



# THE DATASHEET OF AUR9718AGD



**1.5MHz, 1.5A, Step-down DC-DC Converter****AUR9718****General Description**

The AUR9718 is a high efficiency step-down DC-DC voltage converter. The chip operation is optimized by peak-current mode architecture with built-in synchronous power MOSFET switchers.

The oscillator and timing capacitors are all built-in providing an internal switching frequency of 1.5MHz that allows the use of small surface mount inductors and capacitors for portable product implementations. Additional features including Soft Start (SS), Under Voltage Lock Out (UVLO), Thermal Shutdown Detection (TSD) and short circuit protection are integrated to provide reliable product applications.

The device is available in adjustable output voltage versions ranging from 0.8V to  $0.9 \times V_{IN}$  when input voltage range is from 2.7V to 5.5V, and is able to deliver up to 1.5A.

The AUR9718 is available in DFN-3×3-6 package.

**Features**

- High Efficiency Buck Power Converter
- Low  $R_{DS(ON)}$  Internal Switches : 150m $\Omega$
- Output Current: 1.5A
- Adjustable Output Voltage from 0.8V to  $0.9 \times V_{IN}$
- Wide Operating Voltage Range: 2.7V to 5.5V
- Built-in Power Switchers for Synchronous Rectification with High Efficiency
- Feedback Voltage: 800mV
- 1.5MHz Switching Frequency
- Thermal Shutdown Protection
- Low Drop-out Operation at 90% Duty Cycle
- No Schottky Diode Required

**Applications**

- LCD TV
- Set Top Box
- Post DC-DC Voltage Regulation
- PDA and Notebook Computer



Figure 1. Package Type of AUR9718

## Pin Configuration

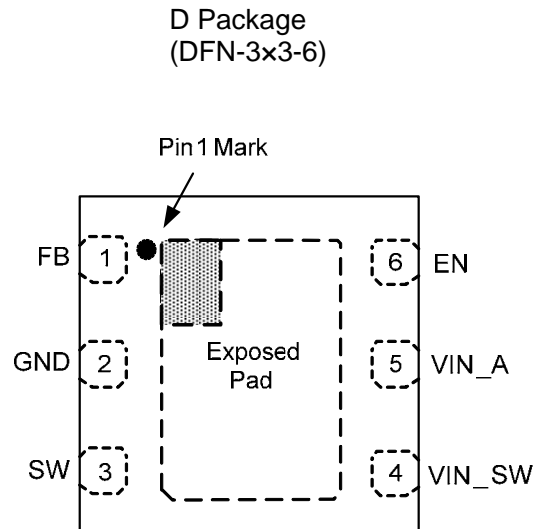


Figure 2. Pin Configuration of AUR9718 (Top View)

## Pin Description

Pin Number	Pin Name	Function
1	FB	Output voltage feedback pin
2	GND	Ground pin
3	SW	Switch output pin
4	VIN_SW	Power supply input for the MOSFET switch
5	VIN_A	Supply input for the analog circuit
6	EN	Enable pin, active high

**1.5MHz, 1.5A, Step-down DC-DC Converter**

**AUR9718**

**Functional Block Diagram**

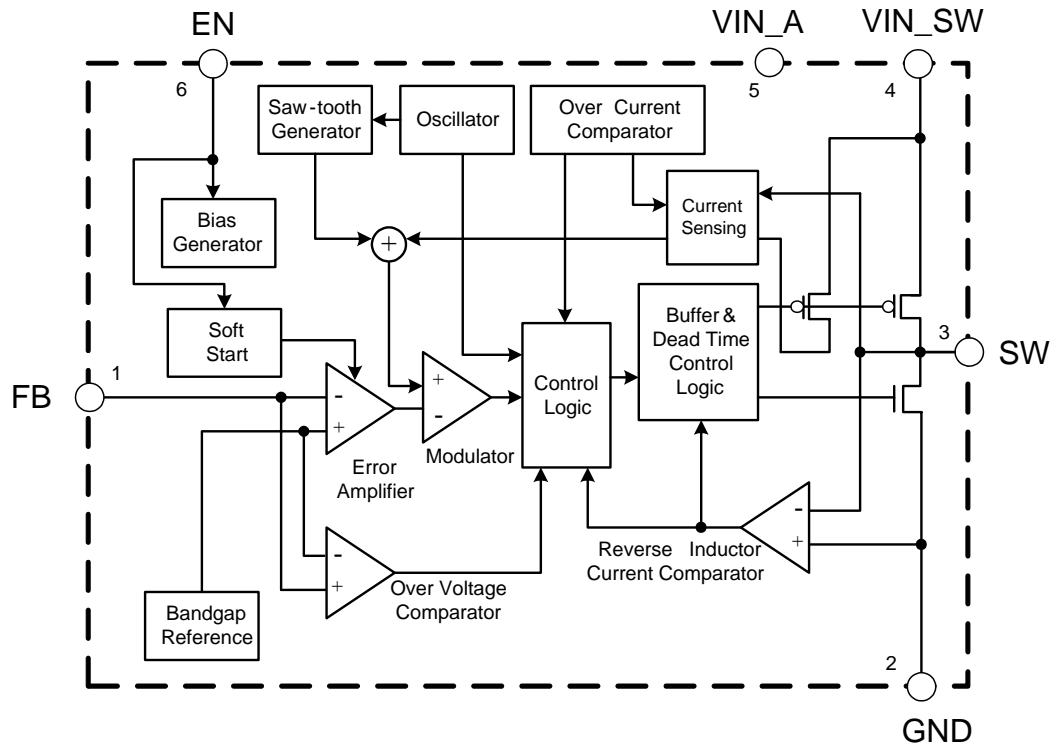
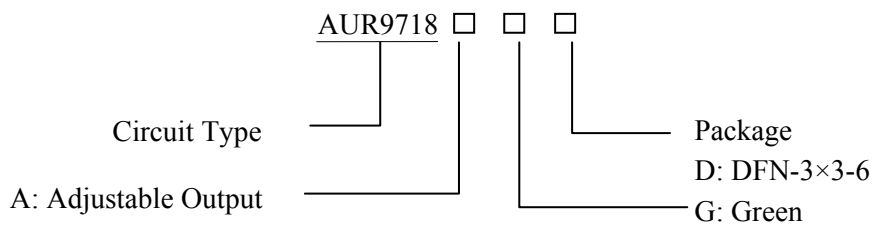


Figure 3. Functional Block Diagram of AUR9718

**Ordering Information**



Package	Temperature Range	Part Number	Marking ID	Packing Type
DFN-3x3-6	-40 to 80°C	AUR9718AGD	9718A	Tape & Reel

BCD Semiconductor's Pb-free products, as designated with "G" in the part number, are RoHS compliant and green.

**1.5MHz, 1.5A, Step-down DC-DC Converter****AUR9718****Absolute Maximum Ratings (Note 1)**

Parameter	Symbol	Value	Unit
Supply Input Voltage ( Pin VIN_SW)	V <sub>IN_SW</sub>	0 to 6.0	V
Supply Input Voltage ( Pin VIN_A)	V <sub>IN_A</sub>	0 to 6.0	V
VIN_SW to VIN_A Voltage		-0.3 to 0.3	V
SW Pin Switch Voltage	V <sub>SW</sub>	-0.3 to V <sub>IN_SW</sub> +0.3	V
Enable Voltage	V <sub>EN</sub>	-0.3 to V <sub>IN_A</sub> +0.3	V
SW Pin Switch Current	I <sub>SW</sub>	2.5	A
Power Dissipation (On PCB, T <sub>A</sub> =25°C)	P <sub>D</sub>	2.49	W
Thermal Resistance (Junction to Ambient, Simulation)	θ <sub>JA</sub>	40.11	°C/W
Operating Junction Temperature	T <sub>J</sub>	150	°C
Operating Temperature	T <sub>OP</sub>	-40 to 85	°C
Storage Temperature	T <sub>STG</sub>	-55 to 150	°C
ESD (Human Body Model)	V <sub>HBM</sub>	2000	V
ESD (Machine Model)	V <sub>MM</sub>	200	V

Note 1: Stresses greater than those listed under “Absolute Maximum Ratings” may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under “Recommended Operating Conditions” is not implied. Exposure to “Absolute Maximum Ratings” for extended periods may affect device reliability.

**Recommended Operating Conditions**

Parameter	Symbol	Min	Max	Unit
Supply Input Voltage	V <sub>IN</sub>	2.7	5.5	V
Junction Temperature Range	T <sub>J</sub>	-40	125	°C
Ambient Temperature Range	T <sub>A</sub>	-40	80	°C

**1.5MHz, 1.5A, Step-down DC-DC Converter****AUR9718****Electrical Characteristics**

$V_{IN\_SW}=V_{IN\_A}=V_{EN}=5V$ ,  $V_{OUT}=1.2V$ ,  $V_{FB}=0.8V$ ,  $L=3.3\mu H$ ,  $C_{IN}=4.7\mu F$ ,  $C_{OUT}=22\mu F$ ,  $T_A=25^\circ C$ , unless otherwise specified.

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Input Voltage Range	$V_{IN}$	$V_{IN}=V_{IN\_SW}=V_{IN\_A}$	2.7		5.5	V
Shutdown Current	$I_{OFF}$	$V_{EN}=0V$		4		$\mu A$
Active Current	$I_{ON}$	$V_{FB}=0.95V$		460		$\mu A$
Regulated Feedback Voltage	$V_{FB}$	For Adjustable Output Voltage	0.784	0.8	0.816	V
Regulated Output Voltage Accuracy	$\Delta V_{OUT}/V_{OUT}$	$V_{IN}=2.7V$ to $5.5V$ , $I_{OUT}=10mA$ to $2A$	-3		3	%
Peak Inductor Current	$I_{PK}$		1.7	2.5		A
Oscillator Frequency	$f_{OSC}$		1.2	1.5	1.8	MHz
PMOSFET $R_{ON}$	$R_{DS(ON)P}$	$I_{SW}=0.75A$		150		$m\Omega$
NMOSFET $R_{ON}$	$R_{DS(ON)N}$	$I_{SW}=0.75A$		150		$m\Omega$
EN High-level Input Voltage	$V_{EN\_H}$		1.5			V
EN Low-level Input Voltage	$V_{EN\_L}$				0.4	V
EN Input Current	$I_{EN}$			2		$\mu A$
Soft-start time	$t_{SS}$			450		$\mu S$
Maximum Duty Cycle	$D_{MAX}$		90			%
Under Voltage Lock Out	$V_{UVLO}$	Rising		2.4		V
		Falling		2.3		
Hysteresis		Hysteresis		0.1		V
Thermal Shutdown	$T_{SD}$	Hysteresis= $30^\circ C$		150		$^\circ C$

Typical Performance Characteristics

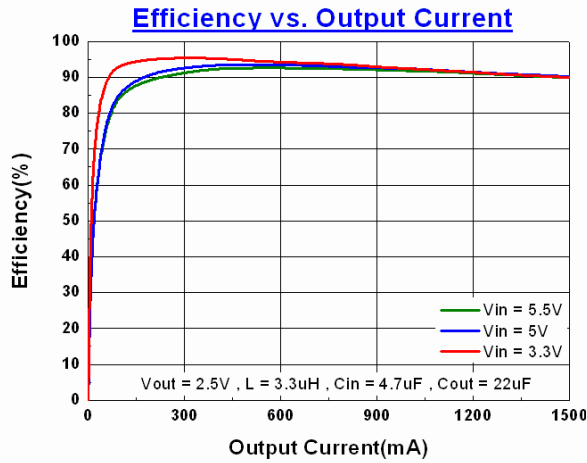


Figure 4. Efficiency vs. Output Current

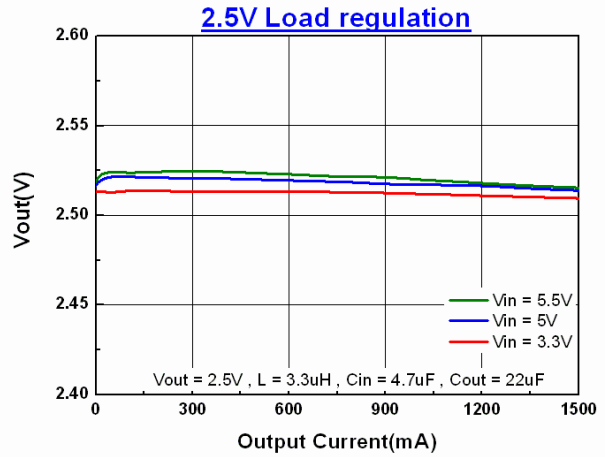


Figure 5. 2.5V Load Regulation

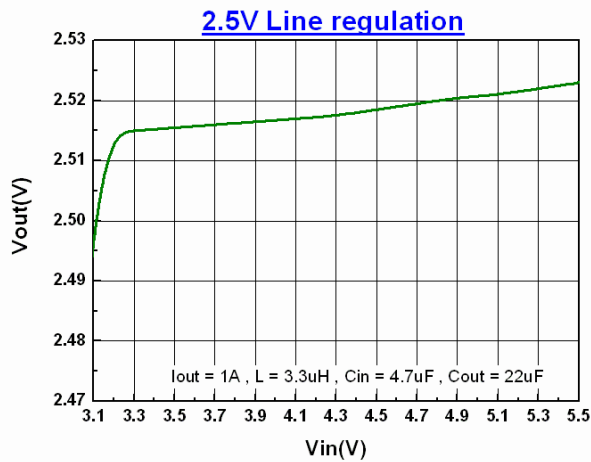


Figure 6. 2.5V Line Regulation

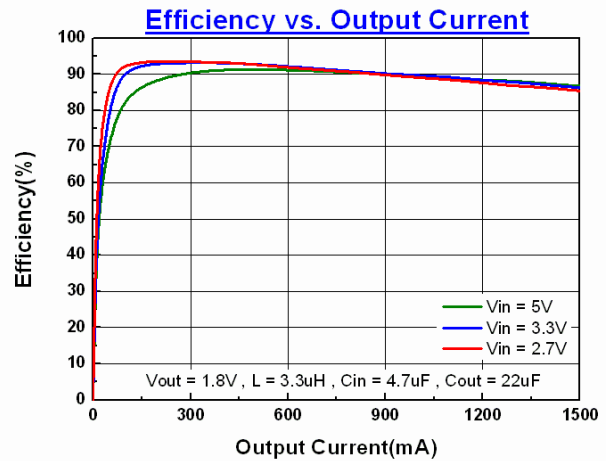


Figure 7. Efficiency vs. Output Current

Typical Performance Characteristics (Continued)

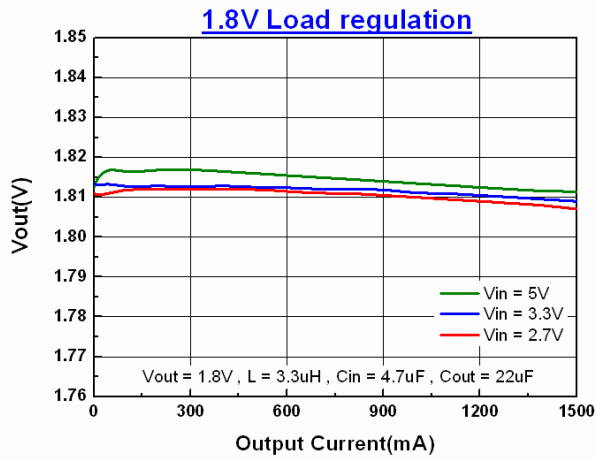


Figure 8. 1.8V Load Regulation

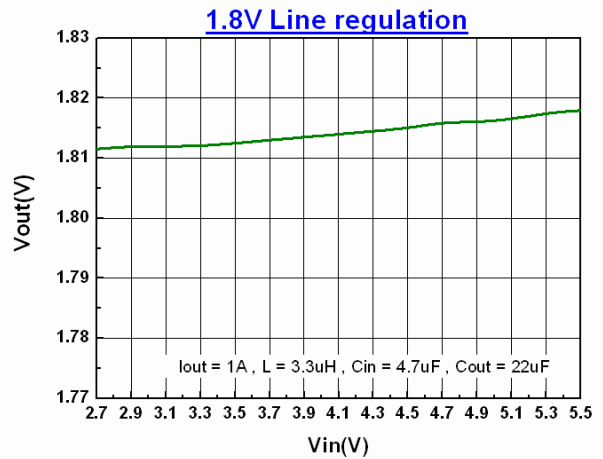


Figure 9. 1.8V Line Regulation

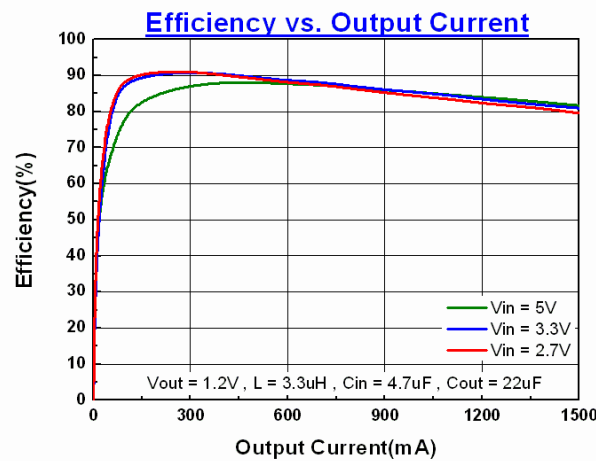


Figure 10. Efficiency vs. Output Current

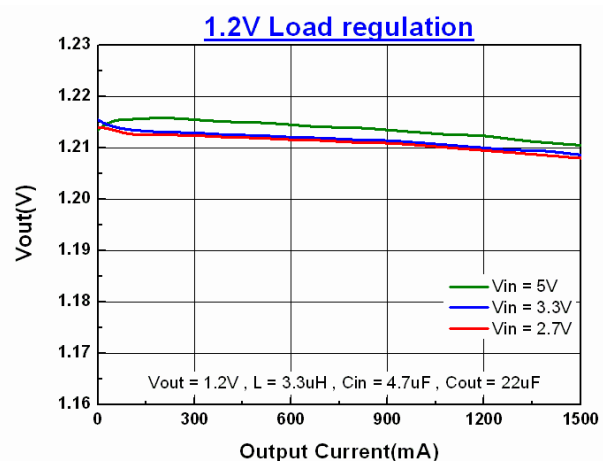


Figure 11. 1.2V Load Regulation

Typical Performance Characteristics (Continued)

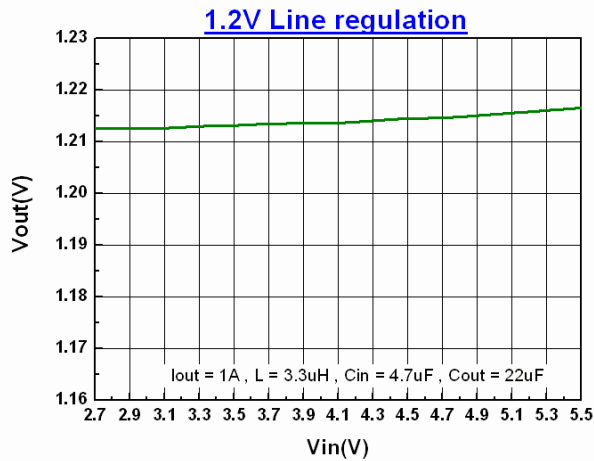


Figure 12. 1.2V Line Regulation

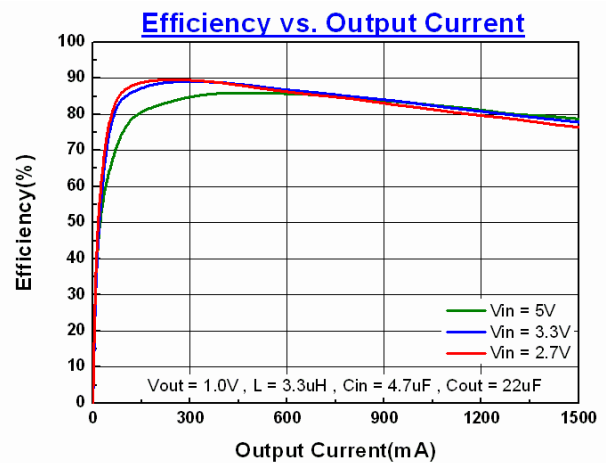


Figure 13. Efficiency vs. Output Current

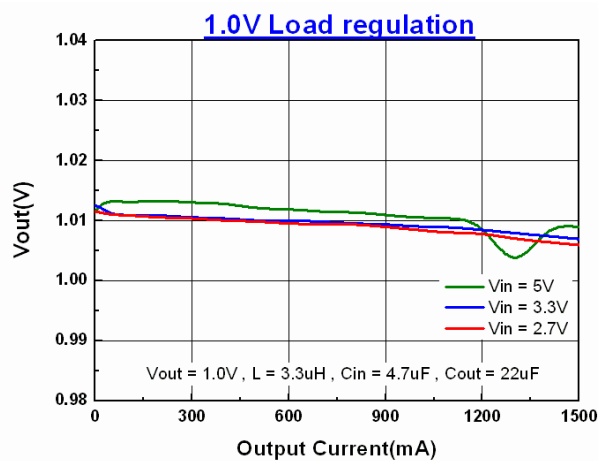


Figure 14. 1.0V Load Regulation

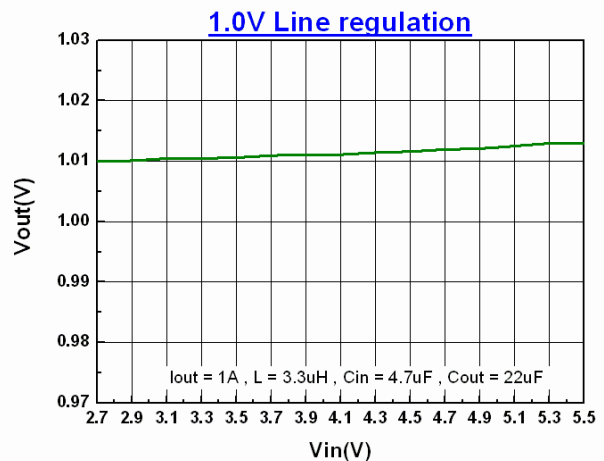


Figure 15. 1.0V Line Regulation

Typical Performance Characteristics (Continued)

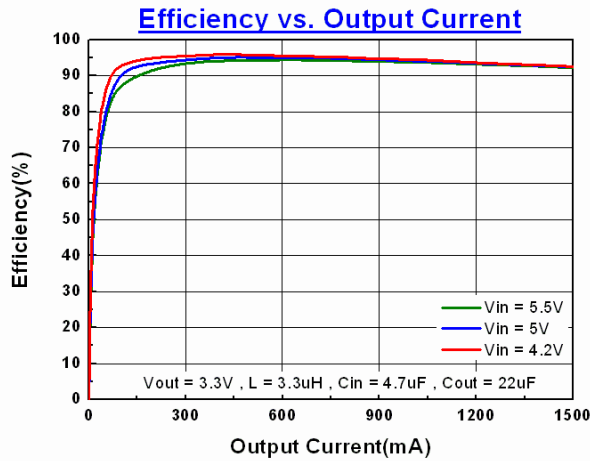


Figure 16. Efficiency vs. Output Current

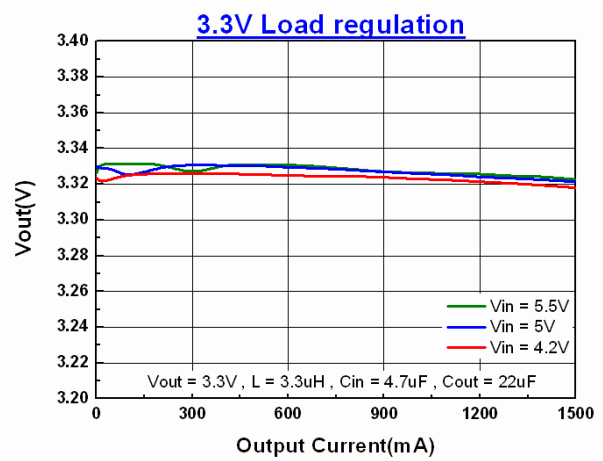


Figure 17. 3.3V Load Regulation

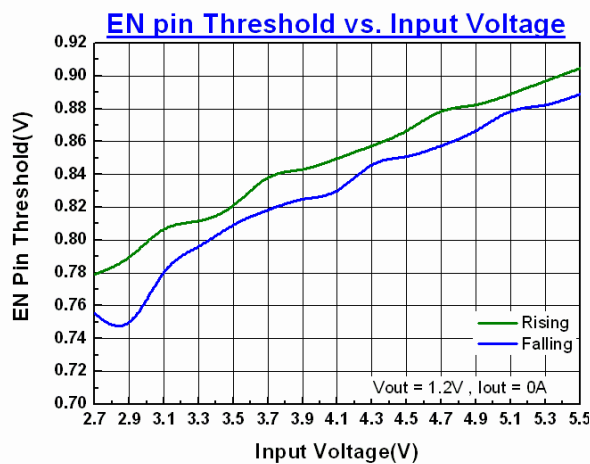


Figure 18. EN Pin Threshold vs. Input Voltage

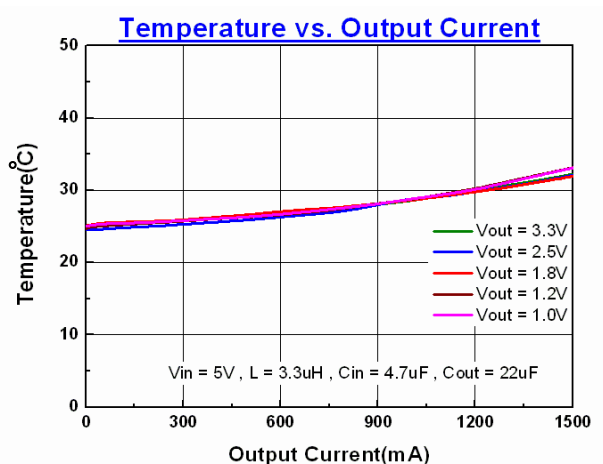


Figure 19. Temperature vs. Output Current

Typical Performance Characteristics (Continued)

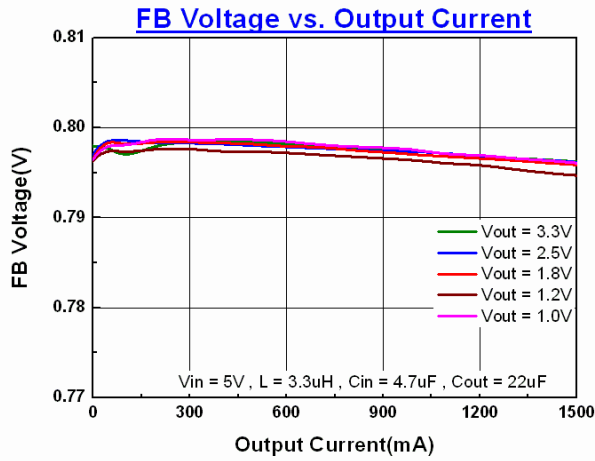
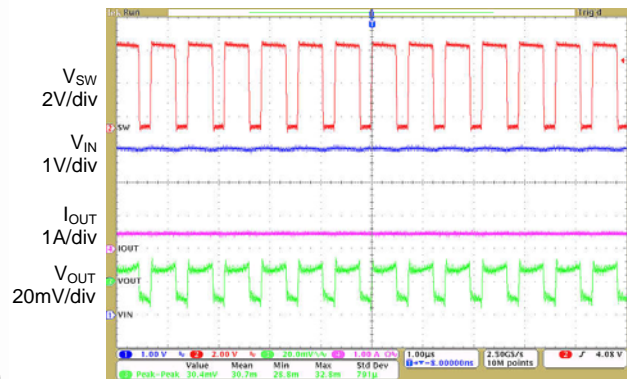
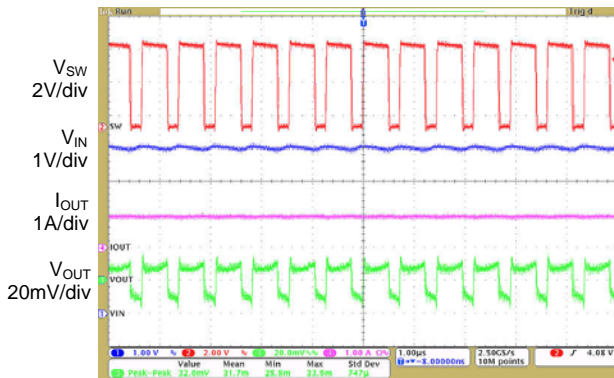


Figure 20. FB Voltage vs. Output Current



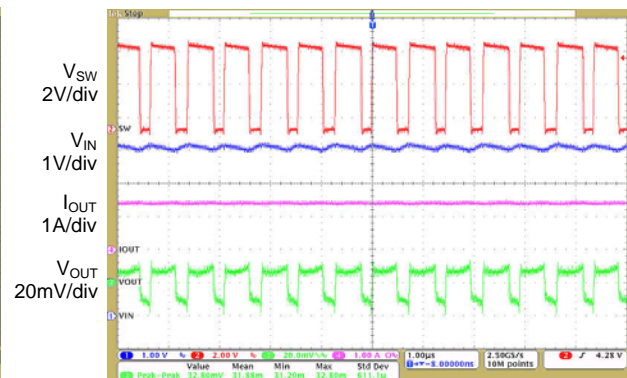
Time 1µs/div

Figure 21. V<sub>OUT</sub> Ripple  
(V<sub>IN</sub>=5V, V<sub>OUT</sub>=3.3V, I<sub>OUT</sub>=500mA)



Time 1µs/div

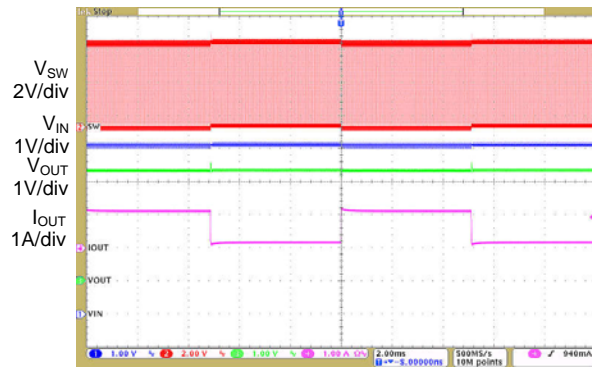
Figure 22. V<sub>OUT</sub> Ripple  
(V<sub>IN</sub>=5V, V<sub>OUT</sub>=3.3V, I<sub>OUT</sub>=1000mA)



Time 1µs/div

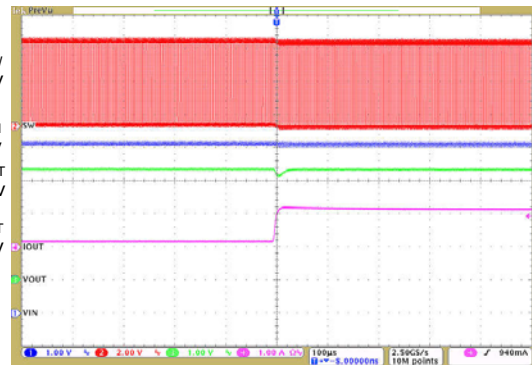
Figure 23. V<sub>OUT</sub> Ripple  
(V<sub>IN</sub>=5V, V<sub>OUT</sub>=3.3V, I<sub>OUT</sub>=1500mA)

Typical Performance Characteristics (Continued)



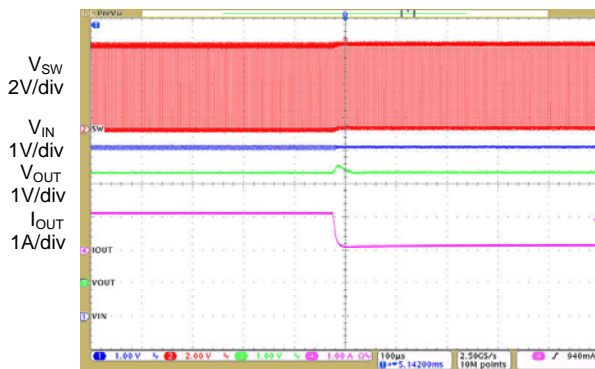
Time 2ms/div

Figure 24. Dynamic Mode  
( $I_{LOAD}=200mA$  to  $1200mA$ ,  $V_{IN}=5V$ ,  $V_{OUT}=3.3V$ )



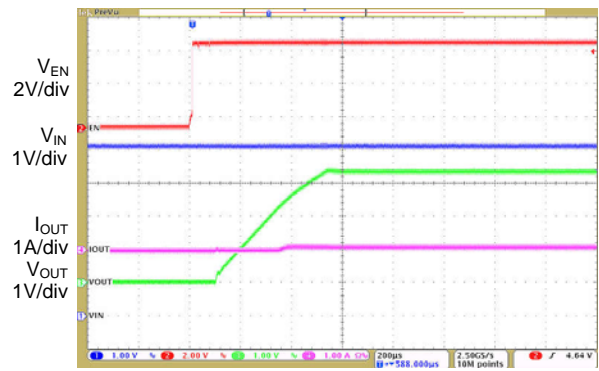
Time 100µs/div

Figure 25. Dynamic Mode (Rising)



Time 100µs/div

Figure 26. Dynamic Mode (Falling)



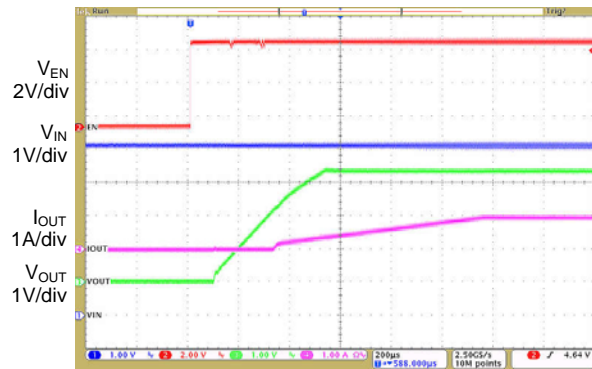
Time 200µs/div

Figure 27. EN Pin L to H  
( $V_{IN}=5V$ ,  $V_{OUT}=3.3V$ ,  $I_{OUT}=100mA$ )

**1.5MHz, 1.5A, Step-down DC-DC Converter**

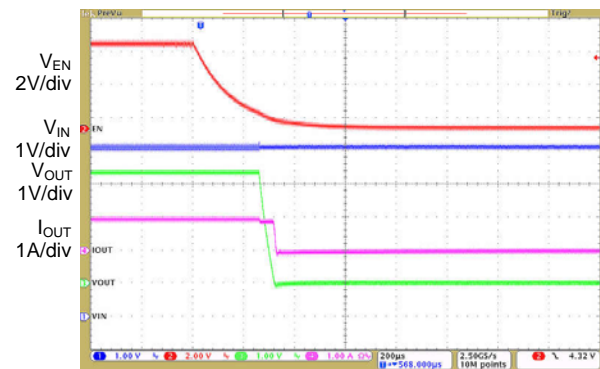
**AUR9718**

**Typical Performance Characteristics (Continued)**



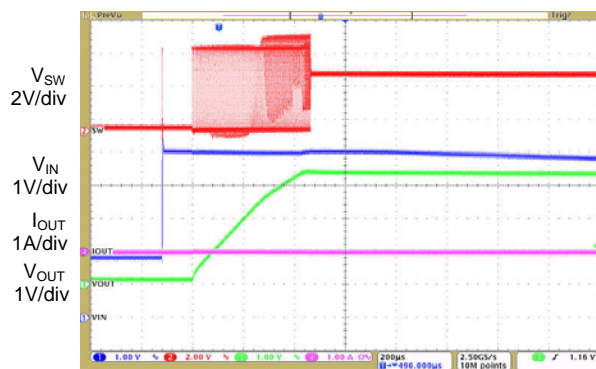
Time 200µs/div

Figure 28. EN Pin L to H  
( $V_{IN}=5V$ ,  $V_{OUT}=3.3V$ ,  $I_{OUT}=1A$ )



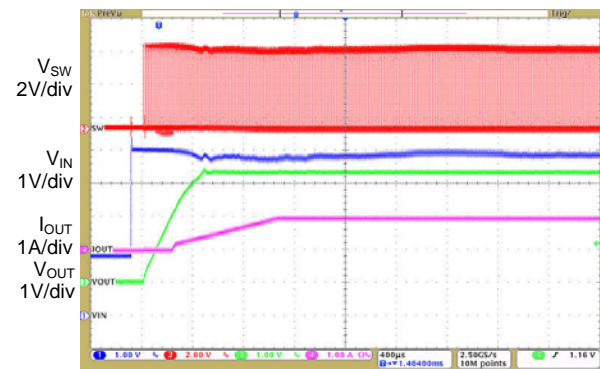
Time 200µs/div

Figure 29. EN Pin H to L  
( $V_{IN}=5V$ ,  $V_{OUT}=3.3V$ ,  $I_{OUT}=1A$ )



Time 200µs/div

Figure 30. Soft Start Function  
( $V_{IN}=5V$ ,  $V_{OUT}=3.3V$ ,  $I_{OUT}=0A$ )



Time 400µs/div

Figure 31. Soft Start Function  
( $V_{IN}=5V$ ,  $V_{OUT}=3.3V$ ,  $I_{OUT}=1A$ )

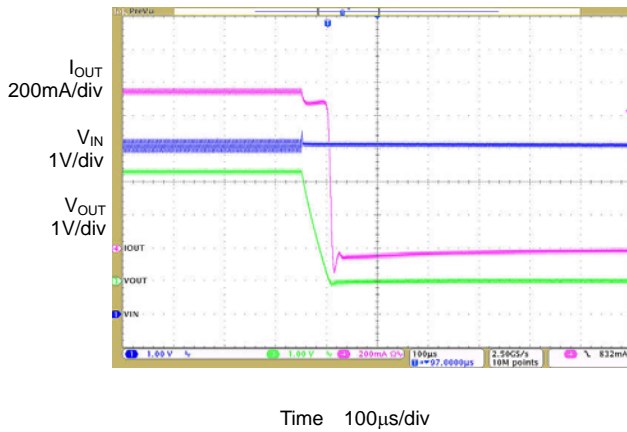
**1.5MHz, 1.5A, Step-down DC-DC Converter****AUR9718****Typical Performance Characteristics (Continued)**

Figure 32. OTP Function

**1.5MHz, 1.5A, Step-down DC-DC Converter**
**AUR9718**

## Application Information

The basic AUR9718 application circuit is shown in Figure 35.

### 1. Inductor Selection

For most applications, the value of inductor is chosen based on the required ripple current with the range of 1.0μH to 6.8μH.

$$\Delta I_L = \frac{1}{f \times L} V_{OUT} \left(1 - \frac{V_{OUT}}{V_{IN}}\right)$$

The largest ripple current occurs at the highest input voltage. Having a small ripple current reduces the ESR loss in the output capacitor and improves the efficiency. The highest efficiency is realized at low operating frequency with small ripple current. However, larger value inductors will be required. A reasonable starting point for ripple current setting is  $\Delta I_L = 40\% I_{MAX}$ . For a maximum ripple current stays below a specified value, the inductor should be chosen according to the following equation:

$$L = \left[ \frac{V_{OUT}}{f \times \Delta I_L (MAX)} \right] \left[ 1 - \frac{V_{OUT}}{V_{IN} (MAX)} \right]$$

The DC current rating of the inductor should be at least equal to the maximum output current plus half the highest ripple current to prevent inductor core saturation. For better efficiency, a lower DC-resistance inductor should be selected.

### 2. Capacitor Selection

The input capacitance,  $C_{IN}$ , is needed to filter the trapezoidal current at the source of the top MOSFET. To prevent large ripple voltage, a low ESR input capacitor sized for the maximum RMS current must be used. The maximum RMS capacitor current is given by:

$$I_{RMS} = I_{OMAX} \times \frac{[V_{OUT} (V_{IN} - V_{OUT})]^{\frac{1}{2}}}{V_{IN}}$$

It indicates a maximum value at  $V_{IN} = 2V_{OUT}$ , where  $I_{RMS} = I_{OUT}/2$ . This simple worst-case condition is commonly used for design because even significant

deviations do not much relieve. The selection of  $C_{OUT}$  is determined by the Effective Series Resistance (ESR) that is required to minimize output voltage ripple and load step transients, as well as the amount of bulk capacitor that is necessary to ensure that the control loop is stable. The output ripple,  $\Delta V_{OUT}$ , is determined by:

$$\Delta V_{OUT} \leq \Delta I_L \left[ ESR + \frac{1}{8 \times f \times C_{OUT}} \right]$$

The output ripple is the highest at the maximum input voltage since  $\Delta I_L$  increases with input voltage.

### 3. Load Transient

A switching regulator typically takes several cycles to respond to the load current step. When a load step occurs,  $V_{OUT}$  immediately shifts by an amount equal to  $\Delta I_{LOAD} \times ESR$ , where ESR is the effective series resistance of output capacitor.  $\Delta I_{LOAD}$  also begins to charge or discharge  $C_{OUT}$  generating a feedback error signal used by the regulator to return  $V_{OUT}$  to its steady-state value. During the recovery time,  $V_{OUT}$  can be monitored for overshoot or ringing that would indicate a stability problem.

### 4. Output Voltage Setting

The output voltage of AUR9718 can be adjusted by a resistive divider according to the following formula:

$$V_{OUT} = V_{FB} \times \left(1 + \frac{R_1}{R_2}\right) = 0.8V \times \left(1 + \frac{R_1}{R_2}\right)$$

The resistive divider senses the fraction of the output voltage as shown in Figure 33.

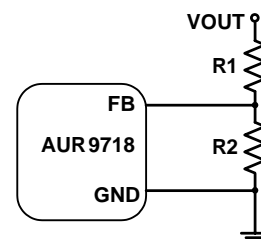


Figure 33. Setting the Output Voltage

## Application Information (Continued)

### 5. Short Circuit Protection

When AUR9718 output node is shorted to GND, as  $V_{FB}$  drops under 0.4V, the chip will enter soft-start to protect itself; when short circuit is removed, and  $V_{FB}$  rises over 0.4V, the chip will enter normal operation again. If AUR9718 reaches OCP threshold while short circuit, it will enter soft-start cycle and last until the current drops under OCP threshold.

### 6. Efficiency Considerations

The efficiency of switching regulator is equal to the output power divided by the input power times 100%. It is usually useful to analyze the individual losses to determine what is limiting efficiency and which change could produce the largest improvement. Efficiency can be expressed as:

$$\text{Efficiency} = 100\% - L1 - L2 - \dots$$

Where L1, L2, etc. are the individual losses as a percentage of input power.

Although all dissipative elements in the regulator produce losses, two major sources usually account for most of the power losses:  $V_{IN}$  quiescent current and  $I^2R$  losses. The  $V_{IN}$  quiescent current loss dominates the efficiency loss at very light load currents and the  $I^2R$  loss dominates the efficiency loss at medium to heavy load currents.

**6.1** The  $V_{IN}$  quiescent current loss comprises two parts: the DC bias current as given in the electrical characteristics and the internal MOSFET switch gate charge currents. The gate charge current results from switching the gate capacitance of the internal power MOSFET switches. Each cycle the gate is switched from high to low, then to high again, and the packet of charge,  $dQ$  moves from  $V_{IN}$  to ground. The resulting  $dQ/dt$  is the current out of  $V_{IN}$  that is typically larger than the internal DC bias current. In continuous mode,

$$I_{GATE} = f \times (Q_P + Q_N)$$

Where  $Q_P$  and  $Q_N$  are the gate charge of power PMOSFET and NMOSFET switches. Both the DC bias current and gate charge losses are proportional to

the  $V_{IN}$  and this effect will be more serious at higher input voltages.

**6.2**  $I^2R$  losses are calculated from internal switch resistance,  $R_{SW}$  and external inductor resistance  $R_L$ . In continuous mode, the average output current flowing through the inductor is chopped between power PMOSFET switch and NMOSFET switch. Then, the series resistance looking into the SW pin is a function of both PMOSFET  $R_{DS(ON)P}$  and NMOSFET  $R_{DS(ON)N}$  resistance and the duty cycle (D):

$$R_{SW} = R_{DS(ON)P} \times D + R_{DS(ON)N} \times (1 - D)$$

Therefore, to obtain the  $I^2R$  losses, simply add  $R_{SW}$  to  $R_L$  and multiply the result by the square of the average output current.

Other losses including  $C_{IN}$  and  $C_{OUT}$  ESR dissipative losses and inductor core losses generally account for less than 2% of total additional loss.

### 7. Thermal Characteristics

In most applications, the part does not dissipate much heat due to its high efficiency. However, in some conditions when the part is operating in high ambient temperature with high  $R_{DS(ON)}$  resistance and high duty cycles, such as in LDO mode, the heat dissipated may exceed the maximum junction temperature. To avoid the part from exceeding maximum junction temperature, the user should do some thermal analysis. The maximum power dissipation depends on the layout of PCB, the thermal resistance of IC package, the rate of surrounding airflow and the temperature difference between junction and ambient.

### 8. PC Board Layout Considerations

When laying out the printed circuit board, the following checklist should be used to optimize the performance of AUR9718.

1. The power traces, including the GND trace, the SW trace and the VIN trace should be kept direct, short and wide.
2. Put the input capacitor as close as possible to the VIN\_SW, VIN\_A and GND pins.

**1.5MHz, 1.5A, Step-down DC-DC Converter**

**AUR9718**

**Application Information (Continued)**

3. The FB pin should be connected directly to the feedback resistor divider.

4. Keep the switching node SW away from the sensitive FB pin and the node should be kept small area.

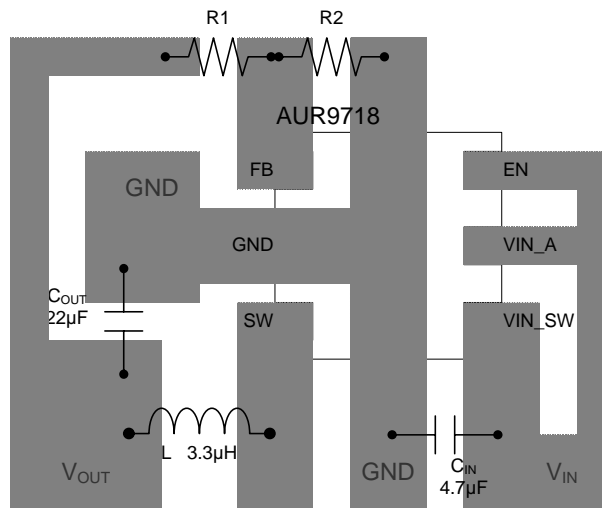
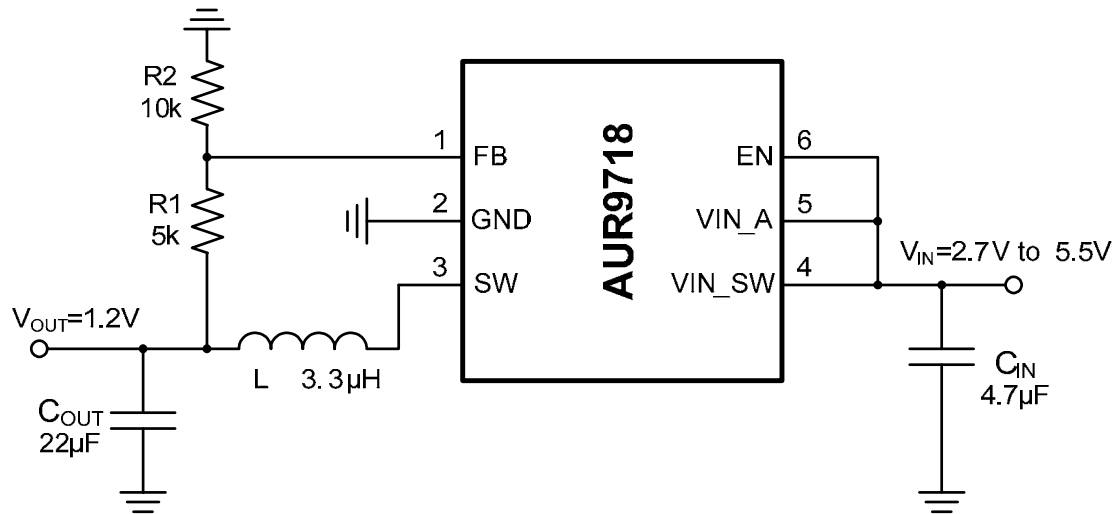


Figure 34. The Layout Guide

**1.5MHz, 1.5A, Step-down DC-DC Converter**
**AUR9718**
**Typical Application**


Note 2:  $V_{OUT} = V_{FB} \times \left(1 + \frac{R_1}{R_2}\right)$

Figure 35. Typical Application Circuit of AUR9718 (Note 2)

**Table 1. Component Guide**

V <sub>OUT</sub> (V)	R1 (kΩ)	R2 (kΩ)	L (µH)
3.3	31.25	10	3.3
2.5	21.5	10	3.3
1.8	12.5	10	3.3
1.2	5	10	3.3
1.0	3	10	3.3





## **BCD Semiconductor Manufacturing Limited**

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