



**THE DATASHEET OF
MT47H64M16NF-25E AAT:M TR**



Automotive DDR2 SDRAM Data Sheet Addendum

MT47H128M8 – 16 Meg x 8 x 8 banks

MT47H64M16 – 8 Meg x 16 x 8 banks

Features

- This addendum provides information to add Automotive Ultra-high Temperature (AUT) option² for the data sheet. This addendum does not provide detailed information about the device. Refer to the full data sheet for a complete description of device functionality, operating modes, and specifications for the same Micron part number products.
- $V_{DD} = 1.8V \pm 0.1V$, $V_{DDQ} = 1.8V \pm 0.1V$
- JEDEC-standard 1.8V I/O (SSTL_18-compatible)
- Differential data strobe (DQS, DQS#) option
- 4n-bit prefetch architecture
- Duplicate output strobe (RDQS) option for x8
- DLL to align DQ and DQS transitions with CK
- 8 internal banks for concurrent operation
- Programmable CAS latency (CL)
- Posted CAS additive latency (AL)
- WRITE latency = READ latency - 1 t_{CK}
- Selectable burst lengths (BL): 4 or 8
- Adjustable data-output drive strength
- 64ms, 8192-cycle refresh
- On-die termination (ODT)
- RoHS-compliant
- Supports JEDEC clock jitter specification
- PPAP submission
- 8D response time

Options¹

- Configuration
 - 128 Meg x 8 (16 Meg x 8 x 8 banks) 128M8
 - 64 Meg x 16 (8 Meg x 16 x 8 banks) 64M16
- FBGA package (Pb-free) – x16
 - 84-ball FBGA (8mm x 12.5mm) NF
- FBGA package (Pb-free) – x8
 - 60-ball FBGA (8mm x 10mm) SH
- Timing – cycle time
 - 2.5ns @ CL = 5 (DDR2-800) -25E
- Special option
 - Standard None
 - Automotive grade A
- Operating temperature
 - Industrial ($-40^{\circ}C \leq T_C \leq +95^{\circ}C$) IT
 - Automotive ($-40^{\circ}C \leq T_C \leq +105^{\circ}C$) AT
 - Ultra-high ($-40^{\circ}C \leq T_C \leq +125^{\circ}C$) UT
- Revision :M

Marking

- Notes:
1. Not all options listed can be combined to define an offered product. Use the Part Catalog Search on www.micron.com for product offerings and availability.
 2. UT option use based on automotive usage model. Please contact Micron sales representative if you have questions.

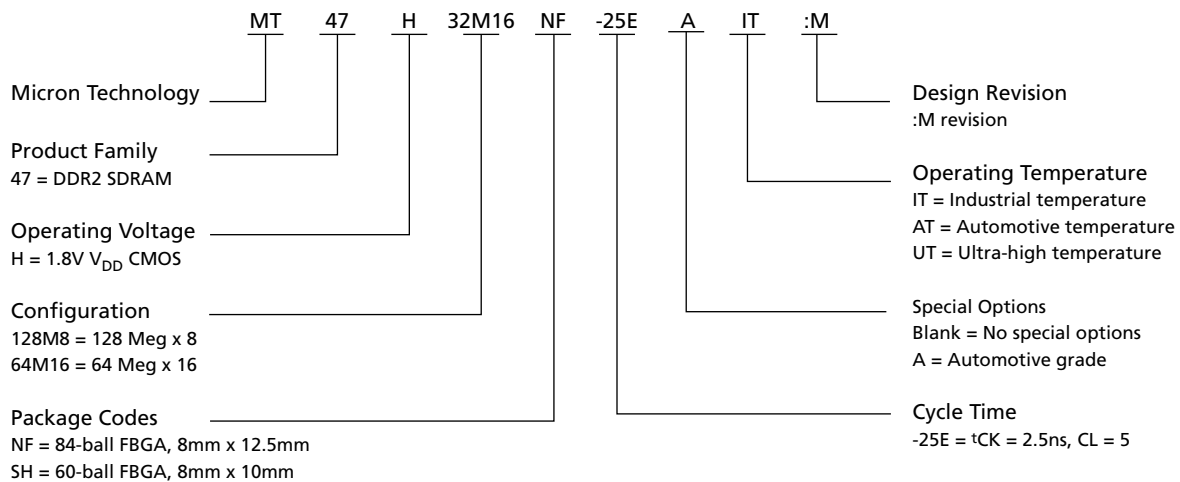
Table 1: Key Timing Parameters

| Speed Grade | Data Rate (MT/s) | | | | t _{RC} (ns) |
|-------------|------------------|--------|--------|--------|----------------------|
| | CL = 3 | CL = 4 | CL = 5 | CL = 6 | |
| -25E | 400 | 533 | 800 | 800 | 55 |

Table 2: Addressing

| Parameter | 128 Meg x 8 | 64 Meg x 16 |
|----------------|----------------------|----------------------|
| Configuration | 16 Meg x 8 x 8 banks | 8 Meg x 16 x 8 banks |
| Refresh count | 8K | 8K |
| Row address | A[13:0] (16K) | A[12:0] (8K) |
| Bank address | BA[2:0] (8) | BA[2:0] (8) |
| Column address | A[9:0] (1K) | A[9:0] (1K) |

Figure 1: 1Gb DDR2 Part Numbers



Note: 1. Not all speeds and configurations are available in all packages.

FBGA Part Number System

Due to space limitations, FBGA-packaged components have an abbreviated part marking that is different from the part number. For a quick conversion of an FBGA code, see the FBGA Part Marking Decoder on Micron’s Web site: <http://www.micron.com>.

Functional Description

The DDR2 SDRAM uses a double data rate architecture to achieve high-speed operation. The double data rate architecture is essentially a $4n$ -prefetch architecture, with an interface designed to transfer two data words per clock cycle at the I/O balls. A single read or write access for the DDR2 SDRAM effectively consists of a single $4n$ -bit-wide, one-clock-cycle data transfer at the internal DRAM core and four corresponding n -bit-wide, one-half-clock-cycle data transfers at the I/O balls.

A bidirectional data strobe (DQS, DQS#) is transmitted externally, along with data, for use in data capture at the receiver. DQS is a strobe transmitted by the DDR2 SDRAM during READs and by the memory controller during WRITEs. DQS is edge-aligned with data for READs and center-aligned with data for WRITEs. The x16 offering has two data strobes, one for the lower byte (LDQS, LDQS#) and one for the upper byte (UDQS, UDQS#).

The DDR2 SDRAM operates from a differential clock (CK and CK#); the crossing of CK going HIGH and CK# going LOW will be referred to as the positive edge of CK. Commands (address and control signals) are registered at every positive edge of CK. Input data is registered on both edges of DQS, and output data is referenced to both edges of DQS as well as to both edges of CK.

Read and write accesses to the DDR2 SDRAM are burst-oriented; accesses start at a selected location and continue for a programmed number of locations in a programmed sequence. Accesses begin with the registration of an ACTIVATE command, which is then followed by a READ or WRITE command. The address bits registered coincident with the ACTIVATE command are used to select the bank and row to be accessed. The address bits registered coincident with the READ or WRITE command are used to select the bank and the starting column location for the burst access.

The DDR2 SDRAM provides for programmable read or write burst lengths of four or eight locations. DDR2 SDRAM supports interrupting a burst read of eight with another read or a burst write of eight with another write. An auto precharge function may be enabled to provide a self-timed row precharge that is initiated at the end of the burst access.

As with standard DDR SDRAM, the pipelined, multibank architecture of DDR2 SDRAM enables concurrent operation, thereby providing high, effective bandwidth by hiding row precharge and activation time.

A self refresh mode is provided, along with a power-saving, power-down mode.

All inputs are compatible with the JEDEC standard for SSTL_18. All full drive-strength outputs are SSTL_18-compatible.

Automotive Industrial Temperature (AIT)

The industrial temperature (AIT) option, if offered, the case temperature cannot be less than -40°C or greater than $+95^{\circ}\text{C}$. JEDEC specifications require the refresh rate to double when T_C exceeds $+85^{\circ}\text{C}$; this also requires use of the high-temperature self refresh option. Additionally, ODT resistance, the input/output impedance, and I_{DD} values must be derated when T_C is $< 0^{\circ}\text{C}$ or $> +85^{\circ}\text{C}$.

Automotive-grade Automotive Temperature (AAT)

The automotive-grade automotive temperature (AAT) option, if offered, the case temperature cannot be less than -40°C or greater than $+105^{\circ}\text{C}$. JEDEC specifications require the refresh rate to double when T_C exceeds $+85^{\circ}\text{C}$; this also requires use of the high-temperature self refresh option. Additionally, ODT resistance, the input/output impedance, and I_{DD} values must be derated when T_C is $< 0^{\circ}\text{C}$ or $> +85^{\circ}\text{C}$.

Automotive Ultra-high Temperature (AUT)

The automotive ultra-high temperature (AUT) option, if offered, the case temperature cannot be less than -40°C or greater than $+125^{\circ}\text{C}$. JEDEC specifications require the refresh rate to double when T_C exceeds $+85^{\circ}\text{C}$; this also requires use of the high-temperature auto refresh mode. When $T_C > +105^{\circ}\text{C}$, the refresh rate must be increased to 8X. Self refresh mode is not available for $T_C > +105^{\circ}\text{C}$. . Additionally, ODT resistance, the input/output impedance, and I_{DD} values must be derated when T_C is $< 0^{\circ}\text{C}$ or $> +85^{\circ}\text{C}$.

General Notes

- The functionality and the timing specifications discussed in this data sheet are for the DLL-enabled mode of operation.
 - Throughout the data sheet, the various figures and text refer to DQs as “DQ.” The DQ term is to be interpreted as any and all DQ collectively, unless specifically stated otherwise. Additionally, the x16 is divided into 2 bytes: the lower byte and the upper byte. For the lower byte (DQ0–DQ7), DM refers to LDM and DQS refers to LDQS. For the upper byte (DQ8–DQ15), DM refers to UDM and DQS refers to UDQS.
 - A x16 device's DQ bus is comprised of two bytes. If only one of the bytes needs to be used, use the lower byte for data transfers and terminate the upper byte as noted:
 - Connect UDQS to ground via $1\text{k}\Omega^*$ resistor
 - Connect UDQS# to V_{DD} via $1\text{k}\Omega^*$ resistor
 - Connect UDM to V_{DD} via $1\text{k}\Omega^*$ resistor
 - Connect DQ[15:8] individually to either V_{SS} or V_{DD} via $1\text{k}\Omega^*$ resistors, or float DQ[15:8].
- *If ODT is used, $1\text{k}\Omega$ resistor should be changed to 4x that of the selected ODT.
- Complete functionality is described throughout the document, and any page or diagram may have been simplified to convey a topic and may not be inclusive of all requirements.
 - Any specific requirement takes precedence over a general statement.



Electrical Specifications – Absolute Ratings

Stresses greater than those listed may cause permanent damage to the device. This is a stress rating only, and functional operation of the device at these or any other conditions outside those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect reliability.

Table 3: Absolute Maximum DC Ratings

| Parameter | Symbol | Min | Max | Units | Notes |
|---|------------------------------------|------|-----|-------|-------|
| V _{DD} supply voltage relative to V _{SS} | V _{DD} | -1.0 | 2.3 | V | 1 |
| V _{DDQ} supply voltage relative to V _{SSQ} | V _{DDQ} | -0.5 | 2.3 | V | 1, 2 |
| V _{DDL} supply voltage relative to V _{SSL} | V _{DDL} | -0.5 | 2.3 | V | 1 |
| Voltage on any ball relative to V _{SS} | V _{IN} , V _{OUT} | -0.5 | 2.3 | V | 3 |
| Input leakage current; any input 0V ≤ V _{IN} ≤ V _{DD} ; all other balls not under test = 0V | I _I | -5 | 5 | μA | |
| Output leakage current; 0V ≤ V _{OUT} ≤ V _{DDQ} ; DQ and ODT disabled | I _{OZ} | -5 | 5 | μA | |
| V _{REF} leakage current; V _{REF} = Valid V _{REF} level | I _{VREF} | -2 | 2 | μA | |

- Notes:
1. V_{DD}, V_{DDQ}, and V_{DDL} must be within 300mV of each other at all times; this is not required when power is ramping down.
 2. V_{REF} ≤ 0.6 × V_{DDQ}; however, V_{REF} may be ≥ V_{DDQ} provided that V_{REF} ≤ 300mV.
 3. Voltage on any I/O may not exceed voltage on V_{DDQ}.

Temperature and Thermal Impedance

It is imperative that the DDR2 SDRAM device’s temperature specifications, shown in Table 4 (page 6), be maintained in order to ensure the junction temperature is in the proper operating range to meet data sheet specifications. An important step in maintaining the proper junction temperature is using the device’s thermal impedances correctly. The thermal impedances are listed in Table 5 (page 6) for the applicable and available die revision and packages.

Incorrectly using thermal impedances can produce significant errors. Read Micron technical note TN-00-08, “Thermal Applications” prior to using the thermal impedances listed in Table 5. For designs that are expected to last several years and require the flexibility to use several DRAM die shrinks, consider using final target theta values (rather than existing values) to account for increased thermal impedances from the die size reduction.

The DDR2 SDRAM device’s safe junction temperature range can be maintained when the T_C specification is not exceeded. In applications where the device’s ambient temperature is too high, use of forced air and/or heat sinks may be required in order to satisfy the case temperature specifications.

Table 4: Temperature Limits

| Parameter | Symbol | Min | Max | Units | Notes |
|--|-----------|-----|-----|-------|-------|
| Storage temperature | T_{STG} | -55 | 150 | °C | 1 |
| Operating temperature: commercial (CT) | T_C | 0 | 85 | °C | 2, 3 |
| Operating temperature: industrial (IT) | T_C | -40 | 95 | °C | 2, 3, |
| Operating temperature: automotive (AT) | T_C | -40 | 105 | °C | 2, 3, |
| Operating temperature: ultra-high (UT) | T_C | -40 | 125 | °C | 2,3,4 |

- Notes:
1. MAX storage case temperature T_{STG} is measured in the center of the package, as shown in Figure 2. This case temperature limit is allowed to be exceeded briefly during package reflow, as noted in Micron technical note TN-00-15, "Recommended Soldering Parameters."
 2. MAX operating case temperature T_C is measured in the center of the package, as shown in Figure 2.
 3. Device functionality is not guaranteed if the device exceeds maximum T_C during operation.
 4. Ultra-high temperature use based on automotive usage model. Please contact Micron sales representative if you have questions.

Figure 2: Example Temperature Test Point Location

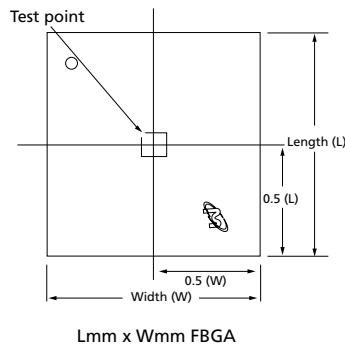


Table 5: Thermal Impedance

| Die Revision | Package | Substrate (pcb) | θ_{JA} (°C/W) | θ_{JA} (°C/W) | θ_{JA} (°C/W) | θ_{JB} (°C/W) | θ_{JC} (°C/W) |
|----------------|---------|-------------------|----------------------|----------------------|----------------------|----------------------|----------------------|
| | | | Airflow = 0m/s | Airflow = 1m/s | Airflow = 2m/s | | |
| M ¹ | 60-ball | Low Conductivity | 85.4 | 70.6 | 64.5 | 42.8 | 11.7 |
| | | High Conductivity | 63.2 | 56.1 | 52.8 | | |
| | 84-ball | Low Conductivity | 80.8 | 67.0 | 61.6 | 44.7 | 11.7 |
| | | High Conductivity | 59.7 | 53.3 | 50.7 | | |

- Note: 1. Thermal resistance data is based on a number of samples from multiple lots and should be viewed as a typical number.



Electrical Specifications – I_{DD} Parameters

I_{DD} Specifications and Conditions

Table 6: General I_{DD} Parameters

| I _{DD} Parameters | -25E | Units |
|---|--|-----------------|
| CL (I _{DD}) | 5 | ^t CK |
| ^t RCD (I _{DD}) | 12.5 | ns |
| ^t RC (I _{DD}) | 57.5 | ns |
| ^t RRD (I _{DD}) - x8 (1KB) | 7.5 | ns |
| ^t RRD (I _{DD}) - x16 (2KB) | 10 | ns |
| ^t CK (I _{DD}) | 2.5 | ns |
| ^t RAS MIN (I _{DD}) | 45 | ns |
| ^t RAS MAX (I _{DD}) | 70,000 | ns |
| ^t RP (I _{DD}) | 12.5 | ns |
| ^t RFC (I _{DD} - 256Mb) | 75 | ns |
| ^t RFC (I _{DD} - 512Mb) | 105 | ns |
| ^t RFC (I _{DD} - 1Gb) | 127.5 | ns |
| ^t RFC (I _{DD} - 2Gb) | 197.5 | ns |
| ^t FAW (I _{DD}) - x8 (1KB) | Defined by pattern in Table 7 (page 7) | |
| ^t FAW (I _{DD}) - x16 (2KB) | Defined by pattern in Table 7 (page 7) | |

I_{DD7} Conditions

The detailed timings are shown below for I_{DD7}. Where general I_{DD} parameters in Table 6 (page 7) conflict with pattern requirements of Table 7, then Table 7 requirements take precedence.

Table 7: I_{DD7} Timing Patterns (8-Bank Interleave READ Operation)

| Speed Grade | I _{DD7} Timing Patterns |
|--|---|
| Timing patterns for 8-bank x4/x8 devices | |
| -25E | A0 RA0 D A1 RA1 D A2 RA2 D A3 RA3 D D A4 RA4 D A5 RA5 D A6 RA6 D A7 RA7 D D D |
| Timing patterns for 8-bank x16 devices | |
| -25E | A0 RA0 D D A1 RA1 D D A2 RA2 D D A3 RA3 D D D A4 RA4 D D A5 RA5 D D A6 RA6 D D A7 RA7 D D D D |

- Notes:
1. A = active; RA = read auto precharge; D = deselect.
 2. All banks are being interleaved at ^tRC (I_{DD}) without violating ^tRRD (I_{DD}) using a BL = 4.
 3. Control and address bus inputs are stable during deselections.

Table 8: DDR2 I_{DD} Specifications and Conditions (Die Revision M)

Notes: 1–7 apply to the entire table

| Parameter/Condition | Symbol | Configuration | -25E | Units |
|---|---|-----------------------|------|-------|
| Operating one bank active-precharge current: $t_{CK} = t_{CK}(I_{DD})$, $t_{RC} = t_{RC}(I_{DD})$, $t_{RAS} = t_{RAS\ MIN}(I_{DD})$; CKE is HIGH, CS# is HIGH between valid commands; Address bus inputs are switching; Data bus inputs are switching | I _{DD0} | x8 | 65 | mA |
| | | x16 | 80 | |
| Operating one bank active-read-precharge current: I _{OUT} = 0mA; BL = 4, CL = CL(I _{DD}), AL = 0; $t_{CK} = t_{CK}(I_{DD})$, $t_{RC} = t_{RC}(I_{DD})$, $t_{RAS} = t_{RAS\ MIN}(I_{DD})$, $t_{RCD} = t_{RCD}(I_{DD})$; CKE is HIGH, CS# is HIGH between valid commands; Address bus inputs are switching; Data pattern is same as I _{DD4W} | I _{DD1} | x8 | 75 | mA |
| | | x16 | 95 | |
| Precharge power-down current: All banks idle; $t_{CK} = t_{CK}(I_{DD})$; CKE is LOW; Other control and address bus inputs are stable; Data bus inputs are floating | I _{DD2P} | x8, x16 | 10 | mA |
| Precharge quiet standby current: All banks idle; $t_{CK} = t_{CK}(I_{DD})$; CKE is HIGH, CS# is HIGH; Other control and address bus inputs are stable; Data bus inputs are floating | I _{DD2Q} | x8 | 24 | mA |
| | | x16 | 26 | |
| Precharge standby current: All banks idle; $t_{CK} = t_{CK}(I_{DD})$; CKE is HIGH, CS# is HIGH; Other control and address bus inputs are switching; Data bus inputs are switching | I _{DD2N} | x8 | 28 | mA |
| | | x16 | 30 | |
| Active power-down current: All banks open; $t_{CK} = t_{CK}(I_{DD})$; CKE is LOW; Other control and address bus inputs are stable; Data bus inputs are floating | I _{DD3P} I _{DD3Ps} | Fast exit MR12 = 0 | 30 | mA |
| | | Slow exit MR12 = 1 | 20 | |
| Active standby current: All banks open; $t_{CK} = t_{CK}(I_{DD})$, $t_{RAS} = t_{RAS\ MAX}(I_{DD})$, $t_{RP} = t_{RP}(I_{DD})$; CKE is HIGH, CS# is HIGH between valid commands; Other control and address bus inputs are switching; Data bus inputs are switching | I _{DD3N} | x8 | 33 | mA |
| | | x16 | 38 | |
| Operating burst write current: All banks open, continuous burst writes; BL = 4, CL = CL(I _{DD}), AL = 0; $t_{CK} = t_{CK}(I_{DD})$, $t_{RAS} = t_{RAS\ MAX}(I_{DD})$, $t_{RP} = t_{RP}(I_{DD})$; CKE is HIGH, CS# is HIGH between valid commands; Address bus inputs are switching; Data bus inputs are switching | I _{DD4W} | x8 | 125 | mA |
| | | x16 | 160 | |
| Operating burst read current: All banks open, continuous burst reads, I _{OUT} = 0mA; BL = 4, CL = CL(I _{DD}), AL = 0; $t_{CK} = t_{CK}(I_{DD})$, $t_{RAS} = t_{RAS\ MAX}(I_{DD})$, $t_{RP} = t_{RP}(I_{DD})$; CKE is HIGH, CS# is HIGH between valid commands; Address bus inputs are switching; Data bus inputs are switching | I _{DD4R} | x8 | 120 | mA |
| | | x16 | 150 | |
| Burst refresh current: $t_{CK} = t_{CK}(I_{DD})$; REFRESH command at every $t_{RFC}(I_{DD})$ interval; CKE is HIGH, CS# is HIGH between valid commands; Other control and address bus inputs are switching; Data bus inputs are switching | I _{DD5} | x8 | 155 | mA |
| | | x16 | 160 | |
| Self refresh current: CK and CK# at 0V; CKE ≤ 0.2V; Other control and address bus inputs are floating; Data bus inputs are floating | I _{DD6} | x8, x16 | 7 | mA |

Table 8: DDR2 I_{DD} Specifications and Conditions (Die Revision M) (Continued)

Notes: 1–7 apply to the entire table

| Parameter/Condition | Symbol | Configuration | -25E | Units |
|--|------------------|---------------|------|-------|
| Operating bank interleave read current: All bank interleaving reads, I _{OUT} = 0mA; BL = 4, CL = CL (I _{DD}), AL = t _{RCD} (I _{DD}) - 1 × t _{CK} (I _{DD}); t _{CK} = t _{CK} (I _{DD}), t _{RC} = t _{RC} (I _{DD}), t _{RRD} = t _{RRD} (I _{DD}), t _{RCD} = t _{RCD} (I _{DD}); CKE is HIGH, CS# is HIGH between valid commands; Address bus inputs are stable during deselects; Data bus inputs are switching; See IDD7 Conditions for details | I _{DD7} | x8 | 210 | mA |
| | | x16 | 260 | |

- Notes:
- I_{DD} specifications are tested after the device is properly initialized. 0°C ≤ T_C ≤ +85°C.
 - V_{DD} = +1.8V ±0.1V, V_{DDQ} = +1.8V ±0.1V, V_{DDL} = +1.8V ±0.1V, V_{REF} = V_{DDQ}/2.
 - I_{DD} parameters are specified with ODT disabled.
 - Data bus consists of DQ, DM, DQS, DQS#, RDQS, RDQS#, LDQS, LDQS#, UDQS, and UDQS#. I_{DD} values must be met with all combinations of EMR bits 10 and 11.
 - Definitions for I_{DD} conditions:
 - LOW** V_{IN} ≤ V_{IL(AC)max}
 - HIGH** V_{IN} ≥ V_{IH(AC)min}
 - Stable** Inputs stable at a HIGH or LOW level
 - Floating** Inputs at V_{REF} = V_{DDQ}/2
 - Switching** Inputs changing between HIGH and LOW every other clock cycle (once per two clocks) for address and control signals
 - Switching** Inputs changing between HIGH and LOW every other data transfer (once per clock) for DQ signals, not including masks or strobes
 - I_{DD1}, I_{DD4R}, and I_{DD7} require A12 in EMR to be enabled during testing.
 - The following I_{DD} values must be derated (I_{DD} limits increase) on IT-option and AT-option devices when operated outside of the range 0°C ≤ T_C ≤ 85°C:
 - When T_C ≤ 0°C** I_{DD2P} and I_{DD3P(SLOW)} must be derated by 4%; I_{DD4R} and I_{DD4W} must be derated by 2%; and I_{DD6} and I_{DD7} must be derated by 7%
 - When T_C ≥ 85°C** I_{DD0}, I_{DD1}, I_{DD2N}, I_{DD2Q}, I_{DD3N}, I_{DD3P(FAST)}, I_{DD4R}, I_{DD4W}, and I_{DD5} must be derated by 2%; I_{DD2P} must be derated by 20%; I_{DD3P(SLOW)} must be derated by 30%; and I_{DD6} must be derated by 80% (I_{DD6} will increase by this amount if T_C < 85°C and the 2X refresh option is still enabled)
 - When T_C ≥ 105°C** 8X refresh is required, self-refresh mode is not available.



1Gb: x8, x16 Automotive DDR2 SDRAM Addendum Electrical Specifications – I_{DD} Parameters

Table 9: AC Operating Specifications and Conditions

Not all speed grades listed may be supported for this device; refer to the title page for speeds supported; Notes: 1–5 apply to the entire table;

V_{DDQ} = 1.8V ±0.1V, V_{DD} = 1.8V ±0.1V

| AC Characteristics | | | -25E | | Units | Notes | |
|------------------------------|------------------------------------|--|--|------|-----------------|----------------|------------|
| Parameter | Symbol | Min | Max | | | | |
| Clock | Clock cycle time | CL = 6 | ^t CK (avg) | 2.5 | 8.0 | ns | 6, 7, 8, 9 |
| | | CL = 5 | ^t CK (avg) | 2.5 | 8.0 | | |
| | | CL = 4 | ^t CK (avg) | 3.75 | 8.0 | | |
| | | CL = 3 | ^t CK (avg) | 5.0 | 8.0 | | |
| | CK high-level width | ^t CH (avg) | 0.48 | 0.52 | ^t CK | 10 | |
| | CK low-level width | ^t CL (avg) | 0.48 | 0.52 | ^t CK | | |
| | Half clock period | ^t HP | MIN = lesser of ^t CH and ^t CL MAX = n/a | | ps | 11 | |
| | Absolute ^t CK | ^t CK (abs) | MIN = ^t CK (AVG) MIN + ^t JITper (MIN) MAX = ^t CK (AVG) MAX + ^t JITper (MAX) | | ps | | |
| Absolute CK high-level width | ^t CH (abs) | MIN = ^t CK (AVG) MIN × ^t CH (AVG) MIN + ^t JITdty (MIN) MAX = ^t CK (AVG) MAX × ^t CH (AVG) MAX + ^t JITdty (MAX) | | ps | | | |
| Absolute CK low-level width | ^t CL (abs) | MIN = ^t CK (AVG) MIN × ^t CL (AVG) MIN + ^t JITdty (MIN) MAX = ^t CK (AVG) MAX × ^t CL (AVG) MAX + ^t JITdty (MAX) | | ps | | | |
| Clock Jitter | Period jitter | ^t JITper | -100 | 100 | ps | 12 | |
| | Half period | ^t JITdty | -100 | 100 | ps | 13 | |
| | Cycle to cycle | ^t JITcc | 200 | | ps | 14 | |
| | Cumulative error, 2 cycles | ^t ERR _{2per} | -150 | 150 | ps | 15 | |
| | Cumulative error, 3 cycles | ^t ERR _{3per} | -175 | 175 | ps | 15 | |
| | Cumulative error, 4 cycles | ^t ERR _{4per} | -200 | 200 | ps | 15 | |
| | Cumulative error, 5 cycles | ^t ERR _{5per} | -200 | 200 | ps | 15, 16 | |
| | Cumulative error, 6–10 cycles | ^t ERR _{6–10per} | -300 | 300 | ps | 15, 16 | |
| Data Strobe-Out | DQS output access time from CK/CK# | ^t DQSCK | -350 | 350 | ps | 19 | |
| | DQS read preamble | ^t RPRE | MIN = 0.9 × ^t CK MAX = 1.1 × ^t CK | | ^t CK | 17, 18, 19 | |
| | DQS read postamble | ^t RPST | MIN = 0.4 × ^t CK MAX = 0.6 × ^t CK | | ^t CK | 17, 18, 19, 20 | |
| | CK/CK# to DQS Low-Z | ^t LZ ₁ | MIN = ^t AC (MIN) MAX = ^t AC (MAX) | | ps | 19, 21, 22 | |



Table 9: AC Operating Specifications and Conditions (Continued)

Not all speed grades listed may be supported for this device; refer to the title page for speeds supported; Notes: 1–5 apply to the entire table;

V_{DDQ} = 1.8V ±0.1V, V_{DD} = 1.8V ±0.1V

| AC Characteristics | | -25E | | Units | Notes | |
|--------------------|--|------------------------------|--|-----------------|--------|------------|
| Parameter | Symbol | Min | Max | | | |
| Data Strobe-In | DQS rising edge to CK rising edge | ^t DQSS | MIN = -0.25 × ^t CK MAX = 0.25 × ^t CK | ^t CK | 18 | |
| | DQS input-high pulse width | ^t DQSH | MIN = 0.35 × ^t CK MAX = n/a | ^t CK | 18 | |
| | DQS input-low pulse width | ^t DQSL | MIN = 0.35 × ^t CK MAX = n/a | ^t CK | 18 | |
| | DQS falling to CK rising: set-up time | ^t DSS | MIN = 0.2 × ^t CK MAX = n/a | ^t CK | 18 | |
| | DQS falling from CK rising: hold time | ^t DSH | MIN = 0.2 × ^t CK MAX = n/a | ^t CK | 18 | |
| | Write preamble setup time | ^t WPRES | MIN = 0 MAX = n/a | ps | 23, 24 | |
| | DQS write preamble | ^t WPRE | MIN = 0.35 × ^t CK MAX = n/a | ^t CK | 18 | |
| | DQS write postamble | ^t WPST | MIN = 0.4 × ^t CK MAX = 0.6 × ^t CK | ^t CK | 18, 25 | |
| | WRITE command to first DQS transition | – | MIN = WL - ^t DQSS MAX = WL + ^t DQSS | ^t CK | | |
| Data-Out | DQ output access time from CK/CK# | ^t AC | -400 | 400 | ps | 19 |
| | DQS–DQ skew, DQS to last DQ valid, per group, per access | ^t DQSQ | – | 200 | ps | 26, 27 |
| | DQ hold from next DQS strobe | ^t QHS | – | 300 | ps | 28 |
| | DQ–DQS hold, DQS to first DQ not valid | ^t QH | MIN = ^t HP - ^t QHS MAX = n/a | | ps | 26, 27, 28 |
| | CK/CK# to DQ, DQS High-Z | ^t HZ | MIN = n/a MAX = ^t AC (MAX) | | ps | 19, 21, 29 |
| | CK/CK# to DQ Low-Z | ^t LZ ₂ | MIN = 2 × ^t AC (MIN) MAX = ^t AC (MAX) | | ps | 19, 21, 22 |
| | Data valid output window | DVW | MIN = ^t QH - ^t DQSQ MAX = n/a | | ns | 26, 27 |

Table 9: AC Operating Specifications and Conditions (Continued)

Not all speed grades listed may be supported for this device; refer to the title page for speeds supported; Notes: 1–5 apply to the entire table;

V_{DDQ} = 1.8V ±0.1V, V_{DD} = 1.8V ±0.1V

| AC Characteristics | | | -25E | | Units | Notes | |
|-------------------------------|---|-------------------|---|------|-----------------|------------|--------|
| Parameter | Symbol | Min | Max | | | | |
| Data-In | DQ and DM input setup time to DQS | t ^{DSb} | 50 | – | ps | 26, 30, 31 | |
| | DQ and DM input hold time to DQS | t ^{DHb} | 125 | – | ps | 26, 30, 31 | |
| | DQ and DM input setup time to DQS | t ^{DSa} | 250 | – | ps | 26, 30, 31 | |
| | DQ and DM input hold time to DQS | t ^{DHa} | 250 | – | ps | 26, 30, 31 | |
| | DQ and DM input pulse width | t ^{DIPW} | MIN = 0.35 × t ^{CK} MAX = n/a | | t ^{CK} | 18, 32 | |
| Command and Address | Input setup time | t ^{ISb} | 175 | – | ps | 31, 33 | |
| | Input hold time | t ^{IHb} | 250 | – | ps | 31, 33 | |
| | Input setup time | t ^{ISa} | 375 | – | ps | 31, 33 | |
| | Input hold time | t ^{IHa} | 375 | – | ps | 31, 33 | |
| | Input pulse width | t ^{IPW} | 0.6 | – | t ^{CK} | 18, 32 | |
| | ACTIVATE-to-ACTIVATE delay, same bank | t ^{RC} | 55 | – | ns | 18, 34, 51 | |
| | ACTIVATE-to-READ or WRITE delay | t ^{RCD} | 12.5 | – | ns | 18 | |
| | ACTIVATE-to-PRECHARGE delay | t ^{RAS} | 45 | 70K | ns | 18, 34, 35 | |
| | PRECHARGE period | t ^{RP} | 12.5 | – | ns | 18, 36 | |
| | PRECHARGE ALL period | <1Gb | t ^{RPA} | 12.5 | – | ns | 18, 36 |
| | | ≥1Gb | t ^{RPA} | 15 | – | ns | 18, 36 |
| | ACTIVATE-to-ACTIVATE delay different bank | x8 | t ^{RRD} | 7.5 | – | ns | 18, 37 |
| | | x16 | t ^{RRD} | 10 | – | ns | 18, 37 |
| 4-bank activate period (≥1Gb) | x8 | t ^{FAW} | 35 | – | ns | 18, 38 | |
| | x16 | t ^{FAW} | 45 | – | ns | 18, 38 | |



Table 9: AC Operating Specifications and Conditions (Continued)

Not all speed grades listed may be supported for this device; refer to the title page for speeds supported; Notes: 1–5 apply to the entire table;

V_{DDQ} = 1.8V ±0.1V, V_{DD} = 1.8V ±0.1V

| AC Characteristics | | -25E | | Units | Notes | | |
|------------------------------------|---|---------------------------------------|--|--|-----------------|------------|--------|
| Parameter | Symbol | Min | Max | | | | |
| Command and Address | Internal READ-to-PRE-CHARGE delay | t ^{RTP} | 7.5 | – | ns | 18, 37, 39 | |
| | CAS#-to-CAS# delay | t ^{CCD} | 2 | – | t ^{CK} | 18 | |
| | Write recovery time | t ^{WR} | 15 | – | ns | 18, 37 | |
| | Write AP recovery + pre-charge time | t ^{DAL} | t ^{WR} + t ^{RP} | – | ns | 40 | |
| | Internal WRITE-to-READ delay | t ^{WTR} | 7.5 | – | ns | 18, 37 | |
| | LOAD MODE cycle time | t ^{MRD} | 2 | – | t ^{CK} | 18 | |
| Refresh | REFRESH-to-ACTIVATE or to -REFRESH interval | 256Mb | t ^{RFC} | 75 | – | ns | 18, 41 |
| | | 512Mb | | 105 | – | | |
| | | 1Gb | | 127.5 | – | | |
| | | 2Gb | | 195 | – | | |
| | Average periodic refresh (commercial) | t ^{REFI} | – | 7.8 | µs | 18, 41 | |
| | Average periodic refresh (industrial) | t ^{REFI_{IT}} | – | 3.9 | µs | 18, 41 | |
| | Average periodic refresh (automotive) | t ^{REFI_{AT}} | – | 3.9 | µs | 18, 41 | |
| | Average periodic refresh (automotive) | t ^{REFI_{UT}} | – | 0.975 | µs | 18, 41 | |
| | CKE LOW to CK, CK# uncertainty | t ^{DELAY} | MIN limit = t ^{IS} + t ^{CK} + t ^{IH} MAX limit = n/a | | ns | 42 | |
| | Self Refresh | Exit SELF REFRESH to non-READ command | t ^{XSNR} | MIN limit = t ^{RFC} (MIN) + 10 MAX limit = n/a | | ns | 52 |
| Exit SELF REFRESH to READ command | | t ^{XSRD} | MIN limit = 200 MAX limit = n/a | | t ^{CK} | 18, 52 | |
| Exit SELF REFRESH timing reference | | t ^{ISXR} | MIN limit = t ^{IS} MAX limit = n/a | | ps | 33, 43, 52 | |

Table 9: AC Operating Specifications and Conditions (Continued)

Not all speed grades listed may be supported for this device; refer to the title page for speeds supported; Notes: 1–5 apply to the entire table;

V_{DDQ} = 1.8V ±0.1V, V_{DD} = 1.8V ±0.1V

| AC Characteristics | | | -25E | | Units | Notes | |
|-----------------------------|--|--------------------|--|--------|-----------------|-----------------|----|
| Parameter | | Symbol | Min | Max | | | |
| Power-Down | Exit active power-down to READ command | MR12 = 0 | t _{XARD} | 2 | – | t _{CK} | 18 |
| | | MR12 = 1 | | 8 - AL | – | t _{CK} | 18 |
| | Exit precharge power-down and active power-down to any nonREAD command | t _{XP} | 2 | – | t _{CK} | 18 | |
| CKE MIN HIGH/LOW time | | t _{CKE} | MIN = 3 MAX = n/a | | t _{CK} | 18, 44 | |
| ODT | ODT to power-down entry latency | t _{ANPD} | 3 | – | t _{CK} | 18 | |
| | ODT power-down exit latency | t _{AXPD} | 8 | – | t _{CK} | 18 | |
| | ODT turn-on delay | t _{AOND} | 2 | | t _{CK} | 18 | |
| | ODT turn-off delay | t _{AOFD} | 2.5 | | t _{CK} | 18, 45 | |
| | ODT turn-on | t _{AON} | MIN = t _{AC} (MIN) MAX = t _{AC} (MAX) + 600 | | ps | 19, 46 | |
| | ODT turn-off | t _{AOF} | MIN = t _{AC} (MIN) MAX = t _{AC} (MAX) + 600 | | ps | 47, 48 | |
| | ODT turn-on (power-down mode) | t _{AONPD} | MIN = t _{AC} (MIN) + 2000 MAX = 2 × t _{CK} + t _{AC} (MAX) + 1000 | | ps | 49 | |
| | ODT turn-off (power-down mode) | t _{AOFPD} | MIN = t _{AC} (MIN) + 2000 MAX = 2.5 × t _{CK} + t _{AC} (MAX) + 1000 | | ps | | |
| ODT enable from MRS command | | t _{MOD} | MIN = 12 MAX = n/a | | ns | 18, 50 | |

- Notes:
- All voltages are referenced to V_{SS}.
 - Tests for AC timing, I_{DD}, and electrical AC and DC characteristics may be conducted at nominal reference/supply voltage levels, but the related specifications and the operation of the device are warranted for the full voltage range specified. ODT is disabled for all measurements that are not ODT-specific.
 - Outputs measured with equivalent load (see Figure 2).
 - AC timing and I_{DD} tests may use a V_{IL}-to-V_{IH} swing of up to 1.0V in the test environment, and parameter specifications are guaranteed for the specified AC input levels under normal use conditions. The slew rate for the input signals used to test the device is 1.0 V/ns for signals in the range between V_{IL(AC)} and V_{IH(AC)}. Slew rates other than 1.0 V/ns may require the timing parameters to be derated as specified.
 - The AC and DC input level specifications are as defined in the SSTL_18 standard (that is, the receiver will effectively switch as a result of the signal crossing the AC input level and will remain in that state as long as the signal does not ring back above [below] the DC input LOW [HIGH] level).

6. CK and CK# input slew rate is referenced at 1 V/ns (2 V/ns if measured differentially).
7. Operating frequency is only allowed to change during self refresh mode (see Figure 1), precharge power-down mode, or system reset condition (see Reset). SSC allows for small deviations in operating frequency, provided the SSC guidelines are satisfied.
8. The clock's $t_{CK}^{(AVG)}$ is the average clock over any 200 consecutive clocks and $t_{CK}^{(AVG)}$ MIN is the smallest clock rate allowed (except for a deviation due to allowed clock jitter). Input clock jitter is allowed provided it does not exceed values specified. Also, the jitter must be of a random Gaussian distribution in nature.
9. Spread spectrum is not included in the jitter specification values. However, the input clock can accommodate spread spectrum at a sweep rate in the range 8–60 kHz with an additional one percent $t_{CK}^{(AVG)}$; however, the spread spectrum may not use a clock rate below $t_{CK}^{(AVG)}$ MIN or above $t_{CK}^{(AVG)}$ MAX.
10. MIN (t_{CL} , t_{CH}) refers to the smaller of the actual clock LOW time and the actual clock HIGH time driven to the device. The clock's half period must also be of a Gaussian distribution; $t_{CH}^{(AVG)}$ and $t_{CL}^{(AVG)}$ must be met with or without clock jitter and with or without duty cycle jitter. $t_{CH}^{(AVG)}$ and $t_{CL}^{(AVG)}$ are the average of any 200 consecutive CK falling edges. t_{CH} limits may be exceeded if the duty cycle jitter is small enough that the absolute half period limits ($t_{CH}^{[ABS]}$, $t_{CL}^{[ABS]}$) are not violated.
11. $t_{HP}^{(MIN)}$ is the lesser of t_{CL} and t_{CH} actually applied to the device CK and CK# inputs; thus, $t_{HP}^{(MIN)} \geq$ the lesser of $t_{CL}^{(ABS)}$ MIN and $t_{CH}^{(ABS)}$ MIN.
12. The period jitter ($t_{JITper}^{(J)}$) is the maximum deviation in the clock period from the average or nominal clock allowed in either the positive or negative direction. JEDEC specifies tighter jitter numbers during DLL locking time. During DLL lock time, the jitter values should be 20 percent less than those noted in the table (DLL locked).
13. The half-period jitter ($t_{JITdty}^{(J)}$) applies to either the high pulse of clock or the low pulse of clock; however, the two cumulatively can not exceed $t_{JITper}^{(J)}$.
14. The cycle-to-cycle jitter ($t_{JITcc}^{(J)}$) is the amount the clock period can deviate from one cycle to the next. JEDEC specifies tighter jitter numbers during DLL locking time. During DLL lock time, the jitter values should be 20 percent less than those noted in the table (DLL locked).
15. The cumulative jitter error ($t_{ERR_{nper}}^{(J)}$), where n is 2, 3, 4, 5, 6–10, or 11–50 is the amount of clock time allowed to consecutively accumulate away from the average clock over any number of clock cycles.
16. JEDEC specifies using $t_{ERR_{6-10per}}^{(J)}$ when derating clock-related output timing (see notes 19 and 48). Micron requires less derating by allowing $t_{ERR_{5per}}^{(J)}$ to be used.
17. This parameter is not referenced to a specific voltage level but is specified when the device output is no longer driving (t_{RPST}) or beginning to drive (t_{RPRE}).
18. The inputs to the DRAM must be aligned to the associated clock, that is, the actual clock that latches it in. However, the input timing (in ns) references to the $t_{CK}^{(AVG)}$ when determining the required number of clocks. The following input parameters are determined by taking the specified percentage times the $t_{CK}^{(AVG)}$ rather than t_{CK} : t_{IPW} , t_{DIPW} , t_{DQSS} , t_{DQSH} , t_{DQSL} , t_{DSS} , t_{DSH} , t_{WPST} , and t_{WPRE} .
19. The DRAM output timing is aligned to the nominal or average clock. Most output parameters must be derated by the actual jitter error when input clock jitter is present; this will result in each parameter becoming larger. The following parameters are required to be derated by subtracting $t_{ERR_{5per}}^{(J)}$ (MAX): $t_{AC}^{(MIN)}$, $t_{DQSK}^{(MIN)}$, $t_{LZ_{DQS}}^{(MIN)}$ (MIN), $t_{LZ_{DQ}}^{(MIN)}$, $t_{AON}^{(MIN)}$; while the following parameters are required to be derated by subtracting $t_{ERR_{5per}}^{(J)}$ (MIN): $t_{AC}^{(MAX)}$, $t_{DQSK}^{(MAX)}$, $t_{HZ}^{(MAX)}$, $t_{LZ_{DQS}}^{(MAX)}$, $t_{LZ_{DQ}}^{(MAX)}$, $t_{AON}^{(MAX)}$. The parameter $t_{RPRE}^{(MIN)}$ is derated by subtracting $t_{JITper}^{(J)}$ (MAX), while $t_{RPRE}^{(MAX)}$, is derated by subtracting $t_{JITper}^{(J)}$ (MIN). The parameter $t_{RPST}^{(MIN)}$ is derated by subtracting $t_{JITdty}^{(J)}$ (MAX), while $t_{RPST}^{(MAX)}$, is derated by subtracting $t_{JITdty}^{(J)}$ (MIN). Output timings that require $t_{ERR_{5per}}^{(J)}$ derating can be observed to have offsets relative to the clock; however, the total window will not degrade.
20. When DQS is used single-ended, the minimum limit is reduced by 100ps.

21. t_{HZ} and t_{LZ} transitions occur in the same access time windows as valid data transitions. These parameters are not referenced to a specific voltage level, but specify when the device output is no longer driving (t_{HZ}) or begins driving (t_{LZ}).
22. t_{LZ} (MIN) will prevail over a t_{DQCK} (MIN) + t_{RPRE} (MAX) condition.
23. This is not a device limit. The device will operate with a negative value, but system performance could be degraded due to bus turnaround.
24. It is recommended that DQS be valid (HIGH or LOW) on or before the WRITE command. The case shown (DQS going from High-Z to logic LOW) applies when no WRITES were previously in progress on the bus. If a previous WRITE was in progress, DQS could be HIGH during this time, depending on t_{DQSS} .
25. The intent of the “Don’t Care” state after completion of the postamble is that the DQS-driven signal should either be HIGH, LOW, or High-Z, and that any signal transition within the input switching region must follow valid input requirements. That is, if DQS transitions HIGH (above $V_{IH[DC]min}$), then it must not transition LOW (below $V_{IH[DC]}$) prior to t_{DQSH} (MIN).
26. Referenced to each output group: x8 = DQS with DQ[7:0]; x16 = LDQS with DQ[7:0]; and UDQS with DQ[15:8].
27. The data valid window is derived by achieving other specifications: t_{HP} ($t_{CK}/2$), t_{DQSQ} , and t_{QH} ($t_{QH} = t_{HP} - t_{QHS}$). The data valid window derates in direct proportion to the clock duty cycle and a practical data valid window can be derived.
28. $t_{QH} = t_{HP} - t_{QHS}$; the worst case t_{QH} would be the lesser of t_{CL} (ABS) MAX or t_{CH} (ABS) MAX times t_{CK} (ABS) MIN - t_{QHS} . Minimizing the amount of t_{CH} (AVG) offset and value of t_{JITdty} will provide a larger t_{QH} , which in turn will provide a larger valid data out window.
29. This maximum value is derived from the referenced test load. t_{HZ} (MAX) will prevail over t_{DQCK} (MAX) + t_{RPST} (MAX) condition.
30. The values listed are for the differential DQS strobe (DQS and DQS#) with a differential slew rate of 2 V/ns (1 V/ns for each signal). There are two sets of values listed: t_{DS_a} , t_{DH_a} and t_{DS_b} , t_{DH_b} . The t_{DS_a} , t_{DH_a} values (for reference only) are equivalent to the baseline values of t_{DS_b} , t_{DH_b} at V_{REF} when the slew rate is 2 V/ns, differentially. The baseline values, t_{DS_b} , t_{DH_b} , are the JEDEC-defined values, referenced from the logic trip points. t_{DS_b} is referenced from $V_{IH(AC)}$ for a rising signal and $V_{IL(AC)}$ for a falling signal, while t_{DH_b} is referenced from $V_{IL(DC)}$ for a rising signal and $V_{IH(DC)}$ for a falling signal. If the differential DQS slew rate is not equal to 2 V/ns, then the baseline values must be derated by adding the values from Table 3 and Table 4. If the DQS differential strobe feature is not enabled, then the DQS strobe is single-ended and the baseline values must be derated using Table 5. Single-ended DQS data timing is referenced at DQS crossing V_{REF} . The correct timing values for a single-ended DQS strobe are listed in Table 6–Table 8 on Table 6, Table 7, and Table 8; listed values are already derated for slew rate variations and converted from baseline values to V_{REF} values.
31. V_{IL}/V_{IH} DDR2 overshoot/undershoot. See AC Overshoot/Undershoot Specification.
32. For each input signal—not the group collectively.
33. There are two sets of values listed for command/address: t_{IS_a} , t_{IH_a} and t_{IS_b} , t_{IH_b} . The t_{IS_a} , t_{IH_a} values (for reference only) are equivalent to the baseline values of t_{IS_b} , t_{IH_b} at V_{REF} when the slew rate is 1 V/ns. The baseline values, t_{IS_b} , t_{IH_b} , are the JEDEC-defined values, referenced from the logic trip points. t_{IS_b} is referenced from $V_{IH(AC)}$ for a rising signal and $V_{IL(AC)}$ for a falling signal, while t_{IH_b} is referenced from $V_{IL(DC)}$ for a rising signal and $V_{IH(DC)}$ for a falling signal. If the command/address slew rate is not equal to 1 V/ns, then the baseline values must be derated by adding the values from Table 1 and Table 2.
34. This is applicable to READ cycles only. WRITE cycles generally require additional time due to t_{WR} during auto precharge.
35. READs and WRITEs with auto precharge are allowed to be issued before t_{RAS} (MIN) is satisfied because t_{RAS} lockout feature is supported in DDR2 SDRAM.

36. When a single-bank PRECHARGE command is issued, t^{RP} timing applies. t^{RPA} timing applies when the PRECHARGE (ALL) command is issued, regardless of the number of banks open. For 8-bank devices ($\geq 1\text{Gb}$), $t^{\text{RPA}}(\text{MIN}) = t^{\text{RP}}(\text{MIN}) + t^{\text{CK}}(\text{AVG})$ (Table 9 (page 10) lists $t^{\text{RP}}[\text{MIN}] + t^{\text{CK}}[\text{AVG}] \text{MIN}$).
37. This parameter has a two clock minimum requirement at any t^{CK} .
38. The $t^{\text{FAW}}(\text{MIN})$ parameter applies to all 8-bank DDR2 devices. No more than four bank-ACTIVATE commands may be issued in a given $t^{\text{FAW}}(\text{MIN})$ period. $t^{\text{RRD}}(\text{MIN})$ restriction still applies.
39. The minimum internal READ-to-PRECHARGE time. This is the time from which the last 4-bit prefetch begins to when the PRECHARGE command can be issued. A 4-bit prefetch is when the READ command internally latches the READ so that data will output CL later. This parameter is only applicable when $t^{\text{RTP}}/(2 \times t^{\text{CK}}) > 1$, such as frequencies faster than 533 MHz when $t^{\text{RTP}} = 7.5\text{ns}$. If $t^{\text{RTP}}/(2 \times t^{\text{CK}}) \leq 1$, then equation AL + BL/2 applies. $t^{\text{RAS}}(\text{MIN})$ has to be satisfied as well. The DDR2 SDRAM will automatically delay the internal PRECHARGE command until $t^{\text{RAS}}(\text{MIN})$ has been satisfied.
40. $t^{\text{DAL}} = (n\text{WR}) + (t^{\text{RP}}/t^{\text{CK}})$. Each of these terms, if not already an integer, should be rounded up to the next integer. t^{CK} refers to the application clock period; $n\text{WR}$ refers to the t^{WR} parameter stored in the MR9–MR11. For example, -37E at $t^{\text{CK}} = 3.75\text{ns}$ with t^{WR} programmed to four clocks would have $t^{\text{DAL}} = 4 + (15\text{ns}/3.75\text{ns}) \text{ clocks} = 4 + (4) \text{ clocks} = 8 \text{ clocks}$.
41. The refresh period is 64ms (commercial) or 32ms (industrial and automotive) or 8ms(automotive ultra-high temperature). This equates to an average refresh rate of 7.8125 μs (commercial) or 3.9607 μs (industrial and automotive) or 0.975 μs (automotive ultra-high temperature). To ensure all rows of all banks are properly refreshed, 8192 REFRESH commands must be issued every 64ms (commercial) or 32ms (industrial and automotive) or 8ms(automotive ultra-high temperature). The JEDEC $t^{\text{RFC}} \text{MAX}$ of 70,000ns is not required as bursting of AUTO REFRESH commands is allowed.
42. t^{DELAY} is calculated from $t^{\text{IS}} + t^{\text{CK}} + t^{\text{IH}}$ so that CKE registration LOW is guaranteed prior to CK, CK# being removed in a system RESET condition (see Reset).
43. t^{ISXR} is equal to t^{IS} and is used for CKE setup time during self refresh exit, as shown in Figure 1.
44. $t^{\text{CKE}}(\text{MIN})$ of three clocks means CKE must be registered on three consecutive positive clock edges. CKE must remain at the valid input level the entire time it takes to achieve the three clocks of registration. Thus, after any CKE transition, CKE may not transition from its valid level during the time period of $t^{\text{IS}} + 2 \times t^{\text{CK}} + t^{\text{IH}}$.
45. The half-clock of t^{AOFD} 's 2.5 t^{CK} assumes a 50/50 clock duty cycle. This half-clock value must be derated by the amount of half-clock duty cycle error. For example, if the clock duty cycle was 47/53, t^{AOFD} would actually be 2.5 - 0.03, or 2.47, for $t^{\text{AOF}}(\text{MIN})$ and 2.5 + 0.03, or 2.53, for $t^{\text{AOF}}(\text{MAX})$.
46. ODT turn-on time $t^{\text{AON}}(\text{MIN})$ is when the device leaves High-Z and ODT resistance begins to turn on. ODT turn-on time $t^{\text{AON}}(\text{MAX})$ is when the ODT resistance is fully on. Both are measured from t^{AOND} .
47. ODT turn-off time $t^{\text{AOF}}(\text{MIN})$ is when the device starts to turn off ODT resistance. ODT turn off time $t^{\text{AOF}}(\text{MAX})$ is when the bus is in High-Z. Both are measured from t^{AOFD} .
48. Half-clock output parameters must be derated by the actual $t^{\text{ERR}}_{5\text{per}}$ and $t^{\text{JIT}}_{\text{dty}}$ when input clock jitter is present; this will result in each parameter becoming larger. The parameter $t^{\text{AOF}}(\text{MIN})$ is required to be derated by subtracting both $t^{\text{ERR}}_{5\text{per}}(\text{MAX})$ and $t^{\text{JIT}}_{\text{dty}}(\text{MAX})$. The parameter $t^{\text{AOF}}(\text{MAX})$ is required to be derated by subtracting both $t^{\text{ERR}}_{5\text{per}}(\text{MIN})$ and $t^{\text{JIT}}_{\text{dty}}(\text{MIN})$.
49. The -187E maximum limit is $2 \times t^{\text{CK}} + t^{\text{AC}}(\text{MAX}) + 1000$ but it will likely be $3 \times t^{\text{CK}} + t^{\text{AC}}(\text{MAX}) + 1000$ in the future.
50. Should use 8 t^{CK} for backward compatibility.
51. DRAM devices should be evenly addressed when being accessed. Disproportionate accesses to a particular row address may result in reduction of the product lifetime.



1Gb: x8, x16 Automotive DDR2 SDRAM Addendum Electrical Specifications – I_{DD} Parameters

52. Self-refresh is not available when $T_c > 105C$.



Revision History

Rev. A – 09/2015



- Initial release

8000 S. Federal Way, P.O. Box 6, Boise, ID 83707-0006, Tel: 208-368-4000
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