNC | I | 51 | TTL level input. This includes: 16 Red, 16 Green, 16 Blue, and 3 control lines HSYNC, VSYNC, DE (Data Enable). ⁽¹⁾ |
| AnP | O | 8 | Positive LVDS differential data output. |
| AnM | O | 8 | Negative LVDS differential data output. |
| CLKIN | I | 1 | TTL level clock input. |
| R_FB | I | 1 | Programmable data strobe select. Rising data strobe edge selected when input is high. ⁽¹⁾ |
| R_FDE | I | 1 | Programmable control (DE) strobe select. Tied high for data active when DE is high. ⁽¹⁾ |
| CLK1P | O | 1 | Positive LVDS differential clock output. |
| CLK1M | O | 1 | Negative LVDS differential clock output. |
| $\overline{\text{PD}}$ | I | 1 | TTL level input. Assertion (low input) tri-states the outputs, ensuring low current at power down. ⁽¹⁾ |
| PLLSEL | I | 1 | PLL range select. This pin must be tied to V_{CC} for auto-range. NC or tied to Ground is reserved for future use. Typical shift point is between 55 and 68 MHz. ^{(1) (2)} |
| BAL | I | 1 | Mode select for DC Balanced (new) or non-DC Balanced (backward compatible) interface. DC Balance is active when input is high. NC or tied to Ground, the DC Balance function is disabled. ^{(1) (3) (4)} |
| PRE | I | 1 | Pre-emphasis level select. Pre-emphasis is active when input is tied to V_{CC} through external pull-up resistor. Resistor value determines pre-emphasis level (see Pre-Emphasis). For normal LVDS drive level (No pre-emphasis) leave this pin open (do not tie to ground). ⁽¹⁾ |
| DUAL | I | 1 | Three-mode select for dual pixel, single pixel, or single pixel input to dual pixel output operation. Single pixel mode when input is low (only LVDS channels A0 thru A3 and CLK1 are active) for power savings. Dual mode is active when input is high. Single in - dual out when input is at 1/2 V_{CC} . ⁽¹⁾ Figure 16 |
| V_{CC} | I | 4 | Power supply pins for TTL inputs and digital circuitry. |
| GND | I | 5 | Ground pins for TTL inputs and digital circuitry. |
| PLL V_{CC} | I | 2 | Power supply pin for PLL circuitry. |
| PLLGND | I | 3 | Ground pins for PLL circuitry. |
| LVDS V_{CC} | I | 3 | Power supply pin for LVDS outputs. |
| LVDSGND | I | 4 | Ground pins for LVDS outputs. |
| CLK2P/NC | O | 1 | Additional positive LVDS differential clock output. Identical to CLK1P. No connect if not used. |
| CLK2M/NC | O | 1 | Additional negative LVDS differential clock output. Identical to CLK1M. No connect if not used. |

- (1) Inputs default to "low" when left open due to internal pull-down resistor.
- (2) The PLL range shift point is in the 55 - 68 MHz range, typically the shift will occur during the lock time.
- (3) DC Balancing is functionally tested on Automatic Test Equipment (ATE) at 85 MHz only. A sample of characterization units have been bench tested at 112 MHz to verify full speed performance.
- (4) The DS90CF388 is designed to automatically detect the DC Balance or non-DC Balance transmitted data from the DS90C387 and deserialize the LVDS data according to the defined bit mapping.

DS90CF388 PIN DESCRIPTIONS — FPD LINK RECEIVER

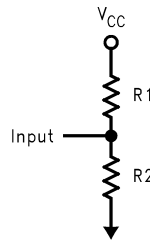
| Pin Name | I/O | No. | Description |
|------------------------------|-----|-----|---|
| AnP | I | 8 | Positive LVDS differential data inputs. |
| AnM | I | 8 | Negative LVDS differential data inputs. |
| Rn, Gn, Bn, DE, HSYNC, VSYNC | O | 51 | TTL level data outputs. This includes: 16 Red, 16 Green, 16 Blue, and 3 control lines— HSYNC (LP), VSYNC (FLM), DE (Data Enable). |
| RxCLK INP | I | 1 | Positive LVDS differential clock input. |
| RxCLK INM | I | 1 | Negative LVDS differential clock input. |
| RxCLK OUT | O | 1 | TTL level clock output. The falling edge acts as data strobe. |
| R_FDE | I | 1 | Programmable control (DE) strobe select. Tied high for data active when DE is high. ⁽¹⁾ |
| PLLSEL | I | 1 | PLL range select. This pin must be tied to V_{CC} for auto-range. NC or tied to Ground is reserved for future use. Typical shift point is between 55 and 68 MHz. ^{(2) (3)} |

- (1) Inputs default to "low" when left open due to internal pull-down resistor.
- (2) DC Balancing is functionally tested on Automatic Test Equipment (ATE) at 85 MHz only. A sample of characterization units have been bench tested at 112 MHz to verify full speed performance.
- (3) The PLL range shift point is in the 55 - 68 MHz range, typically the shift will occur during the lock time.

DS90CF388 PIN DESCRIPTIONS — FPD LINK RECEIVER (continued)

| Pin Name | I/O | No. | Description |
|--------------------------------|-----|-----|---|
| BAL | I | 1 | Mode select for DC Balanced (new) or non-DC Balanced (backward compatible) interface. BAL = LOW for non-DC Balanced mode. BAL = HIGH for DC Balanced Mode (Auto-detect mode), with this pin HIGH the received LVDS clock signal is used to determine if the interface is in new or backward compatible mode. ^{(1) (2) (4)} |
| DESKEW | I | 1 | Deskew and oversampling “on/off” select. Deskew is active when input is high. Only supported in DC Balance mode (BAL=High). To complete the deskew operation, a minimum of four clock cycles is required during blanking time. ⁽¹⁾ |
| $\overline{\text{PD}}$ | I | 1 | TTL level input. When asserted (low input) the receiver data outputs are low and clock output is high. ⁽¹⁾ |
| STOPCLK | O | 1 | Indicates receiver clock input signal is not present with a logic high. With a clock input present, a low logic is indicated. |
| V _{CC} | I | 6 | Power supply pins for TTL outputs and digital circuitry. |
| GND | I | 8 | Ground pins for TTL outputs and digital circuitry |
| PLL _{V_{CC}} | I | 1 | Power supply for PLL circuitry. |
| PLL _{GND} | I | 2 | Ground pin for PLL circuitry. |
| LVDS _{V_{CC}} | I | 2 | Power supply pin for LVDS inputs. |
| LVDS _{GND} | I | 3 | Ground pins for LVDS inputs. |
| CNTLE, CNTLF | O | 2 | TTL level data outputs. User-defined control signals - no connect when not used. |

(4) The DS90CF388 is designed to automatically detect the DC Balance or non-DC Balance transmitted data from the DS90C387 and deserialize the LVDS data according to the defined bit mapping.



Recommend using R1=R2=10kΩ for single to dual mode

Figure 16. Resistor Network for “DUAL” pin input

LVDS Interface

Table 1. LVDS DATA BIT NAMING CONVENTION

| X | Y | Z | Description |
|-----|-----|-------|---|
| X=R | | | Red |
| X=G | | | Green |
| X=B | | | Blue |
| | Y=1 | | Odd (First) Pixel |
| | Y=2 | | Even (Second) Pixel |
| | | Z=0-7 | LVDS bit number (not VGA controller LSB to MSB) |

Table 2. SINGLE PIXEL PER CLOCK INPUT APPLICATION DATA MAPPING (DUAL=GND)

| VGA - TFT Data Signals Color Bits | | | Transmitter input pin names | Receiver output pin names | TFT Panel Data Signals | |
|-----------------------------------|--------|--------|-----------------------------|---------------------------|------------------------|--------|
| | 24-bit | 18-bit | DS90C387 | DS90CF388 | 18-bit | 24-bit |
| LSB | R0 | | R16 | R16 | | R0 |
| | R1 | | R17 | R17 | | R1 |
| | R2 | R0 | R10 | R10 | R0 | R2 |

Table 2. SINGLE PIXEL PER CLOCK INPUT APPLICATION DATA MAPPING (DUAL=GND) (continued)

| VGA - TFT Data Signals Color Bits | | | Transmitter input pin names | Receiver output pin names | TFT Panel Data Signals | |
|-----------------------------------|----|----|-----------------------------|---------------------------|------------------------|----|
| | R3 | R1 | R11 | R11 | R1 | R3 |
| | R4 | R2 | R12 | R12 | R2 | R4 |
| | R5 | R3 | R13 | R13 | R3 | R5 |
| | R6 | R4 | R14 | R14 | R4 | R6 |
| MSB | R7 | R5 | R15 | R15 | R5 | R7 |
| LSB | G0 | | G16 | G16 | | G0 |
| | G1 | | G17 | G17 | | G1 |
| | G2 | G0 | G10 | G10 | G0 | G2 |
| | G3 | G1 | G11 | G11 | G1 | G3 |
| | G4 | G2 | G12 | G12 | G2 | G4 |
| | G5 | G3 | G13 | G13 | G3 | G5 |
| | G6 | G4 | G14 | G14 | G4 | G6 |
| MSB | G7 | G5 | G15 | G15 | G5 | G7 |
| LSB | B0 | | B16 | B16 | | B0 |
| | B1 | | B17 | B17 | | B1 |
| | B2 | B0 | B10 | B10 | B0 | B2 |
| | B3 | B1 | B11 | B11 | B1 | B3 |
| | B4 | B2 | B12 | B12 | B2 | B4 |
| | B5 | B3 | B13 | B13 | B3 | B5 |
| | B6 | B4 | B14 | B14 | B4 | B6 |
| MSB | B7 | B5 | B15 | B15 | B5 | B7 |

Table 3. DUAL PIXEL PER CLOCK INPUT APPLICATION DATA MAPPING (DUAL=VCC)

| VGA - TFT Data Signals Color Bits | | | Transmitter input pin names | Receiver output pin names | TFT Panel Data Signals | |
|-----------------------------------|--------|--------|-----------------------------|---------------------------|------------------------|--------|
| | 48-bit | 36-bit | DS90C387 | DS90CF388 | 36-bit | 48-bit |
| LSB | RO0 | | R16 | R16 | | RO0 |
| | RO1 | | R17 | R17 | | RO1 |
| | RO2 | RO0 | R10 | R10 | RO0 | RO2 |
| | RO3 | RO1 | R11 | R11 | RO1 | RO3 |
| | RO4 | RO2 | R12 | R12 | RO2 | RO4 |
| | RO5 | RO3 | R13 | R13 | RO3 | RO5 |
| | RO6 | RO4 | R14 | R14 | RO4 | RO6 |
| MSB | RO7 | RO5 | R15 | R15 | RO5 | RO7 |
| LSB | GO0 | | G16 | G16 | | GO0 |
| | GO1 | | G17 | G17 | | GO1 |
| | GO2 | GO0 | G10 | G10 | GO0 | GO2 |
| | GO3 | GO1 | G11 | G11 | GO1 | GO3 |
| | GO4 | GO2 | G12 | G12 | GO2 | GO4 |
| | GO5 | GO3 | G13 | G13 | GO3 | GO5 |
| | GO6 | GO4 | G14 | G14 | GO4 | GO6 |
| MSB | GO7 | GO5 | G15 | G15 | GO5 | GO7 |
| LSB | BO0 | | B16 | B16 | | BO0 |
| | BO1 | | B17 | B17 | | BO1 |
| | BO2 | BO0 | B10 | B10 | BO0 | BO2 |
| | BO3 | BO1 | B11 | B11 | BO1 | BO3 |
| | BO4 | BO2 | B12 | B12 | BO2 | BO4 |

Table 3. DUAL PIXEL PER CLOCK INPUT APPLICATION DATA MAPPING (DUAL=VCC) (continued)

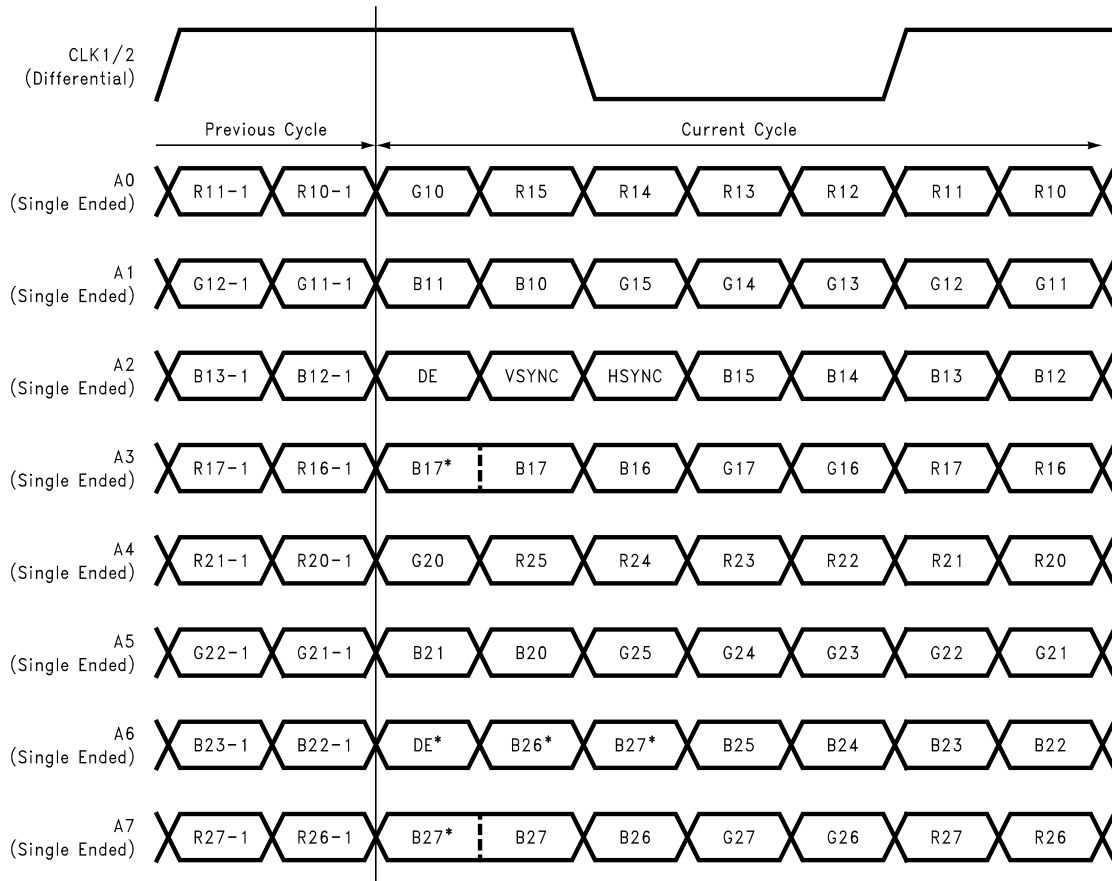
| VGA - TFT Data Signals Color Bits | | | Transmitter input pin names | Receiver output pin names | TFT Panel Data Signals | |
|-----------------------------------|-----|-----|-----------------------------|---------------------------|------------------------|-----|
| | BO5 | BO3 | B13 | B13 | BO3 | BO5 |
| | BO6 | BO4 | B14 | B14 | BO4 | BO6 |
| MSB | BO7 | BO5 | B15 | B15 | BO5 | BO7 |
| LSB | RE0 | | R26 | R26 | | RE0 |
| | RE1 | | R27 | R27 | | RE1 |
| | RE2 | RE0 | R20 | R20 | RE0 | RE2 |
| | RE3 | RE1 | R21 | R21 | RE1 | RE3 |
| | RE4 | RE2 | R22 | R22 | RE2 | RE4 |
| | RE5 | RE3 | R23 | R23 | RE3 | RE5 |
| | RE6 | RE4 | R24 | R24 | RE4 | RE6 |
| MSB | RE7 | RE5 | R25 | R25 | RE5 | RE7 |
| LSB | GE0 | | G26 | G26 | | GE0 |
| | GE1 | | G27 | G27 | | GE1 |
| | GE2 | GE0 | G20 | G20 | GE0 | GE2 |
| | GE3 | GE1 | G21 | G21 | GE1 | GE3 |
| | GE4 | GE2 | G22 | G22 | GE2 | GE4 |
| | GE5 | GE3 | G23 | G23 | GE3 | GE5 |
| | GE6 | GE4 | G24 | G24 | GE4 | GE6 |
| MSB | GE7 | GE5 | G25 | G25 | GE5 | GE7 |
| LSB | BE0 | | B26 | B26 | | BE0 |
| | BE1 | | B27 | B27 | | BE1 |
| | BE2 | BE0 | B20 | B20 | BE0 | BE2 |
| | BE3 | BE1 | B21 | B21 | BE1 | BE3 |
| | BE4 | BE2 | B22 | B22 | BE2 | BE4 |
| | BE5 | BE3 | B23 | B23 | BE3 | BE5 |
| | BE6 | BE4 | B24 | B24 | BE4 | BE6 |
| MSB | BE7 | BE5 | B25 | B25 | BE5 | BE7 |

Table 4. SINGLE PIXEL PER CLOCK INPUT-TO-DUAL PIXEL PER CLOCK OUTPUT DATA MAPPING (DUAL=1/2VCC)

| VGA - TFT Data Signals Color Bits | | | Transmitter input pin names | Receiver output pin names | TFT Panel Data Signals | |
|-----------------------------------|--------|--------|-----------------------------|---------------------------|------------------------|--------|
| | 24-bit | 18-bit | DS90C387 | DS90CF388 | 36-bit | 48-bit |
| LSB | R0 | | R16 | R16 | | RO0 |
| | R1 | | R17 | R17 | | RO1 |
| | R2 | R0 | R10 | R10 | RO0 | RO2 |
| | R3 | R1 | R11 | R11 | RO1 | RO3 |
| | R4 | R2 | R12 | R12 | RO2 | RO4 |
| | R5 | R3 | R13 | R13 | RO3 | RO5 |
| | R6 | R4 | R14 | R14 | RO4 | RO6 |
| MSB | R7 | R5 | R15 | R15 | RO5 | RO7 |
| LSB | G0 | | G16 | G16 | | GO0 |
| | G1 | | G17 | G17 | | GO1 |
| | G2 | G0 | G10 | G10 | GO0 | GO2 |
| | G3 | G1 | G11 | G11 | GO1 | GO3 |
| | G4 | G2 | G12 | G12 | GO2 | GO4 |
| | G5 | G3 | G13 | G13 | GO3 | GO5 |

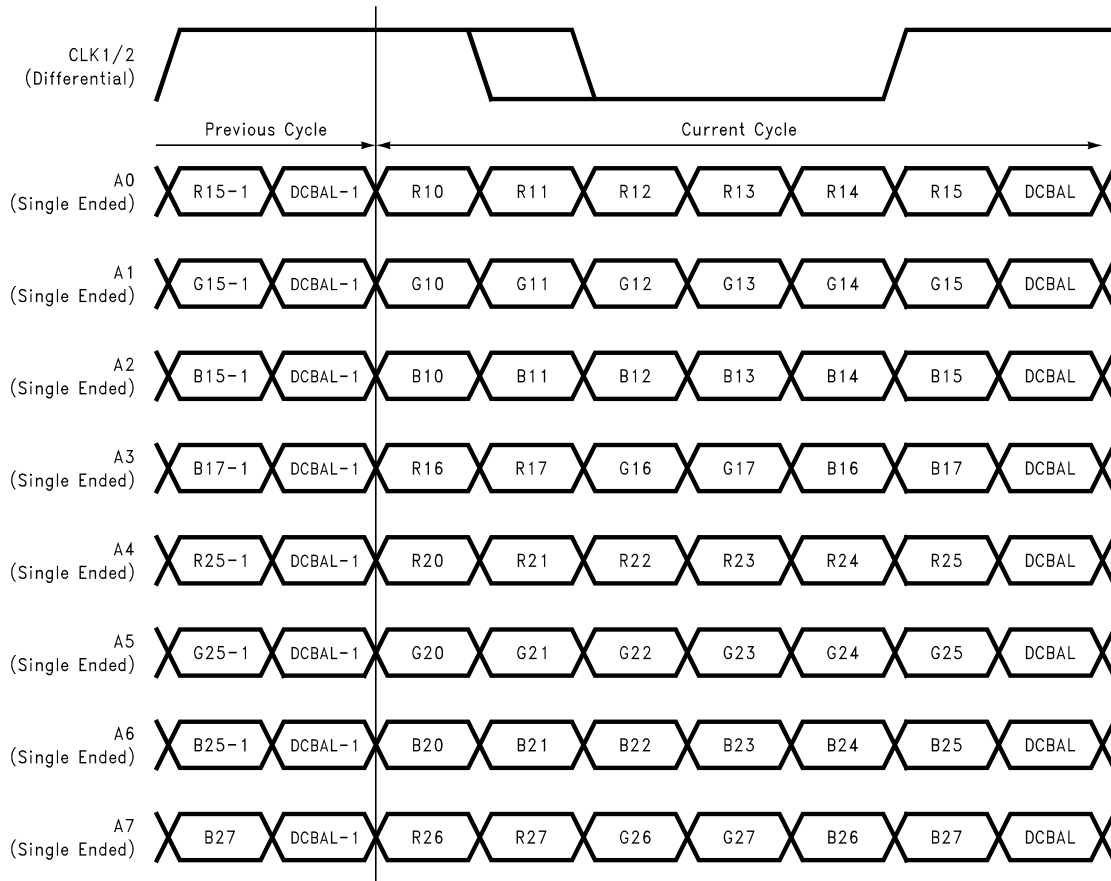
**Table 4. SINGLE PIXEL PER CLOCK INPUT-TO-DUAL PIXEL PER CLOCK OUTPUT DATA MAPPING
(DUAL=1/2VCC) (continued)**

| VGA - TFT Data Signals Color Bits | | | Transmitter input pin names | Receiver output pin names | TFT Panel Data Signals | |
|-----------------------------------|----|----|-----------------------------|---------------------------|------------------------|-----|
| | G6 | G4 | G14 | G14 | GO4 | GO6 |
| MSB | G7 | G5 | G15 | G15 | GO5 | GO7 |
| LSB | B0 | | B16 | B16 | | BO0 |
| | B1 | | B17 | B17 | | BO1 |
| | B2 | B0 | B10 | B10 | BO0 | BO2 |
| | B3 | B1 | B11 | B11 | BO1 | BO3 |
| | B4 | B2 | B12 | B12 | BO2 | BO4 |
| | B5 | B3 | B13 | B13 | BO3 | BO5 |
| | B6 | B4 | B14 | B14 | BO4 | BO6 |
| MSB | B7 | B5 | B15 | B15 | BO5 | BO7 |
| | | | R16 | R26 | | RE0 |
| | | | R17 | R27 | | RE1 |
| | | | R10 | R20 | RE0 | EO2 |
| | | | R11 | R21 | RE1 | RE3 |
| | | | R12 | R22 | RE2 | RE4 |
| | | | R13 | R23 | RE3 | RE5 |
| | | | R14 | R24 | RE4 | RE6 |
| | | | R15 | R25 | RE5 | RE7 |
| | | | G16 | G26 | | GE0 |
| | | | G17 | G27 | | GE1 |
| | | | G10 | G20 | GE0 | GE2 |
| | | | G11 | G21 | GE1 | GE3 |
| | | | G12 | G22 | GE2 | GE4 |
| | | | G13 | G23 | GE3 | GE5 |
| | | | G14 | G24 | GE4 | GE6 |
| | | | G15 | G25 | GE5 | GE7 |
| | | | B16 | B26 | | BE0 |
| | | | B17 | B27 | | BE1 |
| | | | B10 | B20 | BE0 | BE2 |
| | | | B11 | B21 | BE1 | BE3 |
| | | | B12 | B22 | BE2 | BE4 |
| | | | B13 | B23 | BE3 | BE5 |
| | | | B14 | B24 | BE4 | BE6 |
| | | | B15 | B25 | BE5 | BE7 |



NOTE: Redundant copies of certain signals are also sent. These signals are denoted with an * symbol. The DS90CF388 does not sample the bits show with an * symbol. Optional feature supported: Pre-emphasis. See [Applications Information](#) for additional details.

**Figure 17. TTL Data Inputs Mapped to LVDS Outputs
Non-DC Balanced Mode (Backward Compatible, BAL=Low)**



NOTE: The LVDS Clock signal is also DC Balanced in this mode. The rising edge location is fixed, but the location of the falling edge will be in one of two locations as shown above. Optional features supported: Pre-emphasis, and Deskew.

Figure 18. 48 Parallel TTL Data Inputs Mapped to LVDS Outputs DC Balanced Mode - Data Enabled, BAL=High

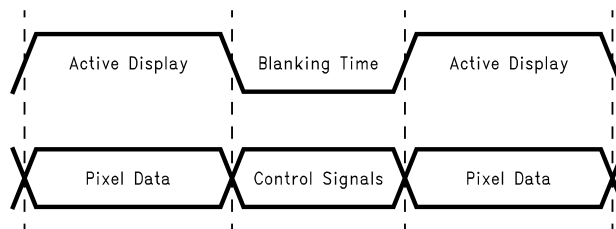


Figure 19. Control Signals Transmitted During Blanking

| Control Signal | Signal Level | Channel | Pattern |
|----------------|--------------|----------|--------------------------|
| DE | HIGH | TxCLKOUT | 1111000 or 1110000 |
| | LOW | | 1111100 or 1100000 |
| HSYNC | HIGH | TXOUT0 | 1100000 or 1111100 |
| | LOW | | 1110000 or 1111000 |
| VSYNC | HIGH | TXOUT1 | 1100000 or 1111100 |
| | LOW | | 1110000 or 1111000 |
| CNTLF | HIGH | TXOUT4 | 1100000 or 1111100 |
| | LOW | | 1110000 or 1111000 |
| CNTLE | HIGH | TXOUT5 | 1100000 or 1111100 |
| | LOW | | 1110000 or 1111000 |

NOTE: The control signal during blanking shown above is for R_FDE=High, when R_FDE=Low all the low/high patterns are reversed.

Figure 20. Control Signals Transmitted During Blanking

APPLICATIONS INFORMATION

HOW TO CONFIGURE THE DS90C387 AND DS90CF388 FOR MOST COMMON APPLICATION

1. To configure for single input pixel-to-dual pixel output application, the DS90C387 "DUAL" pin must be set to $1/2 V_{cc}=1.65V$. This may be implemented using pull-up and pull-down resistors of $10k\Omega$ each as shown in [Figure 16](#). A capacitor between "DUAL" pin and ground will help to stabilize the DC voltage level in a noisy environment. In this configuration, the input signals (single pixel) are split into odd and even pixel (dual pixels) starting with the odd (first) pixel outputs A0-to-A3 the next even (second) pixel outputs to A4-to-A7. The splitting of the data signal also starts with DE (data enable) transitioning from logic low to high indicating active data. The "R_FDE" pin must be set high in this case. This is supported in DC Balanced and non-DC Balanced (BAL=low or high) data transmission. The number of clock cycles during blanking must be an EVEN number. This configuration will allow the user to interface to an LDI receiver (DS90CF388) or if in the non-DC Balanced mode (BAL=low) then two FPD-Link 'notebook' receivers (DS90CF384A). The DC Balance feature is recommended for monitor applications which require >2meters of cable length. Notebook applications should disable this feature to reduce the current consumption of the chipset. Note that only the DS90C387/DS90CF388 support the DC Balance data transmission feature.
2. To configure for single pixel or dual pixel application using the DS90C387/DS90CF388, the "DUAL" pin must be set to V_{cc} (dual) or Gnd (single). In dual mode, the transmitter-DS90C387 has two LVDS clock outputs enabling an interface to two FPD-Link 'notebook' receivers (DS90CF384A or DS90CF386). In single mode, outputs A4-to-A7 and CLK2 are disabled which reduces power dissipation. Both single and dual mode also support the DC Balance data transmission feature, which should only be used for monitor application.
3. The DS90CF388 is able to support single or dual pixel interface up to 112MHz operating frequency. This receiver may also be used to interface to a VGA controller with an integrated LVDS transmitter without DC Balance data transmission. In this case, the receivers "BAL" pin must be tied low (DC Balance disabled).

NEW FEATURES DESCRIPTION

Pre-Emphasis

Adds extra current during LVDS logic transition to reduce the cable loading effects. Pre-emphasis strength is set via a DC voltage level applied from min to max (0.75V to V_{cc}) at the "PRE" pin. A higher input voltage on the "PRE" pin increases the magnitude of dynamic current during data transition. The "PRE" pin requires one pull-up resistor (R_{pre}) to V_{cc} in order to set the DC level. There is an internal resistor network, which cause a voltage drop. See [Table 5](#) and [Table 6](#) to set the voltage level.

Table 5. PRE-EMPHASIS DC VOLTAGE LEVEL WITH (RPRE)⁽¹⁾

| Rpre | Resulting PRE Voltage | Effects |
|-----------|-----------------------|-------------------|
| 1MΩ or NC | 0.75V | Standard LVDS |
| 50kΩ | 1.0V | |
| 9kΩ | 1.5V | 50% pre-emphasis |
| 3kΩ | 2.0V | |
| 1kΩ | 2.6V | |
| 100Ω | V_{cc} | 100% pre-emphasis |

(1) This is based on testing with standard shield twisted pair cable. The amount of pre-emphasis will vary depending on the type of cable, length and operating frequency.

Table 6. PRE-EMPHASIS NEEDED PER CABLE LENGTH

| Frequency | PRE Voltage | Typical cable length |
|-----------|-------------|----------------------|
| 112MHz | 1.0V | 2 meters |
| 112MHz | 1.5V | 5 meters |
| 80MHz | 1.0V | 2 meters |
| 80MHz | 1.2V | 7 meters |

Table 6. PRE-EMPHASIS NEEDED PER CABLE LENGTH (continued)

| Frequency | PRE Voltage | Typical cable length |
|-----------|-------------|----------------------|
| 65MHz | 1.5V | 10 meters |
| 56MHz | 1.0V | 10 meters |

DC Balance

In the Balanced operating modes, in addition to pixel and control information an additional bit is transmitted on every LVDS data signal line during each cycle of active data as shown in [Figure 18](#). This bit is the DC Balance bit (DCBAL). The purpose of the DC Balance bit is to minimize the short- and long-term DC bias on the signal lines. This is achieved by selectively sending the pixel data either unmodified or inverted.

The value of the DC Balance bit is calculated from the running word disparity and the data disparity of the current word to be sent. The data disparity of the current word shall be calculated by subtracting the number of bits of value 0 from the number of bits value 1 in the current word. Initially, the running word disparity may be any value between +7 and –6. The running word disparity shall be calculated as a continuous sum of all the modified data disparity values, where the unmodified data disparity value is the calculated data disparity minus 1 if the data is sent unmodified and 1 plus the inverse of the calculated data disparity if the data is sent inverted. The value of the running word disparity shall saturate at +7 and –6.

The value of the DC Balance bit (DCBAL) shall be 0 when the data is sent unmodified and 1 when the data is sent inverted. To determine whether to send pixel data unmodified or inverted, the running word disparity and the current data disparity are used. If the running word disparity is positive and the current data disparity is positive, the pixel data shall be sent inverted. If the running word disparity is positive and the current data disparity is zero or negative, the pixel data shall be sent unmodified. If the running word disparity is negative and the current data disparity is positive, the pixel data shall be sent unmodified. If the running word disparity is negative and the current data disparity is zero or negative, the pixel data shall be sent inverted. If the running word disparity is zero, the pixel data shall be sent inverted.

Cable drive is enhanced with a user selectable pre-emphasis feature that provides additional output current during transitions to counteract cable loading effects. DC balancing on a cycle-to-cycle basis, is also provided to reduce ISI (Inter-Symbol Interference). With pre-emphasis and DC balancing, a low distortion eye-pattern is provided at the receiver end of the cable. These enhancements allow cables 5 to 10+ meters in length to be driven.

CONTROL SIGNAL SENT DURING BLANKING (DC BALANCE MODE)

The data enable control signal (DE) is used in the DC Balanced mode to distinguish between pixel data and control information being sent. It must be continuously available to the device in order to correctly separate pixel data from control information. For this reason, DE shall be sent on the clock signals, LVDS CLK1 and CLK2, when operating in the DC Balanced mode. If the value of the control to be sent is 1 (active display), the value of the control word sent on the clock signals shall be 1111000 or 1110000. If the value of the control to be sent is 0 (blanking time), the value of the control word sent on the clock signals shall be 1111100 or 1100000. This is true when R_FDE=High. See [Transmitter Pin Descriptions](#) and [Receiver Pin Descriptions](#).

The control information, such as HSYNC and VSYNC, is always sent unmodified. The value of the control word to send is determined by the running word disparity and the value of the control to be sent. If the running word disparity is positive and the value of the control to be sent is 0, the control word sent shall be 1110000. If the running word disparity is zero or negative and the control word to be sent is 0, the control word sent shall be 1111000. If the running word disparity is positive and the value of the control to be sent is 1, the control word sent shall be 1100000. If the running word disparity is zero or negative and the value of the control to be sent is 1, the control word sent shall be 1111100. The DC Balance bit shall be sent as 0 when sending control information during blanking time. See [Figure 19](#).

RGB outputs on the DS90CF388 are forced LOW during the blanking time.

Note that in the backward compatible mode (BAL=low) control and data is sent as regular LVDS data. See [Figure 17](#).

SUPPORT OF CNTLE, CNTLF

The 387/388 will also support the transmission of one or two additional user-defined control signals in the 'dual pixel' DC Balanced output mode which are active during blanking while VSYNC is low. The additional control signals, referred to as CNTLE and CNTLF, should be multiplexed with data signals and provided to the transmitter inputs. Inputs B26 - CNTLF and B27 - CNTLE are designated for this purpose. When operating in 'DC Balanced' mode, controls (CNTLE, CNTLF) are transmitted on LVDS channels A4 and A5 during the blanking interval when VSYNC is low. CNTLE and CNTLF are sampled ONE (1) clock cycle after VSYNC transitions from a HIGH to a LOW state. CNTLE and CNTLF are sampled on each cycle until VSYNC transitions from a LOW to a HIGH, and they are then latched until the next VSYNC LOW cycle. Refer to [Figure 20](#) for details. These signals may be active only during blanking while VSYNC is low. Control signal levels are latched and held in the last valid state when VSYNC transitions from low to high. These control signals are available as TTL outputs on the receiver. CNTLE and CNTLF outputs on the DS90CF388 should be left as a no connect (NC) when not used.

Deskew

The OpenLDI receiver (DS90CF388) is able to tolerate a minimum of 300ps skew between the signals arriving on a single differential pair (intra-pair) and a minimum of ± 1 LVDS data bit time skew between signals arriving on dependent differential pair (pair-to-pair). This is supported in the DC Balance data transmission mode only. Each data channel is deskewed independently and is tuned with a step size of 1/3 of a bit time over a range of ± 1 TBIT. The Deskew feature operates up to clock rates of 80 MHz only. When using the DESKEW feature, the sampling strobe will remain within the middle third of the LVDS sub symbol. To complete the deskew operation, a minimum of four clock cycles is required during blanking time. This allows the chipset to support reduced blanking applications.

Backwards Compatible Mode with FPD-Link

The transmitter provides a second LVDS output clock. Both LVDS clocks will be identical in 'Dual pixel mode'. This feature supports backward compatibility with the previous generation of devices - the second clock allows the transmitter to interface to panels using a 'dual pixel' configuration of two 24-bit or 18-bit 'notebook' receivers.

Note that redundant copies of certain signals are also sent. These signals are denoted with an * symbol, and are shown in [Figure 17](#). The DS90CF388 does not sample the bits show with an * symbol. If interfacing with FPD-Link Receivers, these signals may be recovered if desired.

Pre-emphasis feature is available for use in both the DC Balanced and non-DC Balanced (backwards compatible) modes.

Transmitter Features

The transmitter is designed to reject cycle-to-cycle jitter which may be seen at the transmitter input clock. Very low cycle-to-cycle jitter is passed on to the transmitter outputs. Cycle-to-cycle jitter has been measured over frequency to be less than 100 ps with input step function jitter applied. This should be subtracted from the RSKM/RSKMD budget as shown and described in [Figure 12](#) and [Figure 13](#). This rejection capability significantly reduces the impact of jitter at the TXinput clock pin, and improves the accuracy of data sampling in the receiver. Transmitter output jitter is effected by PLLVCC noise and input clock jitter - minimize supply noise and use a low jitter clock source to limit output jitter. Timing and control signals (VSYNC, HSYNC, DE and two user-defined signals) are sent during blanking intervals to ensure correct reception of these critical signals.

The transmitter is offered with programmable edge data strobes for convenient interface with a variety of graphics controllers. The transmitter can be programmed for rising edge strobe or falling edge strobe through a dedicated pin. A rising edge transmitter will inter-operate with a falling edge receiver without any translation logic.

RSKM - Receiver Skew Margin

RSKM is a chipset parameter and is explained in AN-1059 ([SNLA050](#)) in detail. It is the difference between the transmitter's pulse position and the receiver's strobe window. RSKM must be greater than the summation of: Interconnect skew, LVDS Source Clock Jitter (TJCC), and ISI (if any). See [Figure 12](#). Interconnect skew includes PCB traces differences, connector skew and cable skew for a cable application. PCB trace and connector skew can be compensated for in the design of the system. Cable skew is media type and length dependant.

RSKMD - Receiver Skew Margin with DESKEW

RSKMD is a chipset parameter and is applicable when the DESKEW feature of the DS90CF388 is employed. It is the difference between the receiver's strobe window and the ideal pulse locations. The DESKEW feature adjusts for skew between each data channel and the clock channel. This feature is supported up to 80 MHz clock rate. RSKMD must be greater than the summation of: Transmitter's Pulse Position variance, LVDS Source Clock Jitter (TJCC), and ISI (if any). See [Figure 12](#). With Deskew, RSKMD is $\geq 25\%$ of TBIT. Deskew compensates for interconnect skew which includes PCB traces differences, connector skew and cable skew (for a cable application). PCB trace and connector skew can be compensated for in the design of the system. Note, cable skew is media type and length dependant. Cable length may be limited by the RSKMD parameter prior to the interconnect skew reaching 1 TBIT in length due to ISI effects.

POWER DOWN

Both transmitter and receiver provide a power down feature. When asserted current draw through the supply pins is minimized and the PLLs are shut down. The transmitter outputs are in TRI-STATE when in power down mode. The receiver outputs are forced to a active LOW state when in the power down mode. (See [Transmitter Pin Descriptions](#) and [Receiver Pin Descriptions](#)). The PD pin should be driven HIGH to enable the device once V_{CC} is stable.

DS90C387A/DS90CF388A

The DS90C387/CF388 chipset is electrically similar to the DS90C387A/CF388A. The DS90C387A/CF388A is recommended if support of longer cable drive is not required. DC Balance data transmission and cable deskew features are disabled to minimize overall power dissipation. The devices will also directly inter-operate with existing FPD-Link devices for backward compatibility.

Configuration Table

Table 7. TRANSMITTER / RECEIVER CONFIGURATION TABLE

| Pin | Condition | Configuration |
|------------------------|--------------------|--|
| R_FB (Tx only) | R_FB = V_{CC} | Rising Edge Data Strobe |
| | R_FB = GND | Falling Edge Data Strobe |
| R_FDE (both Tx and Rx) | R_FDE = V_{CC} | Active data DE = High |
| | R_FDE = GND | Active data DE = Low |
| BAL (both Tx and Rx) | BAL = V_{CC} | DC Balanced enabled |
| | BAL = Gnd | DC Balanced disabled (backward compatible to FPD-Link) |
| DUAL (Tx only) | DUAL = V_{CC} | 48-bit color (dual pixel) support |
| | DUAL = $1/2V_{CC}$ | Single-to-dual support |
| | DUAL = Gnd | 24-bit color (single pixel) support |

Pin Diagrams

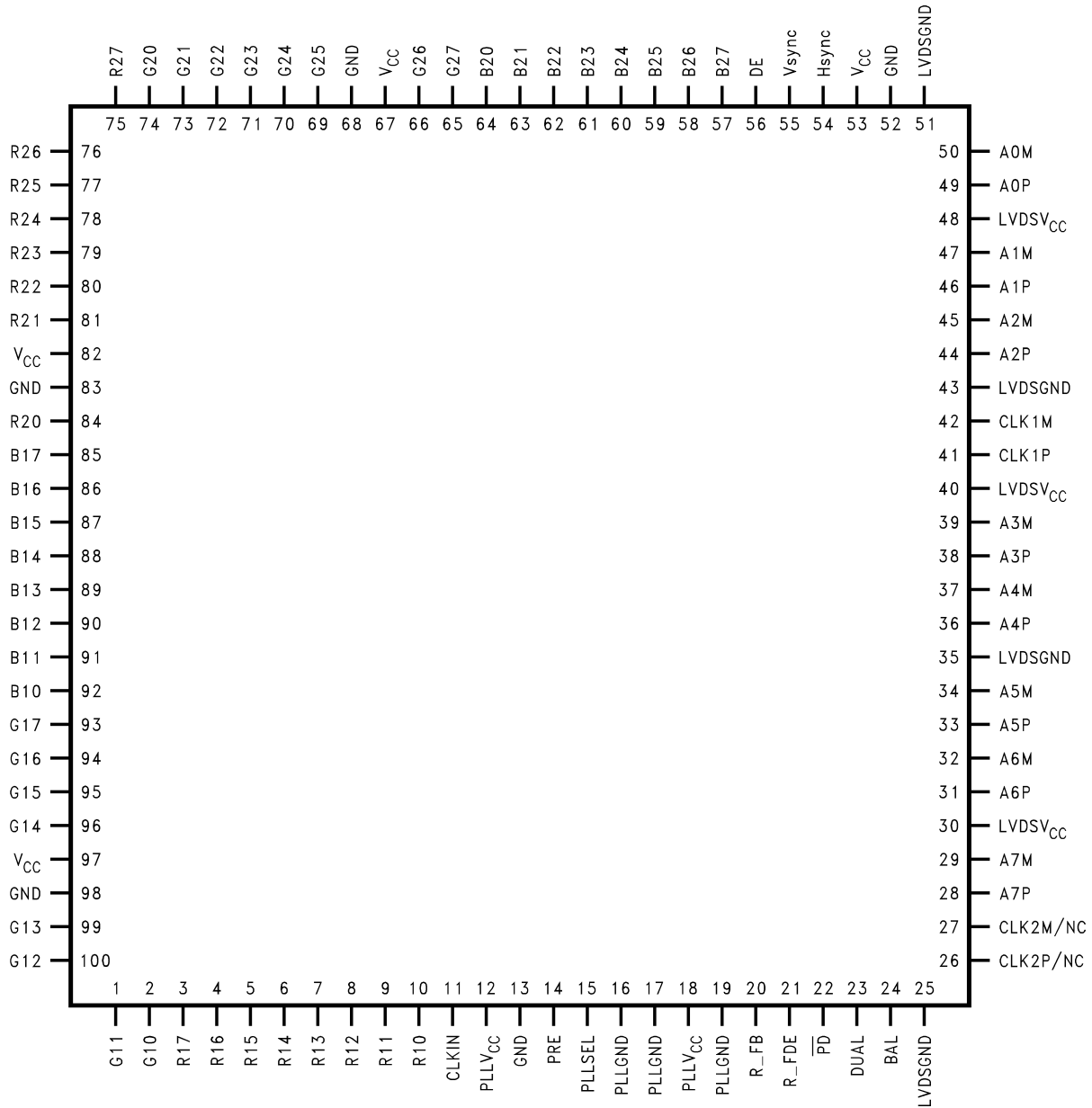


Figure 21. Transmitter-DS90C387
See Package Number NEZ0100A

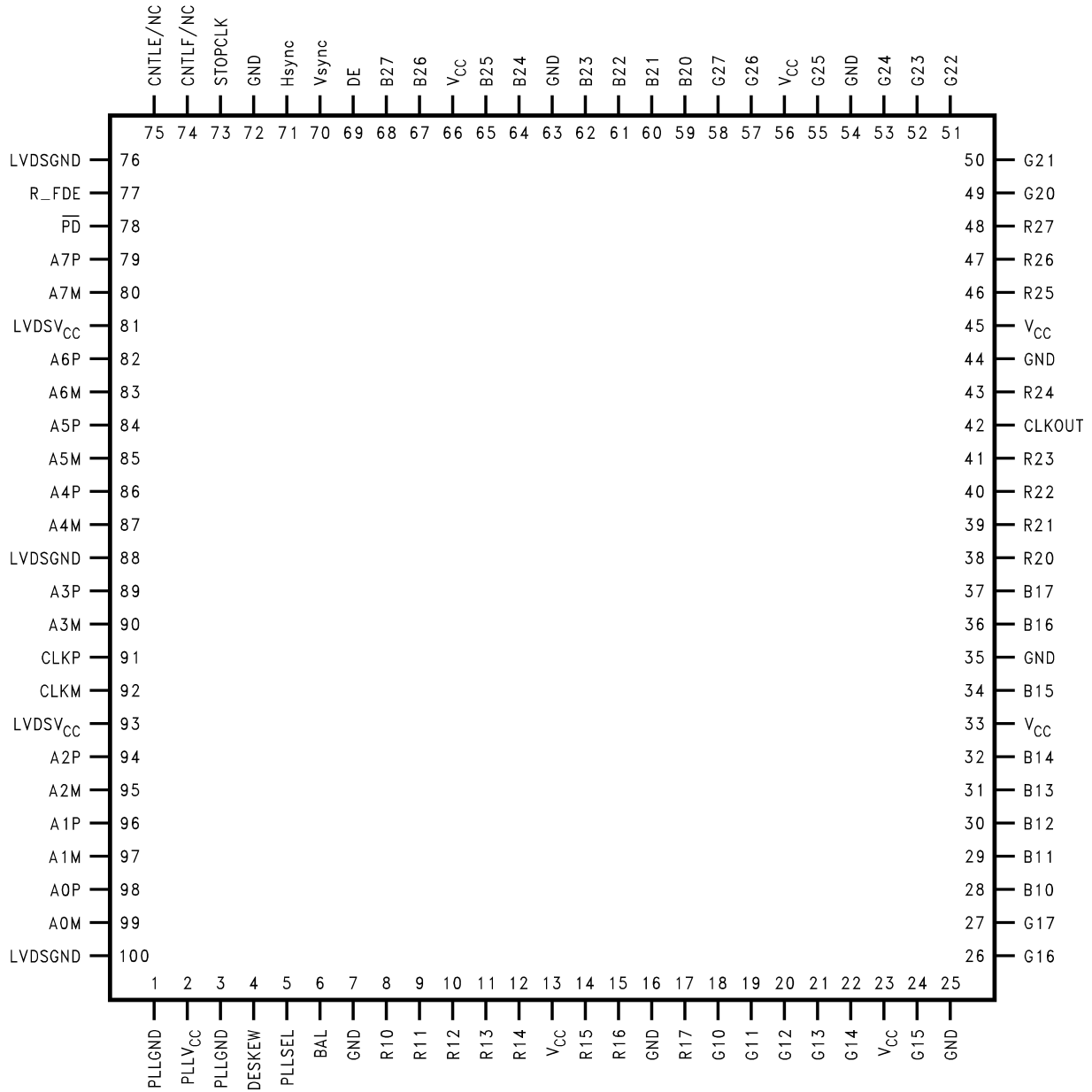


Figure 22. Receiver-DS90CF388
See Package Number NEZ0100A

REVISION HISTORY

| Changes from Revision G (April 2013) to Revision H | Page |
|--|--------------------|
| • Changed layout of National Data Sheet to TI format | 26 |

PACKAGING INFORMATION

| Orderable Device | Status (1) | Package Type | Package Drawing | Pins | Package Qty | Eco Plan (2) | Lead/Ball Finish (6) | MSL Peak Temp (3) | Op Temp (°C) | Device Marking (4/5) | Samples |
|--------------------|---------------|--------------|--------------------|------|----------------|----------------------------|-------------------------|----------------------|--------------|-------------------------|-------------------------|
| DS90C387VJD | NRND | TQFP | NEZ | 100 | 90 | TBD | Call TI | Call TI | -10 to 70 | DS90C387VJD >B | |
| DS90C387VJD/NOPB | ACTIVE | TQFP | NEZ | 100 | 90 | Green (RoHS & no Sb/Br) | CU NIPDAU | Level-3-260C-168 HR | -10 to 70 | DS90C387VJD >B | Samples |
| DS90C387VJDX/NOPB | ACTIVE | TQFP | NEZ | 100 | 1000 | Green (RoHS & no Sb/Br) | CU NIPDAU | Level-3-260C-168 HR | -10 to 70 | DS90C387VJD >B | Samples |
| DS90CF388VJD/NOPB | ACTIVE | TQFP | NEZ | 100 | 90 | Green (RoHS & no Sb/Br) | CU NIPDAU | Level-3-260C-168 HR | -10 to 70 | DS90CF388VJD >B | Samples |
| DS90CF388VJDX/NOPB | ACTIVE | TQFP | NEZ | 100 | 1000 | Green (RoHS & no Sb/Br) | CU NIPDAU | Level-3-260C-168 HR | -10 to 70 | DS90CF388VJD >B | Samples |

(1) The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

OBSOLETE: TI has discontinued the production of the device.

(2) Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS), Pb-Free (RoHS Exempt), or Green (RoHS & no Sb/Br) - please check <http://www.ti.com/productcontent> for the latest availability information and additional product content details.

TBD: The Pb-Free/Green conversion plan has not been defined.

Pb-Free (RoHS): TI's terms "Lead-Free" or "Pb-Free" mean semiconductor products that are compatible with the current RoHS requirements for all 6 substances, including the requirement that lead not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, TI Pb-Free products are suitable for use in specified lead-free processes.

Pb-Free (RoHS Exempt): This component has a RoHS exemption for either 1) lead-based flip-chip solder bumps used between the die and package, or 2) lead-based die adhesive used between the die and leadframe. The component is otherwise considered Pb-Free (RoHS compatible) as defined above.

Green (RoHS & no Sb/Br): TI defines "Green" to mean Pb-Free (RoHS compatible), and free of Bromine (Br) and Antimony (Sb) based flame retardants (Br or Sb do not exceed 0.1% by weight in homogeneous material)

(3) MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

(4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

(5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

⁽⁶⁾ Lead/Ball Finish - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead/Ball Finish values may wrap to two lines if the finish value exceeds the maximum column width.

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TAPE AND REEL INFORMATION



QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



*All dimensions are nominal

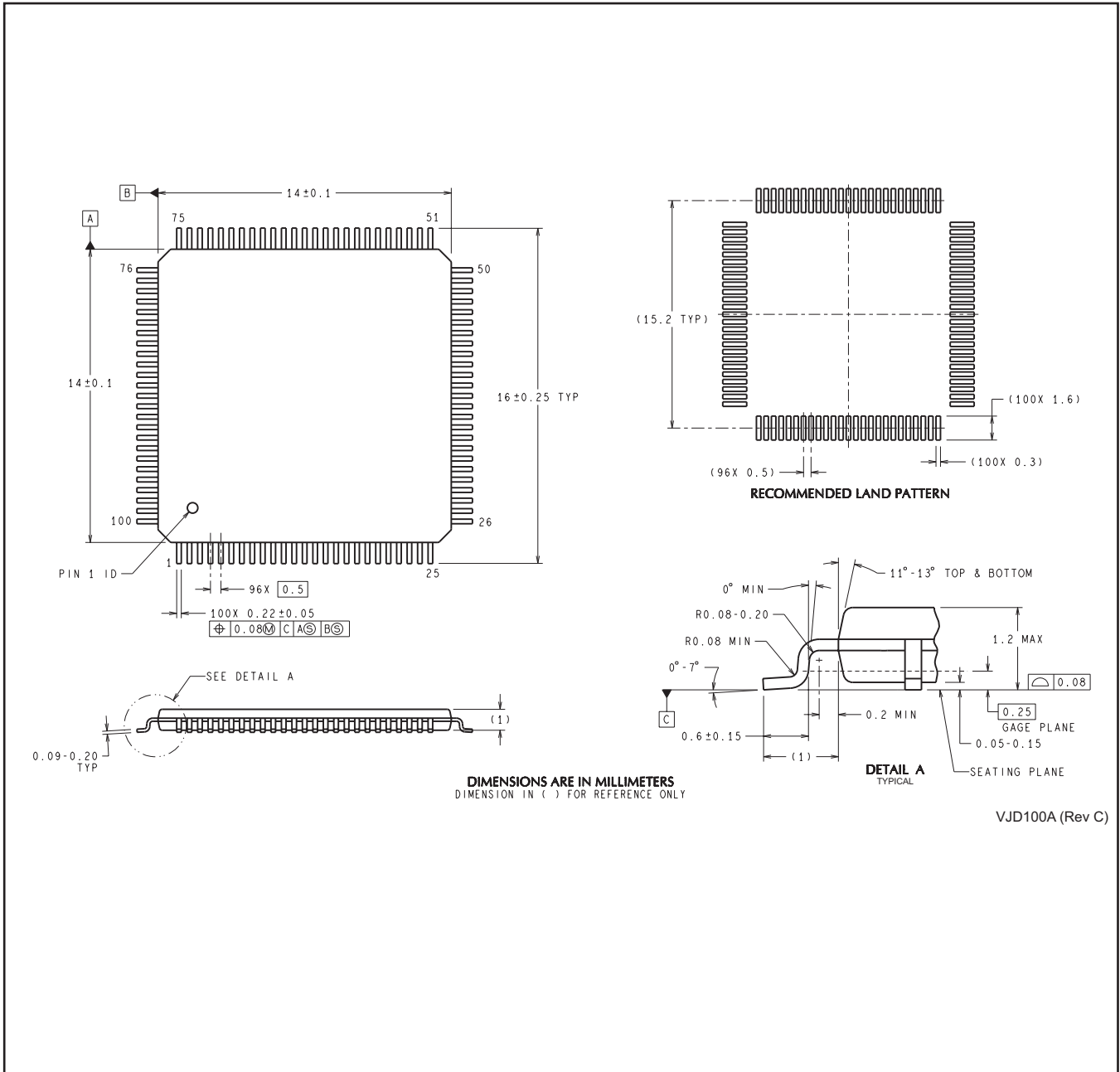
| Device | Package Type | Package Drawing | Pins | SPQ | Reel Diameter (mm) | Reel Width W1 (mm) | A0 (mm) | B0 (mm) | K0 (mm) | P1 (mm) | W (mm) | Pin1 Quadrant |
|--------------------|--------------|-----------------|------|------|--------------------|--------------------|---------|---------|---------|---------|--------|---------------|
| DS90C387VJDX/NOPB | TQFP | NEZ | 100 | 1000 | 330.0 | 32.4 | 18.0 | 18.0 | 1.6 | 24.0 | 32.0 | Q2 |
| DS90CF388VJDX/NOPB | TQFP | NEZ | 100 | 1000 | 330.0 | 32.4 | 18.0 | 18.0 | 1.6 | 24.0 | 32.0 | Q2 |

TAPE AND REEL BOX DIMENSIONS


*All dimensions are nominal

| Device | Package Type | Package Drawing | Pins | SPQ | Length (mm) | Width (mm) | Height (mm) |
|--------------------|--------------|-----------------|------|------|-------------|------------|-------------|
| DS90C387VJDX/NOPB | TQFP | NEZ | 100 | 1000 | 367.0 | 367.0 | 55.0 |
| DS90CF388VJDX/NOPB | TQFP | NEZ | 100 | 1000 | 367.0 | 367.0 | 55.0 |

PFD0100A



VJD100A (Rev C)

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