THE DATASHEET OF

MB95F222HPF-G-SNE1

MB95220H Series

F²MC-8FX 8-bit Microcontroller

MB95220H are a series of general-purpose, single-chip microcontrollers. In addition to a compact instruction set, the microcontrollers of these series contain a variety of peripheral resources.

Features

F²MC-8FX CPU core

Instruction set optimized for controllers

- Multiplication and division instructions
- 16-bit arithmetic operations
- Bit test branch instructions
- Bit manipulation instructions, etc.

Clock

- Selectable main clock source
  - External clock (up to 32.5 MHz, maximum machine clock frequency: 16.25 MHz)
  - Main internal CR clock (1/8/10 MHz ±3%, maximum machine clock frequency: 10 MHz)
- Selectable subclock source
  - External clock (32.768 kHz)
  - Sub-internal CR clock (Typ: 100 kHz, Min: 50 kHz, Max: 200 kHz)

Timer

- 8/16-bit composite timer
- Timebase timer
- Watch prescaler

LIN-UART (MB95F222H/F222K/F223H/F223K)

- Full duplex double buffer
- Capable of clock-synchronized serial data transfer and clock-asynchronized serial data transfer

External interrupt

- Interrupt by edge detection (rising edge, falling edge, and both edges can be selected)
- Can be used to wake up the device from different low power consumption (standby) modes

8/10-bit A/D converter

- 8-bit or 10-bit resolution can be selected.

Low power consumption (standby) modes

- Stop mode
- Sleep mode
- Watch mode
- Timebase timer mode

I/O port (Max: 13) (MB95F222K/F223K)

- General-purpose I/O ports (Max):
  CMOS I/O: 11, N-ch open drain: 2

I/O port (Max: 12) (MB95F222H/F223H)

- General-purpose I/O ports (Max):
  CMOS I/O: 11, N-ch open drain: 1

On-chip debug

- 1-wire serial control
- Serial writing supported (asynchronous mode)

Hardware/software watchdog timer

- Built-in hardware watchdog timer

Low-voltage detection reset circuit

- Built-in low-voltage detector

Clock supervisor counter

- Built-in clock supervisor counter function

Programmable port input voltage level

- CMOS input level / hysteresis input level

Flash memory security function

- Protects the contents of flash memory

Contents

1. Product Line-up

Part number / Parameter	MB95F223H	MB95F222H	MB95F223K	MB95F222K
Type	Flash memory product			
Clock supervisor counter	It supervises the main clock oscillation.			
ROM capacity	8 KB	4 KB	8 KB	4 KB
RAM capacity	496 B	240 B	496 B	240 B
Low-voltage detection reset	No		Yes	
Reset input	Dedicated		Selected by software	
CPU functions	Number of basic instructions : 136 Instruction bit length : 8 bits Instruction length : 1 to 3 bytes Data bit length : 1, 8, and 16 bits Minimum instruction execution time : 61.5 ns (with machine clock = 16.25 MHz) Interrupt processing time : 0.6 µs (with machine clock = 16.25 MHz)			
General-purpose I/O	I/O ports (Max): 12 CMOS: 11, N-ch: 1		I/O ports (Max): 13 CMOS: 11, N-ch: 2	
Timebase timer	Interrupt cycle : 0.256 ms - 8.3 s (when external clock = 4 MHz)			
Hardware/software watchdog timer	Reset generation cycle Main oscillation clock at 10 MHz : 105 ms (Min) The sub-CR clock can be used as the source clock of the hardware watchdog timer.			
Wild register	It can be used to replace three bytes of data.			
LIN-UART	A wide range of communication speed can be selected by a dedicated reload timer. It has a full duplex double buffer. Clock-synchronized serial data transfer and clock-asynchronized serial data transfer is enabled. The LIN function can be used as a LIN master or a LIN slave.			
8/10-bit A/D converter	5 ch.			
	8-bit or 10-bit resolution can be selected.			
8/16-bit composite timer	1 ch.			
	The timer can be configured as an "8-bit timer x 2 channels" or a "16-bit timer x 1 channel". It has built-in timer function, PWC function, PWM function and input capture function. Count clock: it can be selected from internal clocks (seven types) and external clocks. It can output square wave.			
External interrupt	6 ch.			
	Interrupt by edge detection (The rising edge, falling edge, or both edges can be selected.) It can be used to wake up the device from standby modes.			
On-chip debug	1-wire serial control It supports serial writing. (asynchronous mode)			

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Part number / Parameter	MB95F223H	MB95F222H	MB95F223K	MB95F222K
Watch prescaler	Eight different time intervals can be selected.			
Flash memory	It supports automatic programming, Embedded Algorithm, write/erase/erase-suspend/erase-resume commands. It has a flag indicating the completion of the operation of Embedded Algorithm. Number of write/erase cycles: 100000 Data retention time: 20 years For write/erase, external Vpp(+10 V) input is required. Flash security feature for protecting the contents of the flash			
Standby mode	Sleep mode, stop mode, watch mode, timebase timer mode			
Package	DIP-16P-M06 FPT-16P-M06			

2. Packages and Corresponding Products

Part number / Package	MB95F223H	MB95F222H	MB95F223K	MB95F222K
DIP-16P-M06	O	O	O	O
FPT-16P-M06	O	O	O	O

O: Available

3. Differences Among Products and Notes on Product Selection

Current consumption

When using the on-chip debug function, take account of the current consumption of flash erase/program.

For details of current consumption, see “13. Electrical Characteristics”.

Package

For details of information on each package, see “2. Packages and Corresponding Products” and “17. Package Dimensions”.

Operating voltage

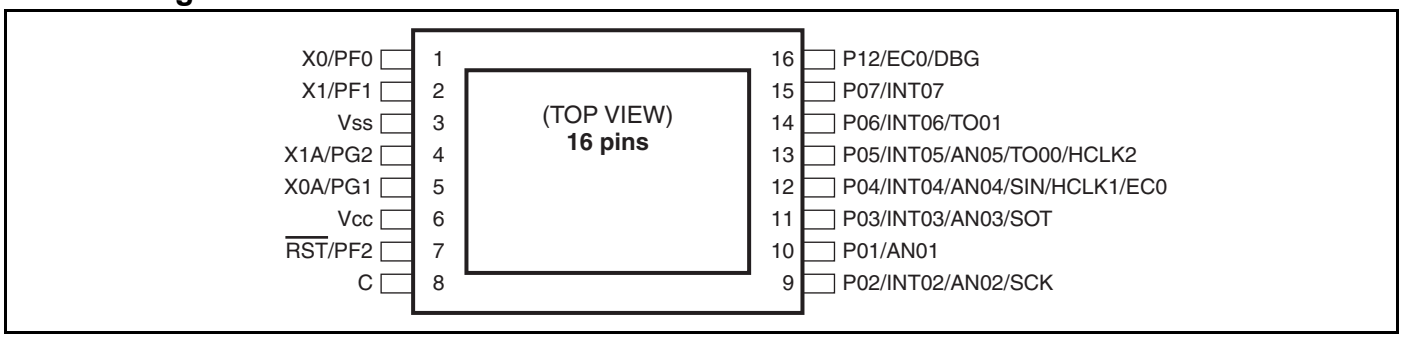
The operating voltage varies, depending on whether the on-chip debug function is used or not.

For details of the operating voltage, see “13. Electrical Characteristics”.

On-chip debug function

The on-chip debug function requires that V_{CC}, V_{SS} and 1 serial-wire be connected to an evaluation tool. In addition, if the flash memory data has to be updated, the $\overline{RST}$/PF2 pin must also be connected to the same evaluation tool.

4. Pin Assignment



5. Pin Description (MB95220H Series)

Pin no.	Pin name	I/O circuit type*	Function
1	PF0	B	General-purpose I/O port
	X0		Main clock input oscillation pin
2	PF1	B	General-purpose I/O port
	X1		Main clock I/O oscillation pin
3	V_{SS}	—	Power supply pin (GND)
4	PG2	C	General-purpose I/O port
	X1A		Subclock I/O oscillation pin
5	PG1	C	General-purpose I/O port
	X0A		Subclock input oscillation pin
6	V_{CC}	—	Power supply pin
7	PF2	A	General-purpose I/O port
	$\overline{RST}$		Reset pin This pin is a dedicated reset pin in MB95F222H/F223H.
8	C	—	Capacitor connection pin
9	P02	E	General-purpose I/O port
	INT02		External interrupt input pin
	AN02		A/D converter analog input pin
	SCK		LIN-UART clock I/O pin
10	P01	E	General-purpose I/O port
	AN01		A/D converter analog input pin
11	P03	E	General-purpose I/O port
	INT03		External interrupt input pin
	AN03		A/D converter analog input pin
	SOT		LIN-UART data output pin
12	P04	F	General-purpose I/O port
	INT04		External interrupt input pin
	AN04		A/D converter analog input pin
	SIN		LIN-UART data input pin
	HCLK1		External clock input pin
	EC0		8/16-bit composite timer ch. 0 clock input pin

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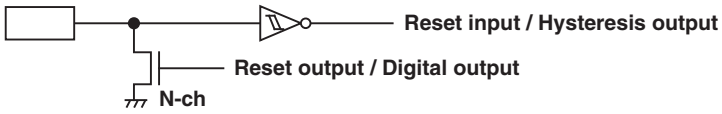
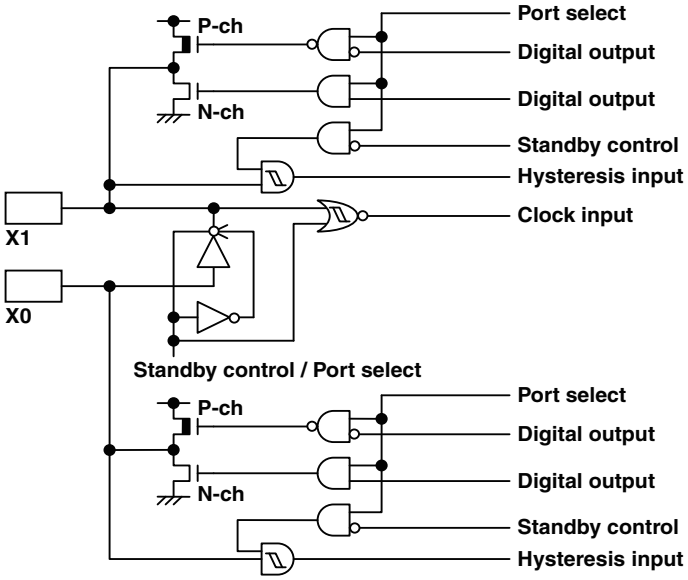
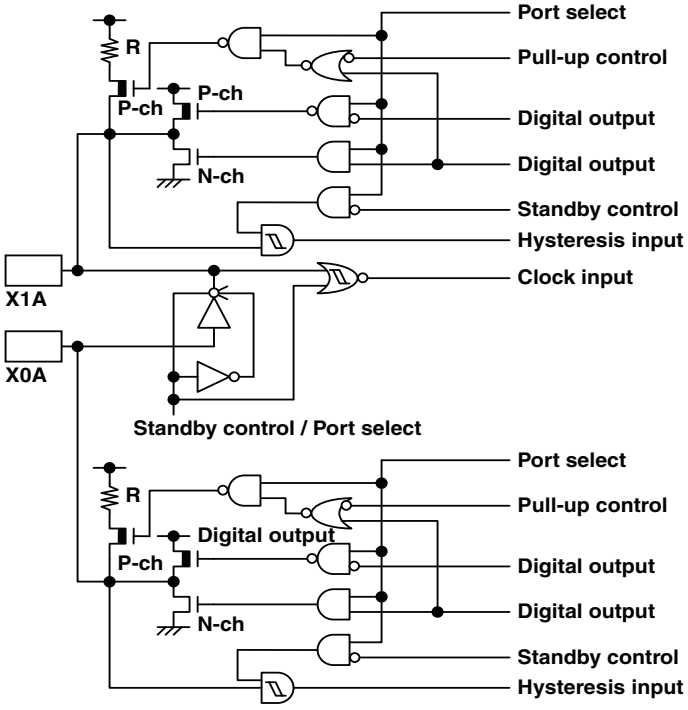
Pin no.	Pin name	I/O circuit type*	Function
13	P05	E	General-purpose I/O port High-current port
	INT05		External interrupt input pin
	AN05		A/D converter analog input pin
	TO00		8/16-bit composite timer ch. 0 clock input pin
	HCLK2		External clock input pin
14	P06	G	General-purpose I/O port High-current port
	INT06		External interrupt input pin
	TO01		8/16-bit composite timer ch. 0 clock input pin
15	P07	G	General-purpose I/O port
	INT07		External interrupt input pin
16	P12	H	General-purpose I/O port
	EC0		8/16-bit composite timer ch. 0 clock input pin
	DBG		DBG input pin

*: For the I/O circuit types, see “6. I/O Circuit Type”.

6. I/O Circuit Type

Type	Circuit	Remarks
A		• N-ch open drain output • Hysteresis input • Reset output
B		• Oscillation circuit • High-speed side Feedback resistance: approx. 1 MΩ • CMOS output • Hysteresis input
C		• Oscillation circuit • Low-speed side Feedback resistance: approx. 10 MΩ • CMOS output • Hysteresis input • Pull-up control available

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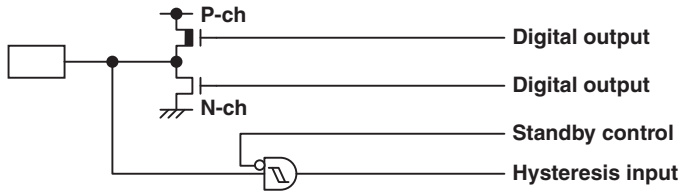
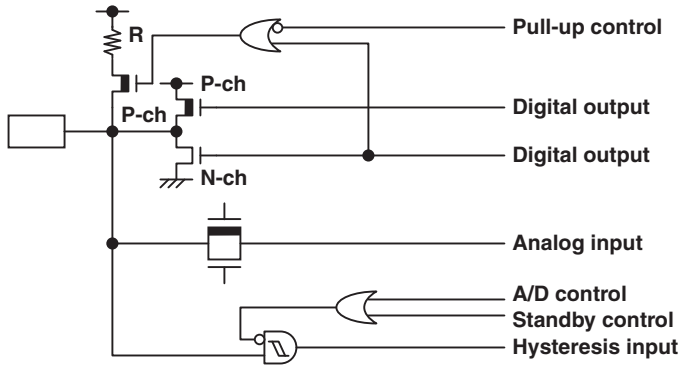
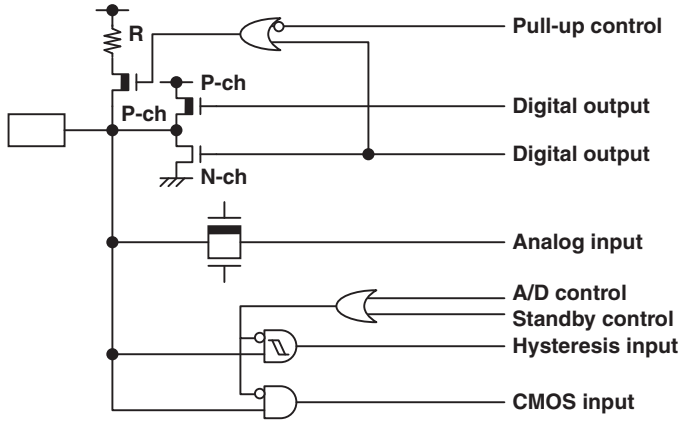
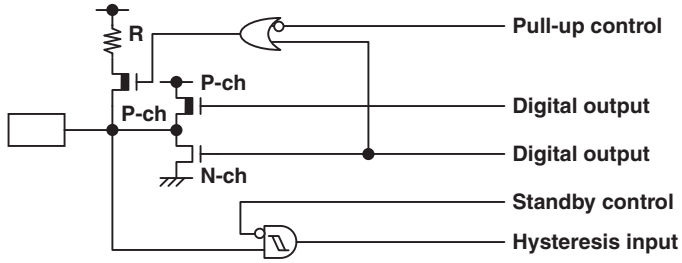
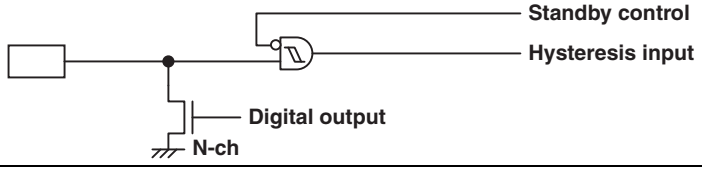
Type	Circuit	Remarks
D		• CMOS output • Hysteresis input
E		• CMOS output • Hysteresis input • Pull-up control available
F		• CMOS output • Hysteresis input • CMOS input • Pull-up control available
G		• Hysteresis input • CMOS output • Pull-up control available
H		• N-ch open drain output • Hysteresis input

7. Notes on Device Handling

Preventing latch-ups

When using the device, ensure that the voltage applied does not exceed the maximum voltage rating.

In a CMOS IC, if a voltage higher than V_{CC} or a voltage lower than V_{SS} is applied to an input/output pin that is neither a medium-withstand voltage pin nor a high-withstand voltage pin, or if a voltage out of the rating range of power supply voltage mentioned in 13.1 Absolute Maximum Ratings of “Electrical Characteristics” is applied to the V_{CC} pin or the V_{SS} pin, a latch-up may occur.

When a latch-up occurs, power supply current increases significantly, which may cause a component to be thermally destroyed.

Stabilizing supply voltage

Supply voltage must be stabilized.

A malfunction may occur when power supply voltage fluctuates rapidly even though the fluctuation is within the guaranteed operating range of the V_{CC} power supply voltage.

As a rule of voltage stabilization, suppress voltage fluctuation so that the fluctuation in V_{CC} ripple (p-p value) at the commercial frequency (50 Hz/60 Hz) does not exceed 10% of the standard V_{CC} value, and the transient fluctuation rate does not exceed 0.1 V/ms at a momentary fluctuation such as switching the power supply.

Notes on using the external clock

When an external clock is used, oscillation stabilization wait time is required for power-on reset, wake-up from subclock mode or stop mode.

8. Pin Connection

Treatment of unused pins

If an unused input pin is left unconnected, a component may be permanently damaged due to malfunctions or latch-ups. Always pull up or pull down an unused input pin through a resistor of at least 2 kΩ. Set an unused input/output pin to the output state and leave it unconnected, or set it to the input state and treat it the same as an unused input pin. If there is an unused output pin, leave it unconnected.

Power supply pins

To reduce unnecessary electro-magnetic emission, prevent malfunctions of strobe signals due to an increase in the ground level, and conform to the total output current standard, always connect the V_{CC} pin and the V_{SS} pin to the power supply and ground outside the device. In addition, connect the current supply source to the V_{CC} pin and the V_{SS} pin with low impedance.

It is also advisable to connect a ceramic capacitor of approximately 0.1 µF as a bypass capacitor between the V_{CC} pin and the V_{SS} pin at a location close to this device.

DBG pin

Connect the DBG pin directly to an external pull-up resistor.

To prevent the device from unintentionally entering the debug mode due to noise, minimize the distance between the DBG pin and the V_{CC} or V_{SS} pin when designing the layout of the printed circuit board.

The DBG pin should not stay at “L” level after power-on until the reset output is released.

$\overline{\text{RST}}$ pin

Connect the $\overline{\text{RST}}$ pin directly to an external pull-up resistor.

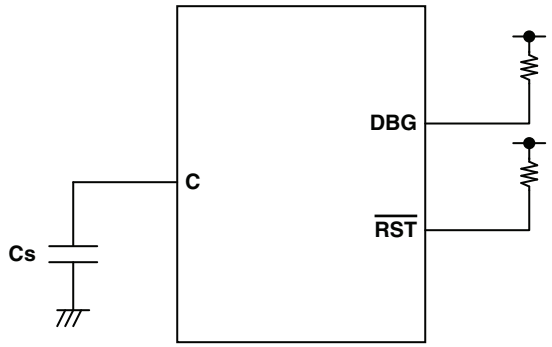
To prevent the device from unintentionally entering the reset mode due to noise, minimize the distance between the $\overline{\text{RST}}$ pin and the V_{CC} or V_{SS} pin when designing the layout of the printed circuit board.

The $\overline{\text{RST}}$/PF2 pin functions as the reset input/output pin after power-on. In addition, the reset output of the $\overline{\text{RST}}$/PF2 pin can be enabled by the RSTOE bit of the SYSC register, and the reset input function and the general purpose I/O function can be selected by the RSTEN bit of the SYSC register.

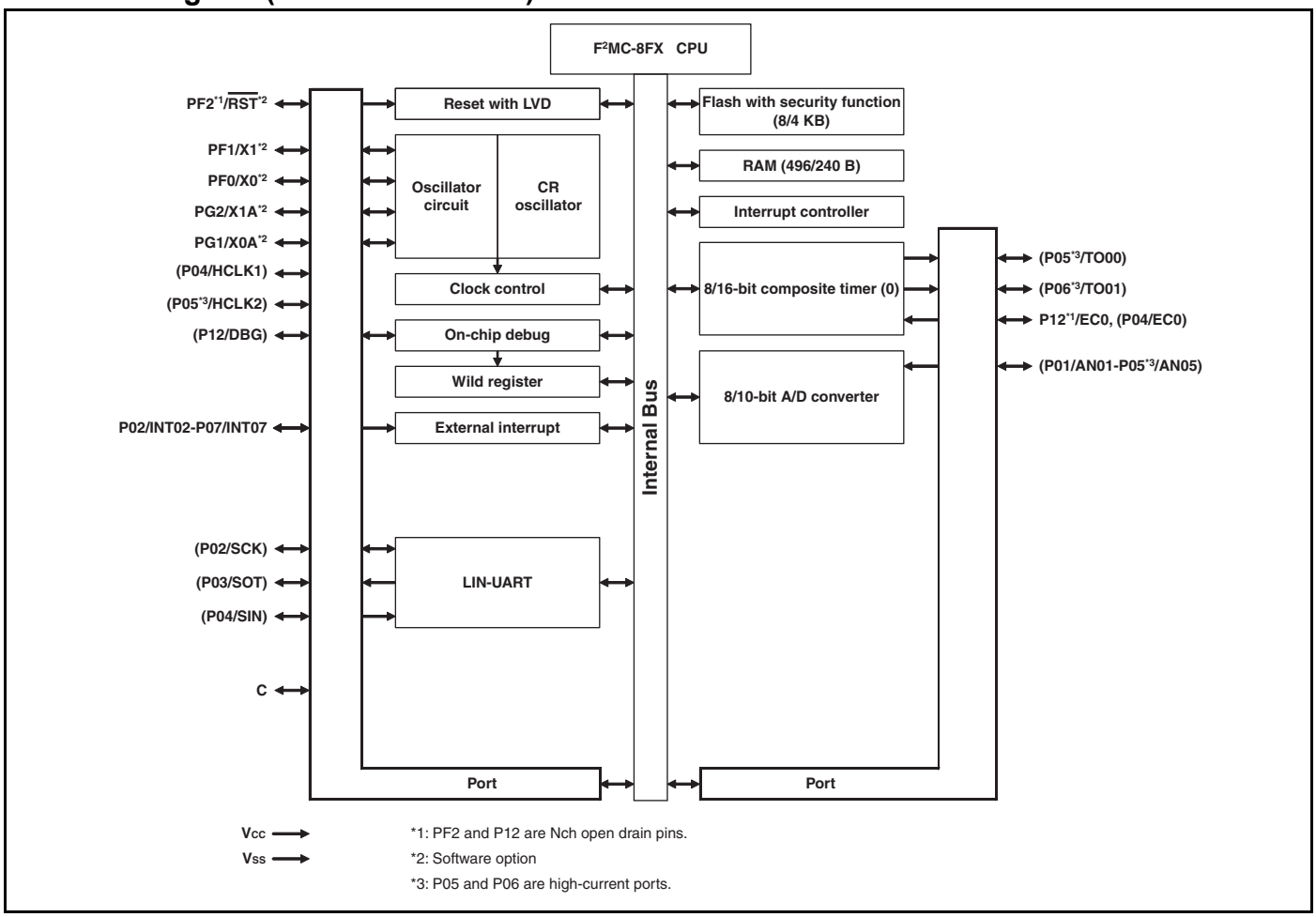
C pin

Use a ceramic capacitor or a capacitor with equivalent frequency characteristics. The bypass capacitor for the V_{CC} pin must have a capacitance larger than C_S. For the connection to a smoothing capacitor C_S, see the diagram below. To prevent the device from unintentionally entering a mode to which the device is not set to transit due to noise, minimize the distance between the C pin and C_S and the distance between C_S and the V_{SS} pin when designing the layout of a printed circuit board.

DBG/$\overline{\text{RST}}$/C pin connection diagram



9. Block Diagram (MB95220H Series)

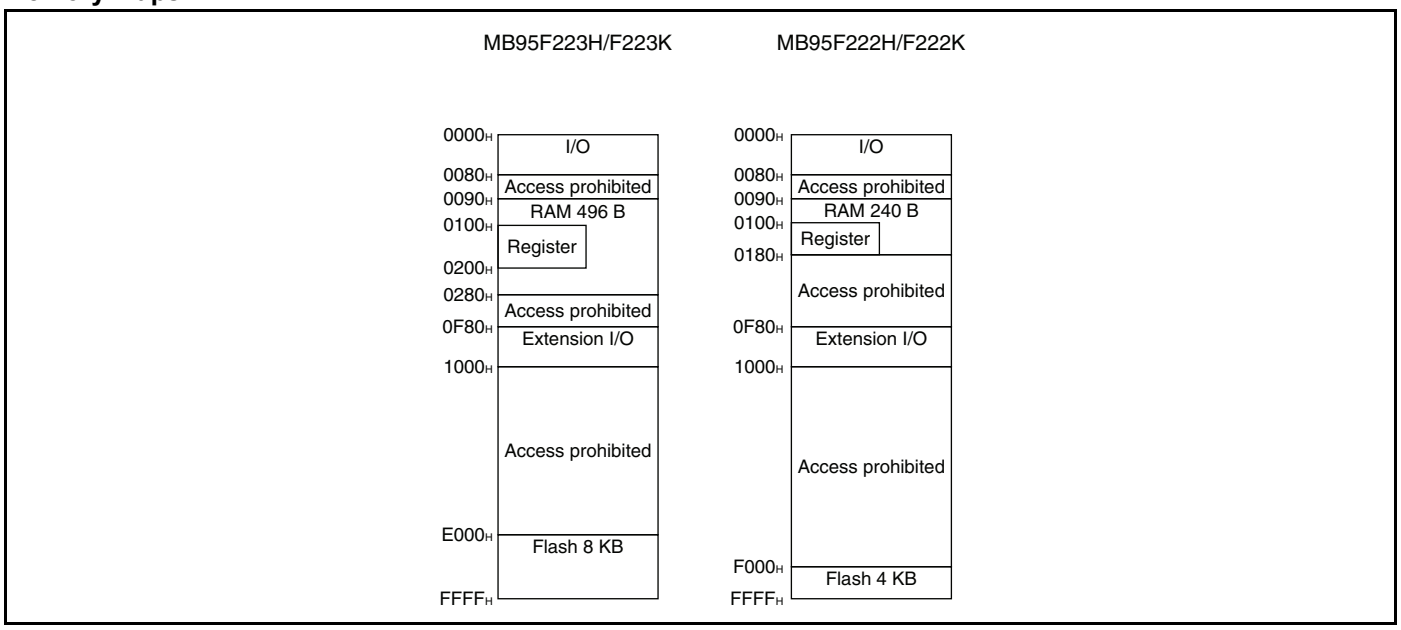


10. CPU Core

Memory Space

The memory space of the MB95220H Series is 64 KB in size, and consists of an I/O area, a data area, and a program area. The memory space includes areas intended for specific purposes such as general-purpose registers and a vector table. The memory maps of the MB95220H Series are shown below.

Memory Maps



11. I/O Map (MB95220H Series)

Address	Register abbreviation	Register name	R/W	Initial value
0000_H	PDR0	Port 0 data register	R/W	00000000_B
0001_H	DDR0	Port 0 direction register	R/W	00000000_B
0002_H	PDR1	Port 1 data register	R/W	00000000_B
0003_H	DDR1	Port 1 direction register	R/W	00000000_B
0004_H	—	(Disabled)	—	—
0005_H	WATR	Oscillation stabilization wait time setting register	R/W	11111111_B
0006_H	—	(Disabled)	—	—
0007_H	SYCC	System clock control register	R/W	$0000X011_B$
0008_H	STBC	Standby control register	R/W	$00000XXX_B$
0009_H	RSRR	Reset source register	R	$XXXXXXXX_B$
$000A_H$	TBTC	Timebase timer control register	R/W	00000000_B
$000B_H$	WPCR	Watch prescaler control register	R/W	00000000_B
$000C_H$	WDTC	Watchdog timer control register	R/W	00000000_B
$000D_H$	SYCC2	System clock control register 2	R/W	$XX100011_B$
$000E_H$ to 0015_H	—	(Disabled)	—	—
0016_H	—	(Disabled)	—	—
0017_H	—	(Disabled)	—	—
0018_H to 0027_H	—	(Disabled)	—	—
0028_H	PDRF	Port F data register	R/W	00000000_B
0029_H	DDRF	Port F direction register	R/W	00000000_B
$002A_H$	PDRG	Port G data register	R/W	00000000_B
$002B_H$	DDRG	Port G direction register	R/W	00000000_B
$002C_H$	PUL0	Port 0 pull-up register	R/W	00000000_B
$002D_H$ to 0034_H	—	(Disabled)	—	—
0035_H	PULG	Port G pull-up register	R/W	00000000_B
0036_H	T01CR1	8/16-bit composite timer 01 status control register 1 ch. 0	R/W	00000000_B
0037_H	T00CR1	8/16-bit composite timer 00 status control register 1 ch. 0	R/W	00000000_B
0038_H	—	(Disabled)	—	—
0039_H	—	(Disabled)	—	—
$003A_H$ to 0048_H	—	(Disabled)	—	—
0049_H	EIC10	External interrupt circuit control register ch. 2/ch. 3	R/W	00000000_B

(Continued)

Address	Register abbreviation	Register name	R/W	Initial value
$004A_H$	EIC20	External interrupt circuit control register ch. 4/ch. 5	R/W	00000000_B
$004B_H$	EIC30	External interrupt circuit control register ch. 6/ch. 7	R/W	00000000_B
$004C_H$ to $004F_H$	—	(Disabled)	—	—
0050_H	SCR	LIN-UART serial control register	R/W	00000000_B
0051_H	SMR	LIN-UART serial mode register	R/W	00000000_B
0052_H	SSR	LIN-UART serial status register	R/W	00001000_B
0053_H	RDR/TDR	LIN-UART receive/transmit data register	R/W	00000000_B
0054_H	ESCR	LIN-UART extended status control register	R/W	00000100_B
0055_H	ECCR	LIN-UART extended communication control register	R/W	$000000XX_B$
0056_H to $006B_H$	—	(Disabled)	—	—
$006C_H$	ADC1	8/10-bit A/D converter control register 1	R/W	00000000_B
$006D_H$	ADC2	8/10-bit A/D converter control register 2	R/W	00000000_B
$006E_H$	ADDH	8/10-bit A/D converter data register (Upper)	R/W	00000000_B
$006F_H$	ADDL	8/10-bit A/D converter data register (Lower)	R/W	00000000_B
0070_H, 0071_H	—	(Disabled)	—	—
0072_H	FSR	Flash memory status register	R/W	$000X0000_B$
0073_H to 0075_H	—	(Disabled)	—	—
0076_H	WREN	Wild register address compare enable register	R/W	00000000_B
0077_H	WROR	Wild register data test setting register	R/W	00000000_B
0078_H	—	Mirror of register bank pointer (RP) and direct bank pointer (DP)	—	—
0079_H	ILR0	Interrupt level setting register 0	R/W	11111111_B
$007A_H$	ILR1	Interrupt level setting register 1	R/W	11111111_B
$007B_H$	ILR2	Interrupt level setting register 2	R/W	11111111_B
$007C_H$	—	(Disabled)	—	—
$007D_H$	ILR4	Interrupt level setting register 4	R/W	11111111_B
$007E_H$	ILR5	Interrupt level setting register 5	R/W	11111111_B
$007F_H$	—	(Disabled)	—	—
$0F80_H$	WRARH0	Wild register address setting register (Upper) ch. 0	R/W	00000000_B

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Address	Register abbreviation	Register name	R/W	Initial value
$0F81_H$	WRARL0	Wild register address setting register (Lower) ch. 0	R/W	00000000_B
$0F82_H$	WRDR0	Wild register data setting register ch. 0	R/W	00000000_B
$0F83_H$	WRARH1	Wild register address setting register (Upper) ch. 1	R/W	00000000_B
$0F84_H$	WRARL1	Wild register address setting register (Lower) ch. 1	R/W	00000000_B
$0F85_H$	WRDR1	Wild register data setting register ch. 1	R/W	00000000_B
$0F86_H$	WRARH2	Wild register address setting register (Upper) ch. 2	R/W	00000000_B
$0F87_H$	WRARL2	Wild register address setting register (Lower) ch. 2	R/W	00000000_B
$0F88_H$	WRDR2	Wild register data setting register ch. 2	R/W	00000000_B
$0F89_H$ to $0F91_H$	—	(Disabled)	—	—
$0F92_H$	T01CR0	8/16-bit composite timer 01 status control register 0 ch. 0	R/W	00000000_B
$0F93_H$	T00CR0	8/16-bit composite timer 00 status control register 0 ch. 0	R/W	00000000_B
$0F94_H$	T01DR	8/16-bit composite timer 01 data register ch. 0	R/W	00000000_B
$0F95_H$	T00DR	8/16-bit composite timer 00 data register ch. 0	R/W	00000000_B
$0F96_H$	TMCR0	8/16-bit composite timer 00/01 timer mode control register ch. 0	R/W	00000000_B
$0F97_H$	—	(Disabled)	—	—
$0F98_H$	—	(Disabled)	—	—
$0F99_H$	—	(Disabled)	—	—
$0F9A_H$	—	(Disabled)	—	—
$0F9B_H$	—	(Disabled)	—	—
$0F9C_H$ to $0FBB_H$	—	(Disabled)	—	—
$0FBC_H$	BGR1	LIN-UART baud rate generator register 1	R/W	00000000_B
$0FBD_H$	BGR0	LIN-UART baud rate generator register 0	R/W	00000000_B
$0FBE_H$ to $0FC2_H$	—	(Disabled)	—	—
$0FC3_H$	AIDRL	A/D input disable register (Lower)	R/W	00000000_B
$0FC4_H$ to $0FE3_H$	—	(Disabled)	—	—
$0FE4_H$	CRTH	Main CR clock trimming register (Upper)	R/W	$1XXXXXXX_B$
$0FE5_H$	CRTL	Main CR clock trimming register (Lower)	R/W	$000XXXXX_B$

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Address	Register abbreviation	Register name	R/W	Initial value
$0FE6_H$, $0FE7_H$	—	(Disabled)	—	—
$0FE8_H$	SYSC	System configuration register	R/W	11000011_B
$0FE9_H$	CMCR	Clock monitoring control register	R/W	00000000_B
$0FEA_H$	CMDR	Clock monitoring data register	R/W	00000000_B
$0FEB_H$	WDTH	Watchdog timer selection ID register (Upper)	R/W	$XXXXXXXX_B$
$0FEC_H$	WDTL	Watchdog timer selection ID register (Lower)	R/W	$XXXXXXXX_B$
$0FED_H$	—	(Disabled)	—	—
$0FEE_H$	ILSR	Input level select register	R/W	00000000_B
$0FEF_H$ to $0FFF_H$	—	(Disabled)	—	—

R/W access symbols

R/W : Readable / Writable
R : Read only
W : Write only

Initial value symbols

0 : The initial value of this bit is “0”.
1 : The initial value of this bit is “1”.
X : The initial value of this bit is undefined.

Note: Do not write to an address that is “(Disabled)”. If a “(Disabled)” address is read, an undefined value is returned.

12. Interrupt Source Table (MB95220H Series)

Interrupt source	Interrupt request number	Vector table address		Bit name of interrupt level setting register	Priority order of interrupt sources of the same level (occurring simultaneously)
		Upper	Lower		
External interrupt ch. 4	IRQ0	$FFFA_H$	$FFFB_H$	L00 [1:0]	High
External interrupt ch. 5	IRQ1	$FFF8_H$	$FFF9_H$	L01 [1:0]	
External interrupt ch. 2	IRQ2	$FFF6_H$	$FFF7_H$	L02 [1:0]	
External interrupt ch. 6					
External interrupt ch. 3	IRQ3	$FFF4_H$	$FFF5_H$	L03 [1:0]	
External interrupt ch. 7					
—	IRQ4	$FFF2_H$	$FFF3_H$	L04 [1:0]	
8/16-bit composite timer ch. 0 (Lower)	IRQ5	$FFF0_H$	$FFF1_H$	L05 [1:0]	
8/16-bit composite timer ch. 0 (Upper)	IRQ6	$FFEE_H$	$FFEF_H$	L06 [1:0]	
LIN-UART (reception)	IRQ7	$FFEC_H$	$FFED_H$	L07 [1:0]	
LIN-UART (transmission)	IRQ8	$FFEA_H$	$FFEB_H$	L08 [1:0]	
—	IRQ9	$FFE8_H$	$FFE9_H$	L09 [1:0]	
—	IRQ10	$FFE6_H$	$FFE7_H$	L10 [1:0]	
—	IRQ11	$FFE4_H$	$FFE5_H$	L11 [1:0]	
—	IRQ12	$FFE2_H$	$FFE3_H$	L12 [1:0]	
—	IRQ13	$FFE0_H$	$FFE1_H$	L13 [1:0]	
—	IRQ14	$FFDE_H$	$FFDF_H$	L14 [1:0]	
—	IRQ15	$FFDC_H$	$FFDD_H$	L15 [1:0]	
—	IRQ16	$FFDA_H$	$FFDB_H$	L16 [1:0]	
—	IRQ17	$FFD8_H$	$FFD9_H$	L17 [1:0]	
8/10-bit A/D converter	IRQ18	$FFD6_H$	$FFD7_H$	L18 [1:0]	
Timebase timer	IRQ19	$FFD4_H$	$FFD5_H$	L19 [1:0]	
Watch prescaler	IRQ20	$FFD2_H$	$FFD3_H$	L20 [1:0]	
—	IRQ21	$FFD0_H$	$FFD1_H$	L21 [1:0]	
—	IRQ22	$FFCE_H$	$FFCF_H$	L22 [1:0]	
Flash memory	IRQ23	$FFCC_H$	$FFCD_H$	L23 [1:0]	Low

13. Electrical Characteristics

13.1 Absolute Maximum Ratings

Parameter	Symbol	Rating		Unit	Remarks
		Min	Max		
Power supply voltage*1	V_{CC}	V_{SS}-0.3	V_{SS} + 6	V	
Input voltage*1	V_{I1}	V_{SS}-0.3	V_{CC} + 0.3	V	Other than PF2*2
	V_{I2}	V_{SS}-0.3	10.5	V	PF2
Output voltage*1	V_O	V_{SS}-0.3	V_{SS} + 6	V	*2
Maximum clamp current	I_{CLAMP}	-2	+ 2	mA	Applicable to specific pins*3
Total maximum clamp current	$S\|I_{CLAMP}\|$	—	20	mA	Applicable to specific pins*3
"L" level maximum output current	I_{OL1}	—	15	mA	Other than P05, P06
	I_{OL2}		15		P05, P06
"L" level average current	I_{OLAV1}	—	4	mA	Other than P05, P06 Average output current = operating current × operating ratio (1 pin)
	I_{OLAV2}		12		P05, P06 Average output current = operating current × operating ratio (1 pin)
"L" level total maximum output current	SI_{OL}	—	100	mA	
"L" level total average output current	SI_{OLAV}	—	50	mA	Total average output current = operating current × operating ratio (Total number of pins)
"H" level maximum output current	I_{OH1}	—	-15	mA	Other than P05, P06
	I_{OH2}		-15		P05, P06
"H" level average current	I_{OHAV1}	—	-4	mA	Other than P05, P06 Average output current = operating current × operating ratio (1 pin)
	I_{OHAV2}		-8		P05, P06 Average output current = operating current × operating ratio (1 pin)
"H" level total maximum output current	SI_{OH}	—	-100	mA	
"H" level total average output current	SI_{OHAV}	—	-50	mA	Total average output current = operating current × operating ratio (Total number of pins)
Power consumption	Pd	—	320	mW	
Operating temperature	T_A	-40	+ 85	°C	
Storage temperature	Tstg	-55	+ 150	°C	

(Continued)

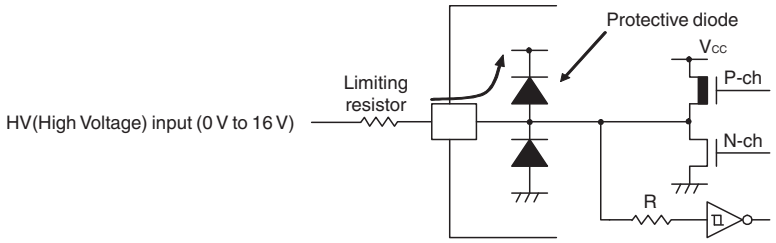
(Continued)

*1: The parameter is based on V_{SS} = 0.0 V.

*2: V_I and V_O must not exceed V_{CC}+0.3 V. V_I must not exceed the rated voltage. However, if the maximum current to/from an input is limited by means of an external component, the I_{CLAMP} rating is used instead of the V_I rating.

*3: Applicable to the following pins: P01 to P07, PG1, PG2, PF0, PF1
- Use under recommended operating conditions.
- Use with DC voltage (current).
- The HV (High Voltage) signal is an input signal exceeding the V_{CC} voltage. Always connect a limiting resistor between the HV (High Voltage) signal and the microcontroller before applying the HV (High Voltage) signal.
- The value of the limiting resistor should be set to a value at which the current to be input to the microcontroller pin when the HV (High Voltage) signal is input is below the standard value, irrespective of whether the current is transient current or stationary current.
- When the microcontroller drive current is low, such as in low power consumption modes, the HV (High Voltage) input potential may pass through the protective diode to increase the potential of the V_{CC} pin, affecting other devices.
- If the HV (High Voltage) signal is input when the microcontroller power supply is off (not fixed at 0 V), since power is supplied from the pins, incomplete operations may be executed.
- If the HV (High Voltage) input is input after power-on, since power is supplied from the pins, the voltage of power supply may not be sufficient to enable a power-on reset.
- Do not leave the HV (High Voltage) input pin unconnected.
- Example of a recommended circuit:

Input/Output equivalent circuit



WARNING: Semiconductor devices can be permanently damaged by application of stress (voltage, current, temperature, etc.) in excess of absolute maximum ratings. Do not exceed these ratings.

13.2 Recommended Operating Conditions

(V_{SS} = 0.0 V)

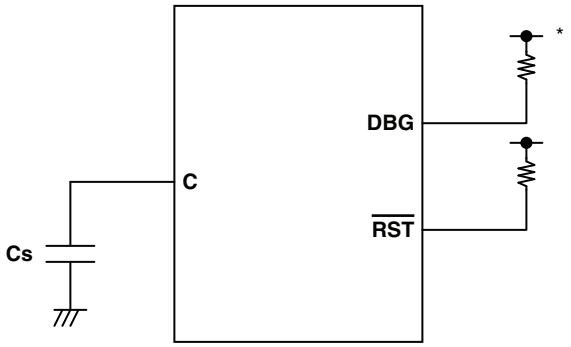
Parameter	Symbol	Value		Unit	Remarks	
		Min	Max			
Power supply voltage	V_{CC}	2.4*1*2	5.5*1	V	In normal operation	Other than on-chip debug mode
		2.3	5.5		Hold condition in stop mode	
		2.9	5.5		In normal operation	On-chip debug mode
		2.3	5.5		Hold condition in stop mode	
Smoothing capacitor	C_S	0.022	1	µF	*3	
Operating temperature	T_A	-40	+85	°C	Other than on-chip debug mode	
		+5	+35		On-chip debug mode	

*1: The value varies depending on the operating frequency, the machine clock and the analog guaranteed range.

*2: The value is 2.88 V when the low-voltage detection reset is used.

*3: Use a ceramic capacitor or a capacitor with equivalent frequency characteristics. The bypass capacitor for the V_{CC} pin must have a capacitance larger than C_S. For the connection to a smoothing capacitor C_S, see the diagram below. To prevent the device from unintentionally entering an unknown mode due to noise, minimize the distance between the C pin and C_S and the distance between C_S and the V_{SS} pin when designing the layout of a printed circuit board.

DBG / $\overline{\text{RST}}$ / C pin connection diagram



*: Since the DBG pin becomes a communication pin in on-chip debug mode, set a pull-up resistor value suiting the input/output specifications of P12/DBG.

WARNING: The recommended operating conditions are required in order to ensure the normal operation of the semiconductor device. All of the device's electrical characteristics are warranted when the device is operated within these ranges. Always use semiconductor devices within their recommended operating condition ranges. Operation outside these ranges may adversely affect reliability and could result in device failure. No warranty is made with respect to uses, operating conditions, or combinations not represented on the data sheet. Users considering application outside the listed conditions are advised to contact their representatives beforehand.

13.3 DC Characteristics

(V_{CC} = 5.0 V±10%, V_{SS} = 0.0 V, T_A = -40°C to +85°C)

Parameter	Symbol	Pin name	Condition	Value			Unit	Remarks
				Min	Typ	Max		
"H" level input voltage	V_{IHI}	P04	*1	0.7 V_{CC}	—	V_{CC}+0.3	V	When CMOS input level (hysteresis input) is selected
	V_{IHS}	P01 to P07, P12, PF0, PF1, PG1, PG2	*1	0.8 V_{CC}	—	V_{CC}+0.3	V	Hysteresis input
	V_{IHM}	PF2	—	0.7 V_{CC}	—	10.5	V	Hysteresis input*3
“L” level input voltage	V_{IL}	P04	*1	V_{SS}-0.3	—	0.3 V_{CC}	V	When CMOS input level (hysteresis input) is selected
	V_{ILS}	P01 to P07, P12, PF0, PF1, PG1, PG2	*1	V_{SS}-0.3	—	0.2 V_{CC}	V	Hysteresis input
	V_{ILM}	PF2	—	V_{SS}-0.3	—	0.3 V_{CC}	V	Hysteresis input
Open-drain output application voltage	V_D	PF2, P12	—	V_{SS}-0.3	—	V_{SS} + 5.5	V	
“H” level output voltage	V_{OH1}	Output pins other than P05, P06, P12, PF2	I_{OH} = -4 mA	V_{CC}-0.5	—	—	V	
	V_{OH2}	P05, P06	I_{OH} = -8 mA	V_{CC}-0.5	—	—	V	
“L” level output voltage	V_{OL1}	Output pins other than P05, P06	I_{OL} = 4 mA	—	—	0.4	V	
	V_{OL2}	P05, P06	I_{OL} = 12 mA	—	—	0.4	V	
Input leak current (Hi-Z output leak current)	I_{LI}	All input pins	0.0 V < V_I < V_{CC}	-5	—	+5	µA	When pull-up resistance is disabled
Pull-up resistance	R_{PULL}	P01 to P07, PG1, PG2	V_I = 0 V	25	50	100	kΩ	When pull-up resistance is enabled
Input capacitance	C_{IN}	Other than V_{CC} and V_{SS}	f = 1 MHz	—	5	15	pF	

(Continued)

(V_{CC} = 5.0 V±10%, V_{SS} = 0.0 V, T_A = -40°C to +85°C)

Parameter	Symbol	Pin name	Condition	Value			Unit	Remarks
				Min	Typ	Max		
Power supply current*2	I_{CC}	V_{CC} (External clock operation)	V_{CC} = 5.5 V F_{CH} = 32 MHz F_{MP} = 16 MHz Main clock mode (divided by 2)	—	13	17	mA	Flash memory product (except writing and erasing)
				—	33.5	39.5	mA	Flash memory product (at writing and erasing)
				—	15	21	mA	At A/D conversion
	I_{CCS}		V_{CC} = 5.5 V F_{CH} = 32 MHz F_{MP} = 16 MHz Main sleep mode (divided by 2)	—	5.5	9	mA	
	I_{CCL}		V_{CC} = 5.5 V F_{CL} = 32 kHz F_{MPL} = 16 kHz Subclock mode (divided by 2) T_A = +25°C	—	65	153	µA	
	I_{CCLS}		V_{CC} = 5.5 V F_{CL} = 32 kHz F_{MPL} = 16 kHz Subsleep mode (divided by 2) T_A = +25°C	—	10	84	µA	
	I_{CCT}		V_{CC} = 5.5 V F_{CL} = 32 kHz Watch mode Main stop mode T_A = +25°C	—	5	30	µA	
	I_{CCMCR}	V_{CC}	V_{CC} = 5.5 V F_{CRH} = 10 MHz F_{MP} = 10 MHz Main CR clock mode	—	8.6	—	mA	
	I_{CCSCR}		V_{CC} = 5.5 V Sub-CR clock mode (divided by 2) T_A = +25°C	—	110	410	µA	

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(V_{CC} = 5.0 V±10%, V_{SS} = 0.0 V, T_A = -40°C to +85°C)

Parameter	Symbol	Pin name	Condition	Value			Unit	Remarks
				Min	Typ	Max		
Power supply current*2	I_{CCTS}	V_{CC} (External clock operation)	V_{CC} = 5.5 V F_{CH} = 32 MHz Timebase timer mode T_A = +25°C	—	1.1	3	mA	
	I_{CCH}		V_{CC} = 5.5 V Substop mode T_A = +25°C	—	3.5	22.5	µA	Main stop mode for single clock selection
	I_{LVD}	V_{CC}	Current consumption for low-voltage detection circuit only	—	37	54	µA	
	I_{CRH}		Current consumption for the internal main CR oscillator	—	0.5	0.6	mA	
	I_{CRL}		Current consumption for the internal sub-CR oscillator oscillating at 100 kHz	—	20	72	µA	

*1: The input level of P04 can be switched between “CMOS input level” and “hysteresis input level”. The input level selection register (ILSR) is used to switch between the two input levels.

*2:
- The power supply current is determined by the external clock. When the low-voltage detection option is selected, the power-supply current will be the sum of adding the current consumption of the low-voltage detection circuit (I_{LVD}) to one of the value from I_{CC} to I_{CCH}. In addition, when both the low-voltage detection option and the CR oscillator are selected, the power supply current will be the sum of adding up the current consumption of the low-voltage detection circuit, the current consumption of the CR oscillators (I_{CRH}, I_{CRL}) and a specified value. In on-chip debug mode, the CR oscillator (I_{CRH}) and the low-voltage detection circuit are always enabled, and current consumption therefore increases accordingly.
- See “13.4. AC Characteristics: 13.4.1. Clock Timing” for F_{CH} and F_{CL}.
- See “13.4. AC Characteristics: 13.4.2. Source Clock/Machine Clock” for F_{MP} and F_{MPL}.

*3: PF2 act as high voltage supply for the flash memory during program and erase. It can tolerate high voltage input. For details, see section “13.6. Flash Memory Program/Erase Characteristics”.

13.4 AC Characteristics

13.4.1 Clock Timing

(V_{CC} = 2.4 V to 5.5 V, V_{SS} = 0.0 V, T_A = -40°C to +85°C)

Parameter	Symbol	Pin name	Condition	Value			Unit	Remarks
				Min	Typ	Max		
Clock frequency	F_{CH}	X0, X1	—	1	—	16.25	MHz	When the main oscillation circuit is used
		X0, HCLK1, HCLK2	X1 open	1	—	12	MHz	When the main external clock is used
		X0, X1, HCLK1, HCLK2	—	1	—	32.5	MHz	
	F_{CRH}	—	—	9.7	10	10.3	MHz	When the main CR clock is used 2.4 V ≤ Vcc < 5.5 V(0 °C ≤ T_A ≤ 40 °C)
				7.76	8	8.24	MHz	
				0.97	1	1.03	MHz	
				9.5	10	10.5	MHz	When the main CR clock is used 2.4 V ≤ Vcc < 5.5 V (-40 °C ≤ T_A < 0 °C, 40 °C < T_A ≤ 85 °C)
				7.6	8	8.4	MHz	
				0.95	1	1.05	MHz	
	F_{CL}	X0A, X1A	—	—	32.768	—	kHz	When the sub oscillation circuit is used
				—	32.768	—	kHz	When the sub-external clock is used
	F_{CRL}	—	—	50	100	200	kHz	When the sub-CR clock is used
Clock cycle time	t_{HCYL}	X0, X1	—	61.5	—	1000	ns	When the main oscillation circuit is used
		X0, HCLK1, HCLK2	X1 open	83.4	—	1000	ns	When the external clock is used
		X0, X1, HCLK1, HCLK2	—	30.8	—	1000	ns	
	t_{LCYL}	X0A, X1A	—	—	30.5	—	µs	When the subclock is used

(Continued)

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(V_{CC} = 2.4 V to 5.5 V, V_{SS} = 0.0 V, T_A = -40°C to +85°C)

Parameter	Symbol	Pin name	Condition	Value			Unit	Remarks
				Min	Typ	Max		
Input clock pulse width	t_{WH1} t_{WL1}	X0, HCLK1, HCLK2	X1 open	33.4	—	—	ns	When the external clock is used, the duty ratio should range between 40% and 60%.
		X0, X1, HCLK1, HCLK2	—	12.4	—	—	ns	
	t_{WH2} t_{WL2}	X0A	—	—	15.2	—	µs	
Input clock rise time and fall time	t_{CR} t_{CF}	X0, HCLK1, HCLK2	X1 open	—	—	5	ns	When the external clock is used
		X0, X1, HCLK1, HCLK2	—	—	—	5	ns	
CR oscillation start time	t_{CRHWK}	—	—	—	—	80	µs	When the main CR clock is used
	t_{CRLWK}	—	—	—	—	10	µs	When the sub-CR clock is used

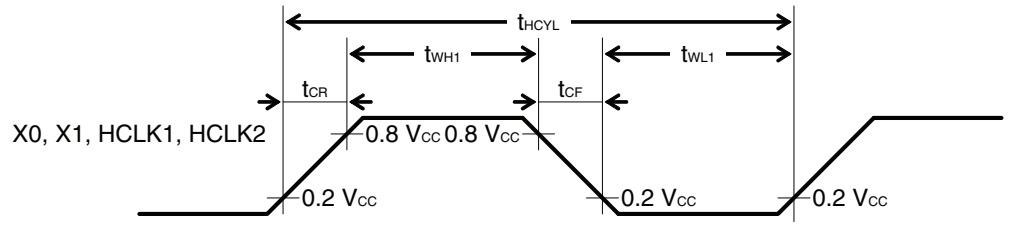
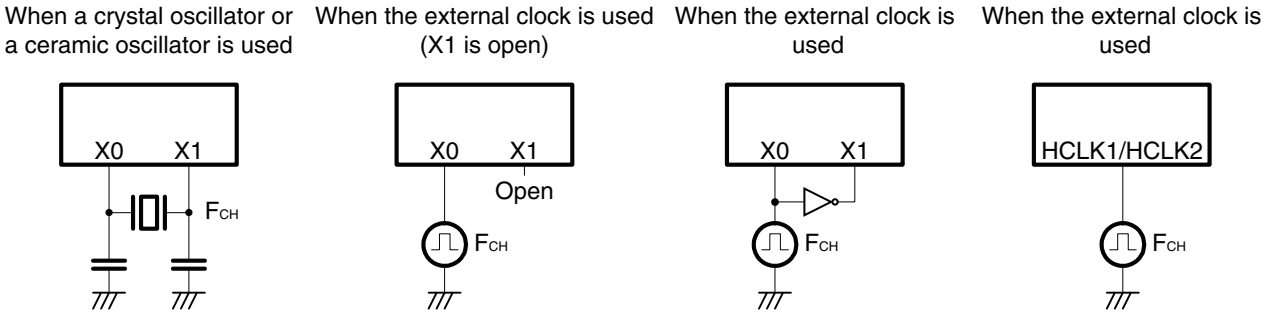


Figure of main clock input port external connection



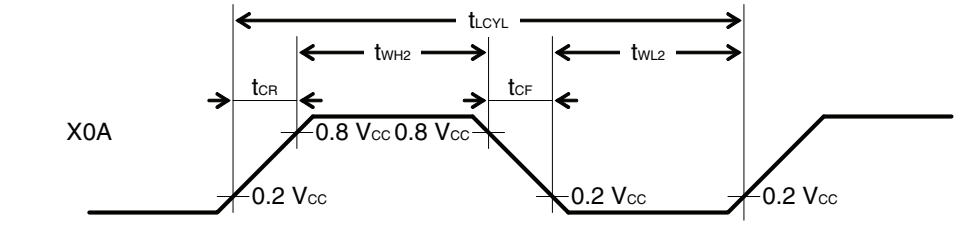
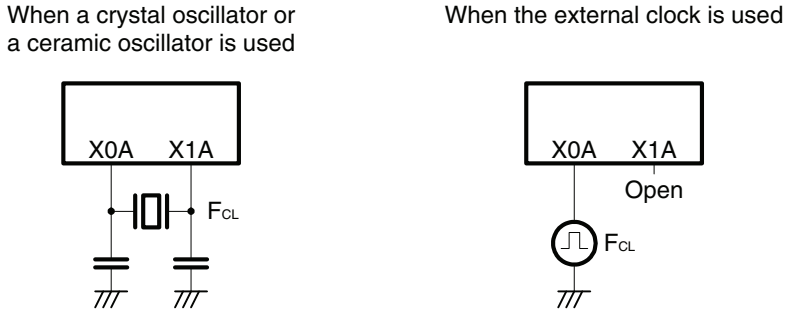


Figure of subclock input port external connection



13.4.2 Source Clock/Machine Clock

(V_{CC} = 5.0 V±10%, V_{SS} = 0.0 V, T_A = -40°C to +85°C)

Parameter	Symbol	Pin name	Value			Unit	Remarks
			Min	Typ	Max		
Source clock cycle time*1	t_{SCLK}	—	61.5	—	2000	ns	When the main external clock is used Min: F_{CH} = 32.5 MHz, divided by 2 Max: F_{CH} = 1 MHz, divided by 2
			100	—	1000	ns	When the main CR clock is used Min: F_{CRH} = 10 MHz Max: F_{CRH} = 1 MHz
			—	61	—	µs	When the sub-CR clock is used F_{CL} = 32.768 kHz, divided by 2
			—	20	—	µs	When the sub-oscillation clock is used F_{CRL} = 100 kHz, divided by 2
Source clock frequency	F_{SP}	—	0.5	—	16.25	MHz	When the main oscillation clock is used
			1	—	10	MHz	When the main CR clock is used
	F_{SPL}		—	16.384	—	kHz	When the sub-oscillation clock is used
			—	50	—	kHz	When the sub-CR clock is used F_{CRL} = 100 kHz, divided by 2
Machine clock cycle time*2 (minimum instruction execution time)	t_{MCLK}	—	61.5	—	32000	ns	When the main oscillation clock is used Min: F_{SP} = 16.25 MHz, no division Max: F_{SP} = 0.5 MHz, divided by 16
			100	—	16000	ns	When the main CR clock is used Min: F_{SP} = 10 MHz Max: F_{SP} = 1 MHz, divided by 16
			61	—	976.5	µs	When the sub-oscillation clock is used Min: F_{SPL} = 16.384 kHz, no division Max: F_{SPL} = 16.384 kHz, divided by 16
			20	—	320	µs	When the sub-CR clock is used Min: F_{SPL} = 50 kHz, no division Max: F_{SPL} = 50 kHz, divided by 16
Machine clock frequency	F_{MP}	—	0.031	—	16.25	MHz	When the main oscillation clock is used
			0.0625	—	10	MHz	When the main CR clock is used
	F_{MPL}		1.024	—	16.384	kHz	When the sub-oscillation clock is used
			3.125	—	50	kHz	When the sub-CR clock is used F_{CRL} = 100 kHz

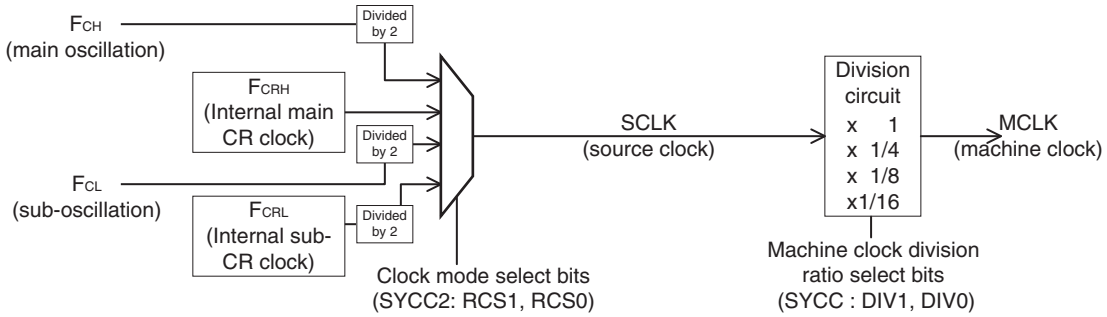
*1: This is the clock before it is divided according to the division ratio set by the machine clock division ratio selection bits (SYCC : DIV1 and DIV0) . This source clock is divided to become a machine clock according to the division ratio set by the machine clock division ratio selection bits (SYCC : DIV1 and DIV0) . In addition, a source clock can be selected from the following.

- Main clock divided by 2
- Main CR clock
- Subclock divided by 2
- Sub-CR clock divided by 2

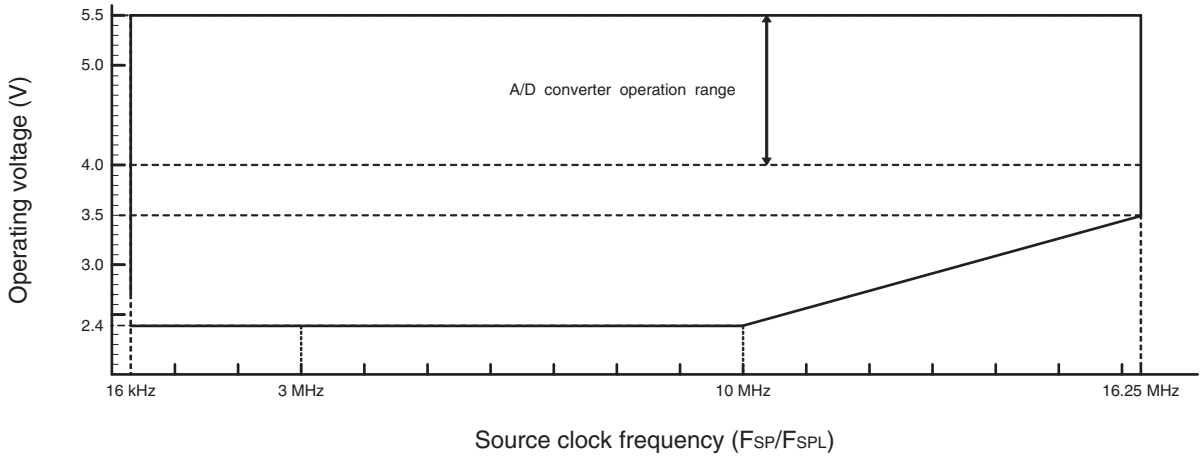
*2: This is the operating clock of the microcontroller. A machine clock can be selected from the following.

- Source clock (no division)
- Source clock divided by 4
- Source clock divided by 8
- Source clock divided by 16

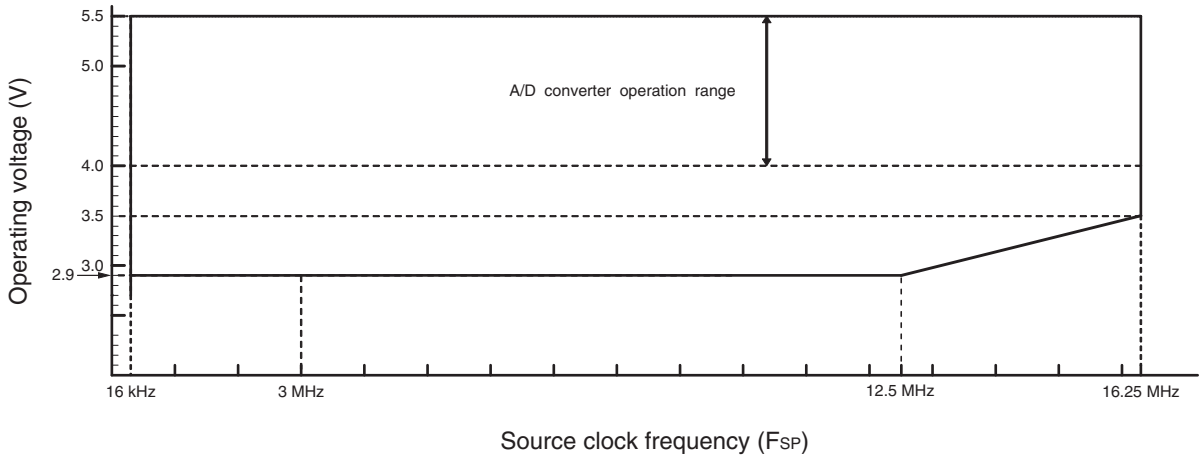
Schematic diagram of the clock generation block



Operating voltage - Operating frequency (When T_A = -40°C to +85°C)
MB95220H (without the on-chip debug function)



Operating voltage - Operating frequency (When T_A = -40°C to +85°C)
MB95220H (with the on-chip debug function)



13.4.3 External Reset

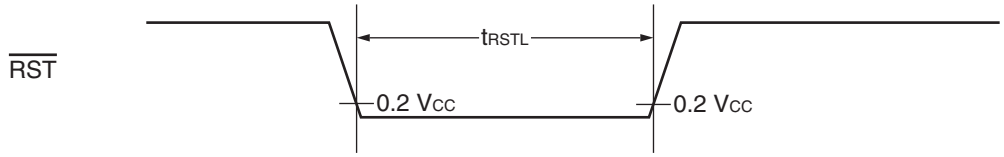
(V_{CC} = 5.0 V±10%, V_{SS} = 0.0 V, T_A = -40°C to +85°C)

Parameter	Symbol	Value		Unit	Remarks
		Min	Max		
$\overline{RST}$ "L" level pulse width	t_{RSTL}	2 t_{MCLK}*1	—	ns	In normal operation
		Oscillation time of the oscillator*2+100	—	µs	In stop mode, subclock mode, sub-sleep mode, watch mode, and power on
		100	—	µs	In timebase timer mode

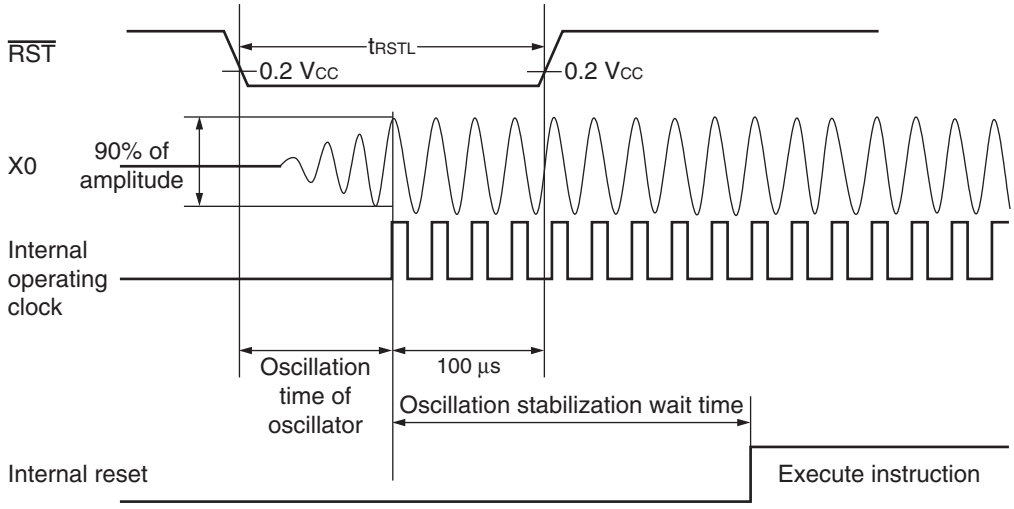
*1: See "13.4.2. Source Clock/Machine Clock" for t_{MCLK}.

*2: The oscillation time of an oscillator is the time for it to reach 90% of its amplitude. The crystal oscillator has an oscillation time of between several ms and tens of ms. The ceramic oscillator has an oscillation time of between hundreds of µs and several ms. The external clock has an oscillation time of 0 ms. The CR oscillator clock has an oscillation time of between several µs and several ms.

In normal operation



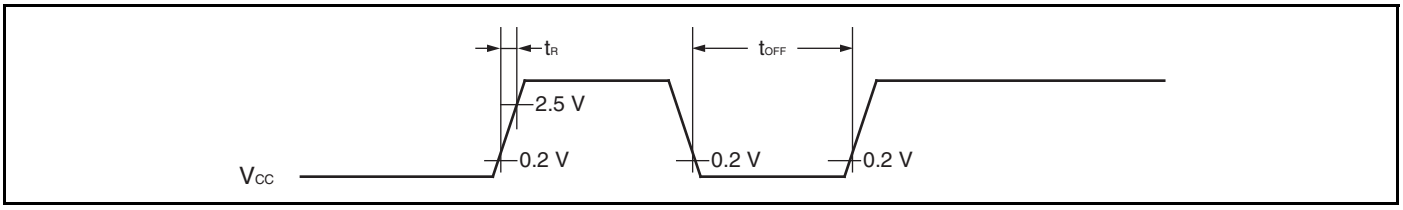
In stop mode, subclock mode, subsleep mode, watch mode and power-on



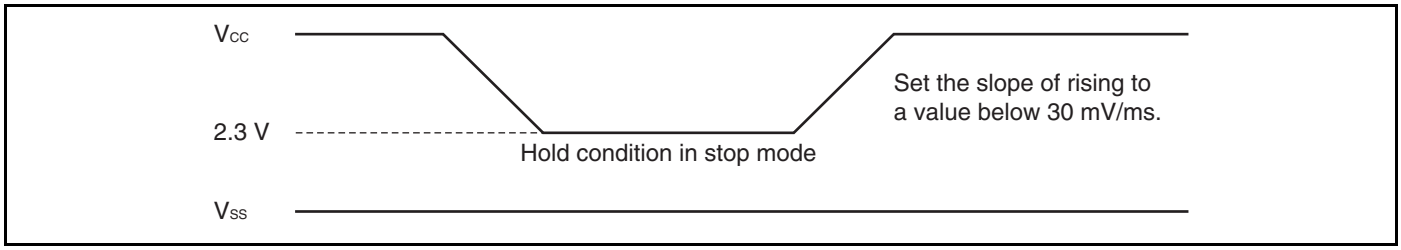
13.4.4 Power-on Reset

(V_{SS} = 0.0 V, T_A = -40°C to +85°C)

Parameter	Symbol	Condition	Value		Unit	Remarks
			Min	Max		
Power supply rising time	t_R	—	—	50	ms	
Power supply cutoff time	t_{OFF}	—	1	—	ms	Wait time until power-on



Note: A sudden change of power supply voltage may activate the power-on reset function. When changing the power supply voltage during the operation, set the slope of rising to a value below within 30 mV/ms as shown below.

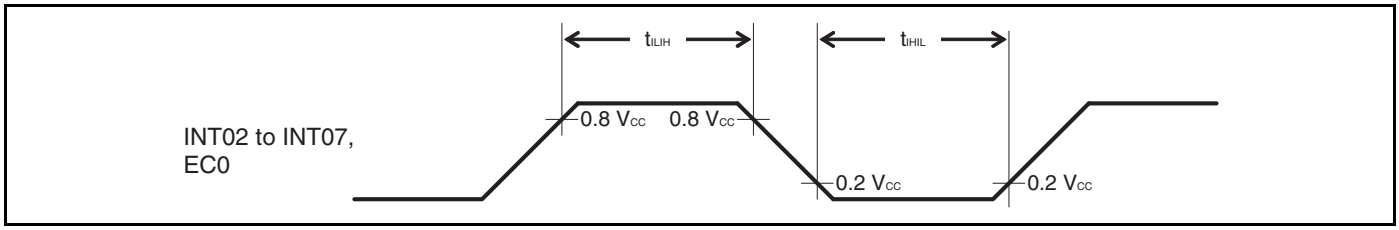


13.4.5 Peripheral Input Timing

(V_{CC} = 5.0 V±10%, V_{SS} = 0.0 V, T_A = -40°C to +85°C)

Parameter	Symbol	Pin name	Value		Unit
			Min	Max	
Peripheral input “H” pulse width	t_{ILIH}	INT02 to INT07, EC0	2 t_{MCLK}*	—	ns
Peripheral input “L” pulse width	t_{IHIL}		2 t_{MCLK}*	—	ns

* See “13.4.2. Source Clock/Machine Clock” for t_{MCLK}.



13.4.6 LIN-UART Timing (Available only in MB95F222H/F222K/F223H/F223K)

*Sampling is executed at the rising edge of the sampling clock*1, and serial clock delay is disabled*2.*
(ESCR register:SCES bit = 0, ECCR register:SCDE bit = 0)

(V_{CC} = 5.0 V±10%, AV_{SS} = V_{SS} = 0.0 V, T_A = -40°C to +85°C)

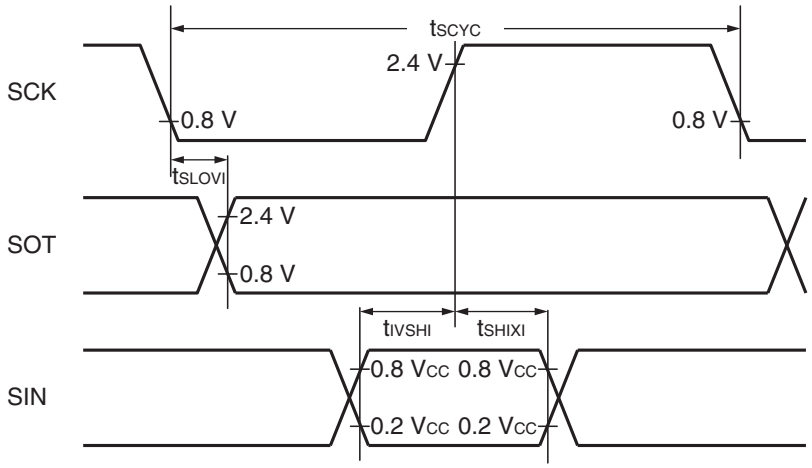
Parameter	Symbol	Pin name	Condition	Value		Unit
				Min	Max	
Serial clock cycle time	t_{SCYC}	SCK	Internal clock operation output pin: C_L = 80 pF+1 TTL	5 t_{MCLK}*3	—	ns
SCK ↓→SOT delay time	t_{SLOVI}	SCK, SOT		-95	+95	ns
Valid SIN → SCK ↑	t_{IVSHI}	SCK, SIN		t_{MCLK}*3+190	—	ns
SCK ↑→ valid SIN hold time	t_{SHIXI}	SCK, SIN		0	—	ns
Serial clock “L” pulse width	t_{SLSH}	SCK	External clock operation output pin: C_L = 80 pF+1 TTL	3 t_{MCLK}*3-t_R	—	ns
Serial clock “H” pulse width	t_{SHSL}	SCK		t_{MCLK}*3+95	—	ns
SCK ↓→SOT delay time	t_{SLOVE}	SCK, SOT		—	2 t_{MCLK}*3+95	ns
Valid SIN → SCK ↑	t_{IVSHE}	SCK, SIN		190	—	ns
SCK ↑→valid SIN hold time	t_{SHIXE}	SCK, SIN		t_{MCLK}*3+95	—	ns
SCK fall time	t_F	SCK		—	10	ns
SCK rise time	t_R	SCK		—	10	ns

*1: There is a function used to choose whether the sampling of reception data is performed at a rising edge or a falling edge of the serial clock.

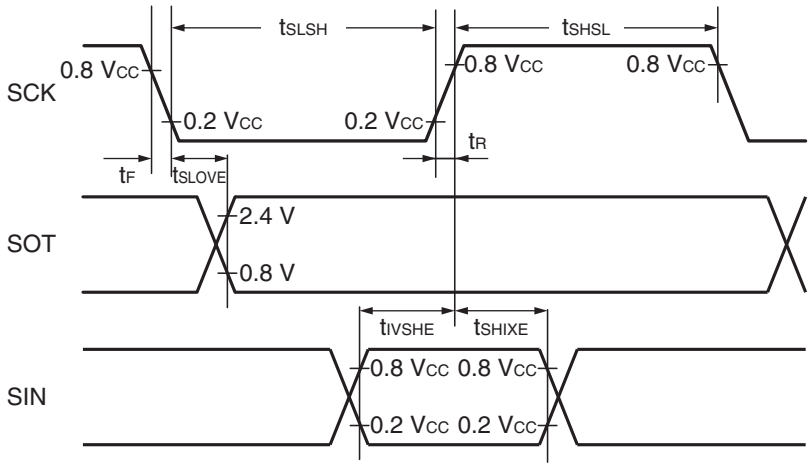
*2: The serial clock delay function is a function used to delay the output signal of the serial clock for half the clock.

*3: See “13.4.2. Source Clock/Machine Clock” for t_{MCLK}.

Internal shift clock mode



External shift clock mode



*Sampling is executed at the falling edge of the sampling clock*1, and serial clock delay is disabled*2.*
(ESCR register:SCES bit = 1, ECCR register:SCDE bit = 0)

(V_{CC} = 5.0 V±10%, V_{SS} = 0.0 V, T_A = -40°C to +85°C)

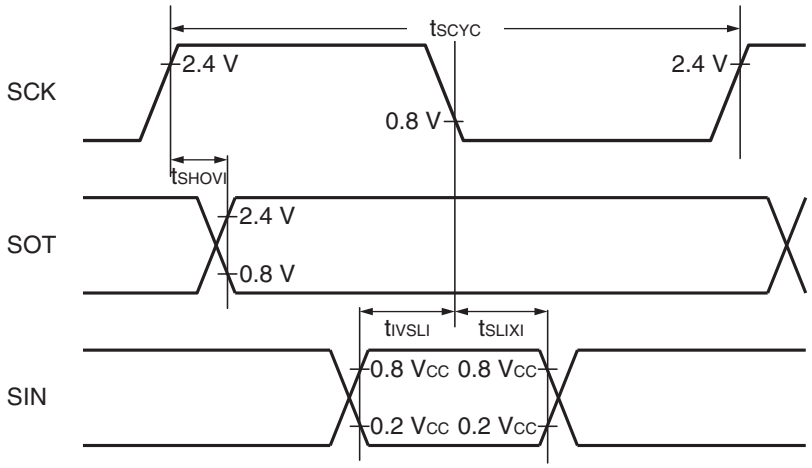
Parameter	Symbol	Pin name	Condition	Value		Unit
				Min	Max	
Serial clock cycle time	t_{SCYC}	SCK	Internal clock operation output pin: C_L = 80 pF+1 TTL	5 t_{MCLK}*3	—	ns
SCK ↑→ SOT delay time	t_{SHOVI}	SCK, SOT		-95	+95	ns
Valid SIN → SCK↓	t_{IVSLI}	SCK, SIN		t_{MCLK}*3+190	—	ns
SCK ↓→ valid SIN hold time	t_{SLIXI}	SCK, SIN		0	—	ns
Serial clock “H” pulse width	t_{SHSL}	SCK	External clock operation output pin: C_L = 80 pF+1 TTL	3 t_{MCLK}*3-t_R	—	ns
Serial clock “L” pulse width	t_{SLSH}	SCK		t_{MCLK}*3+95	—	ns
SCK ↑→ SOT delay time	t_{SHOVE}	SCK, SOT		—	2 t_{MCLK}*3+95	ns
Valid SIN → SCK ↓	t_{IVSLE}	SCK, SIN		190	—	ns
SCK↓→ valid SIN hold time	t_{SLIXE}	SCK, SIN		t_{MCLK}*3+95	—	ns
SCK fall time	t_F	SCK		—	10	ns
SCK rise time	t_R	SCK		—	10	ns

*1: There is a function used to choose whether the sampling of reception data is performed at a rising edge or a falling edge of the serial clock.

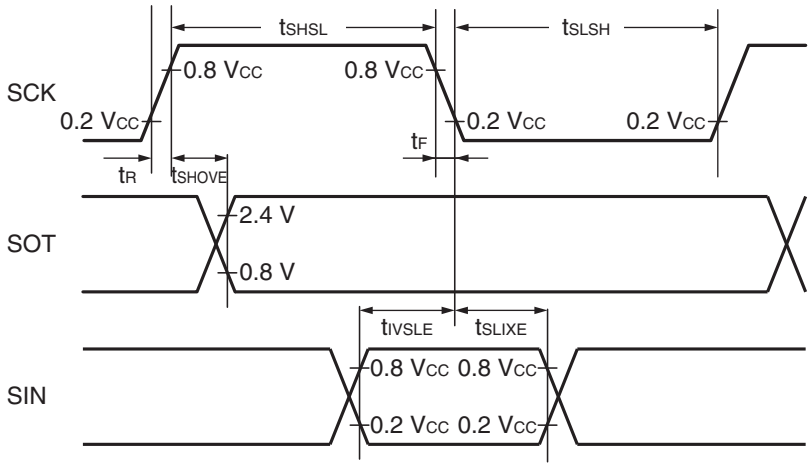
*2: The serial clock delay function is a function used to delay the output signal of the serial clock for half the clock.

*3: See “13.4.2. Source Clock/Machine Clock” for t_{MCLK}.

Internal shift clock mode



External shift clock mode



*Sampling is executed at the rising edge of the sampling clock*1, and serial clock delay is enabled*2.*
(ESCR register:SCES bit = 0, ECCR register:SCDE bit = 1)

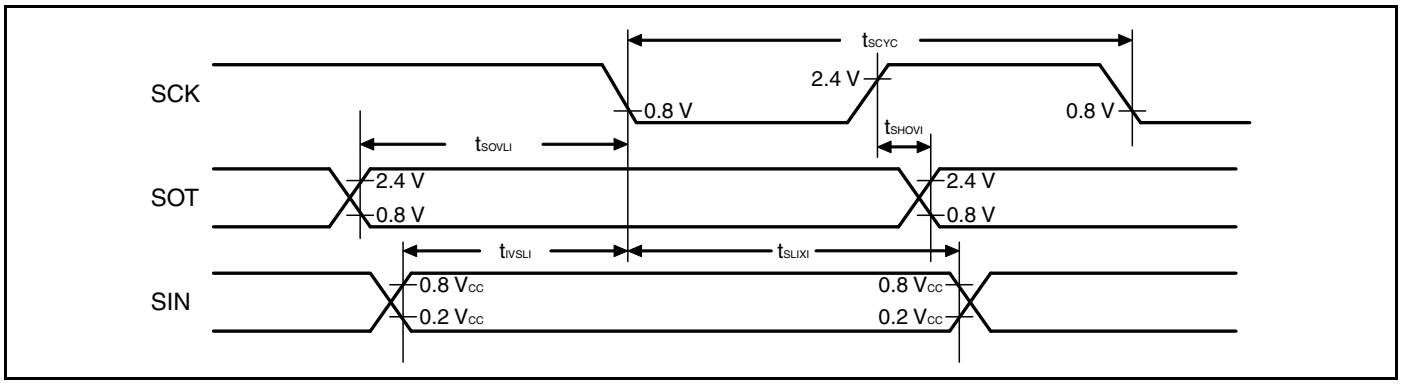
(V_{CC} = 5.0 V±10%, V_{SS} = 0.0 V, T_A = -40°C to +85°C)

Parameter	Symbol	Pin name	Condition	Value		Unit
				Min	Max	
Serial clock cycle time	t_{SCYC}	SCK	Internal clock operation output pin: C_L = 80 pF+1 TTL	5 t_{MCLK}*3	—	ns
SCK↑→ SOT delay time	t_{SHOVI}	SCK, SOT		-95	+95	ns
Valid SIN → SCK ↓	t_{IVSLI}	SCK, SIN		t_{MCLK}*3+190	—	ns
SCK ↓→ valid SIN hold time	t_{SLIXI}	SCK, SIN		0	—	ns
SOT → SCK ↓ delay time	t_{SOVLI}	SCK, SOT		—	4 t_{MCLK}*3	ns

*1: There is a function used to choose whether the sampling of reception data is performed at a rising edge or a falling edge of the serial clock.

*2: The serial clock delay function is a function that delays the output signal of the serial clock for half clock.

*3: See “13.4.2. Source Clock/Machine Clock” for t_{MCLK}.



*Sampling is executed at the falling edge of the sampling clock*1, and serial clock delay is enabled*2.*
(ESCR register:SCES bit = 1, ECCR register:SCDE bit = 1)

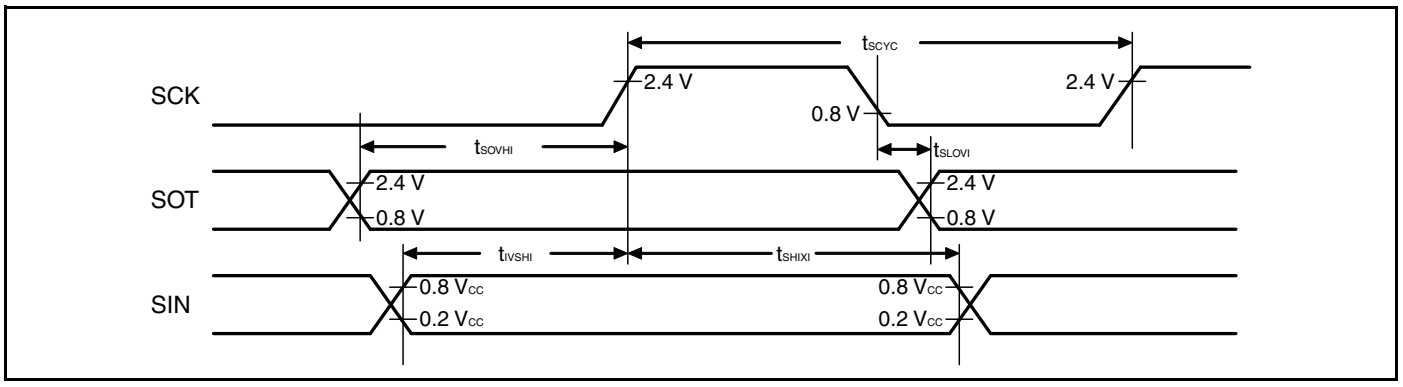
(V_{CC} = 5.0 V±10%, V_{SS} = 0.0 V, T_A = -40°C to +85°C)

Parameter	Symbol	Pin name	Condition	Value		Unit
				Min	Max	
Serial clock cycle time	t_{SCYC}	SCK	Internal clock operation output pin: C_L = 80 pF+1 TTL	5 t_{MCLK}*3	—	ns
SCK ↓→ SOT delay time	t_{SLOVI}	SCK, SOT		-95	+95	ns
Valid SIN → SCK ↑	t_{IVSHI}	SCK, SIN		t_{MCLK}*3+190	—	ns
SCK ↑→ valid SIN hold time	t_{SHIXI}	SCK, SIN		0	—	ns
SOT → SCK ↑ delay time	t_{SOVHI}	SCK, SOT		—	4 t_{MCLK}*3	ns

*1:There is a function used to choose whether the sampling of reception data is performed at a rising edge or a falling edge of the serial clock.

*2: The serial clock delay function is a function that delays the output signal of the serial clock for half clock.

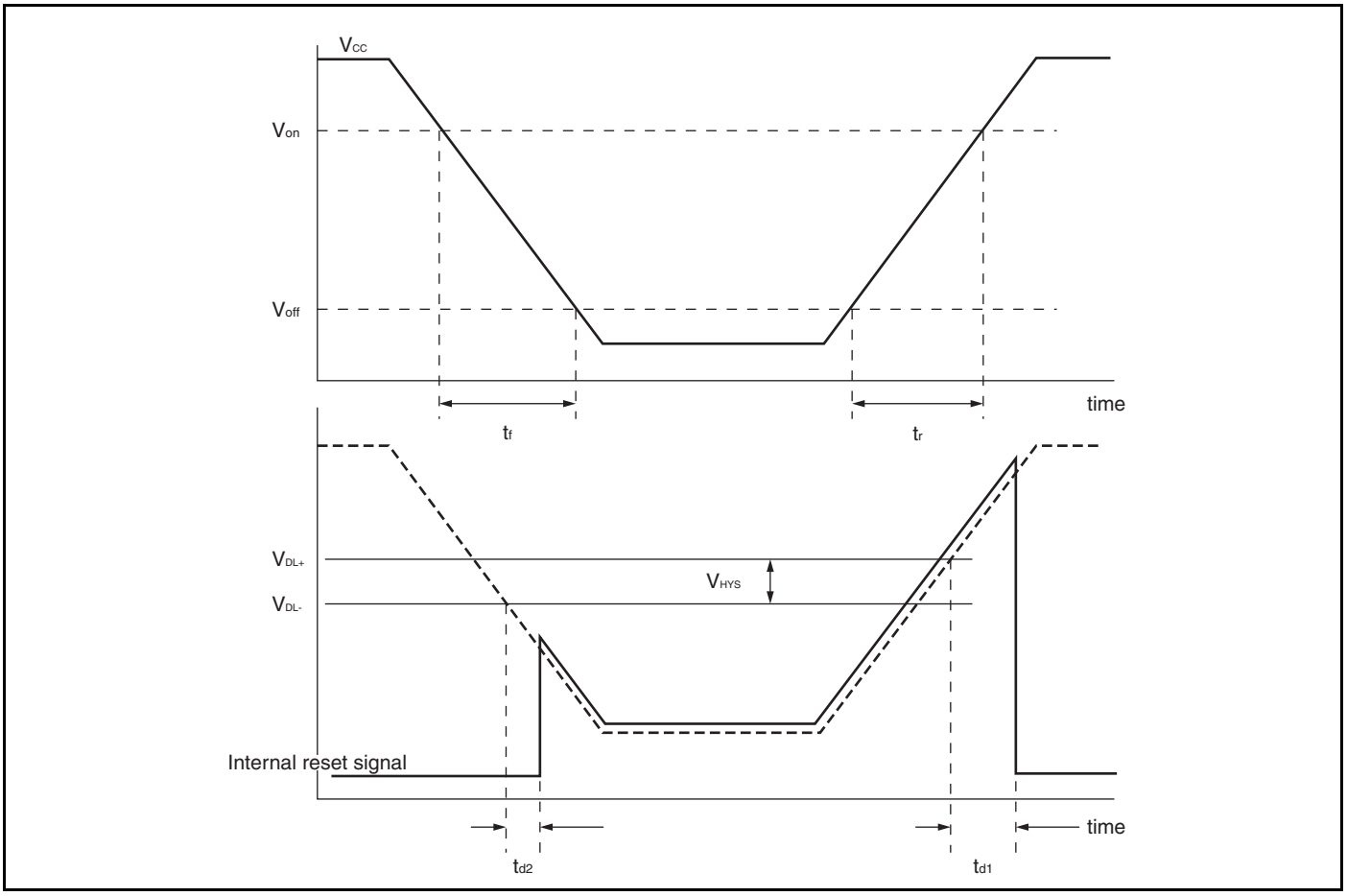
*3: See “13.4.2. Source Clock/Machine Clock” for t_{MCLK}.



13.4.7 Low-voltage Detection

(V_{SS} = 0.0 V, T_A = -40°C to +85°C)

Parameter	Symbol	Value			Unit	Remarks
		Min	Typ	Max		
Release voltage	V_{DL+}	2.52	2.7	2.88	V	At power supply rise
Detection voltage	V_{DL-}	2.42	2.6	2.78	V	At power supply fall
Hysteresis width	V_{HYS}	70	100	—	mV	
Power supply start voltage	V_{off}	—	—	2.3	V	
Power supply end voltage	V_{on}	4.9	—	—	V	
Power supply voltage change time (at power supply rise)	t_r	1	—	—	µs	Slope of power supply that the reset release signal generates
		—	3000	—	µs	Slope of power supply that the reset release signal generates within the rating (V_{DL+})
Power supply voltage change time (at power supply fall)	t_f	300	—	—	µs	Slope of power supply that the reset detection signal generates
		—	300	—	µs	Slope of power supply that the reset detection signal generates within the rating (V_{DL-})
Reset release delay time	t_{d1}	—	—	300	µs	
Reset detection delay time	t_{d2}	—	—	20	µs	


V_{CC}
V_{on}
V_{off}
time
t_f
t_r
V_{DL+}
V_{DL-}
V_{HYS}
Internal reset signal
time
t_{d2}
t_{d1}

13.5 A/D Converter

13.5.1 A/D Converter Electrical Characteristics

(V_{CC} = 4.0 V to 5.5 V, V_{SS} = 0.0 V, T_A = -40°C to +85°C)

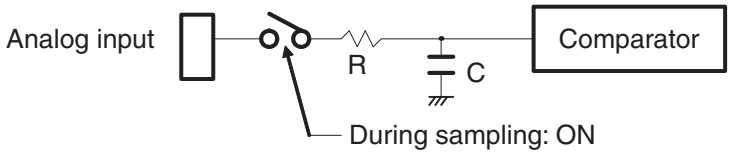
Parameter	Symbol	Value			Unit	Remarks
		Min	Typ	Max		
Resolution	—	—	—	10	bit	
Total error		-3	—	+3	LSB	
Linearity error		-2.5	—	+2.5	LSB	
Differential linear error		-1.9	—	+1.9	LSB	
Zero transition voltage	V_{OT}	V_{SS}-1.5 LSB	V_{SS}+0.5 LSB	V_{SS}+2.5 LSB	V	
Full-scale transition voltage	V_{FST}	V_{CC}-4.5 LSB	V_{CC}-2 LSB	V_{CC}+0.5 LSB	V	
Compare time	—	0.9	—	16500	µs	4.5 V ≤ V_{CC} ≤ 5.5 V
		1.8	—	16500	µs	4.0 V≤ V_{CC} < 4.5 V
Sampling time	—	0.6	—	∞	µs	4.5 V ≤ V_{CC} ≤ 5.5 V, with external impedance < 5.4 kΩ
		1.2	—	∞	µs	4.0 V ≤ V_{CC} ≤ 4.5 V, with external impedance < 2.4 kΩ
Analog input current	I_{AIN}	-0.3	—	+0.3	µA	
Analog input voltage	V_{AIN}	V_{SS}	—	V_{CC}	V	

13.5.2 Notes on Using the A/D Converter

External impedance of analog input and its sampling time

The A/D converter has a sample and hold circuit. If the external impedance is too high to keep sufficient sampling time, the analog voltage charged to the capacitor of the internal sample and hold circuit is insufficient, adversely affecting A/D conversion precision. Therefore, to satisfy the A/D conversion precision standard, considering the relationship between the external impedance and minimum sampling time, either adjust the register value and operating frequency or decrease the external impedance so that the sampling time is longer than the minimum value. In addition, if sufficient sampling time cannot be secured, connect a capacitor of about 0.1 µF to the analog input pin.

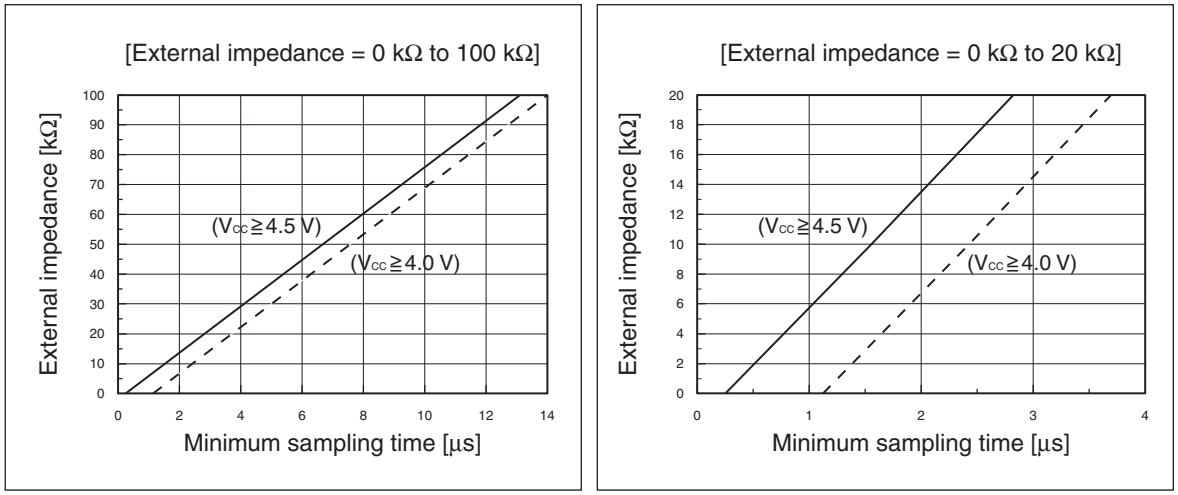
Analog input equivalent circuit



$4.5\ V \leqq V_{CC} \leqq 5.5\ V$: R ≈ 1.95 kΩ (Max), C ≈ 17 pF (Max)
$4.0\ V \leqq V_{CC} < 4.5\ V$: R ≈ 8.98 kΩ (Max), C ≈ 17 pF (Max)

Note: The values are reference values.

Relationship between external impedance and minimum sampling time



A/D conversion error

As $|V_{CC}–V_{SS}|$ decreases, the A/D conversion error increases proportionately.

13.5.3 Definitions of A/D Converter Terms

Resolution

It indicates the level of analog variation that can be distinguished by the A/D converter.
When the number of bits is 10, analog voltage can be divided into 2^{10} = 1024.

Linearity error (unit: LSB)

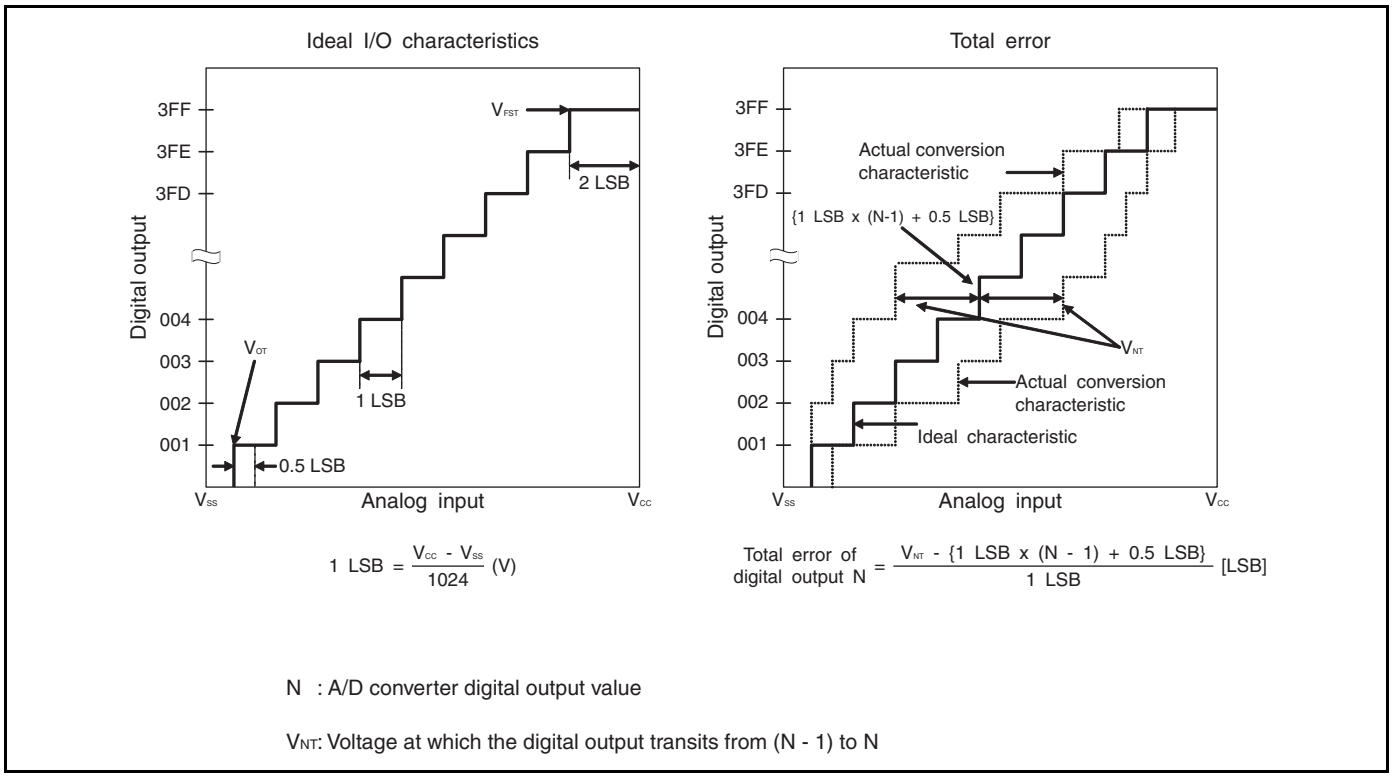
It indicates how much an actual conversion value deviates from the straight line connecting the zero transition point ("00 0000 0000" ← → "00 0000 0001") of a device to the full-scale transition point ("11 1111 1111" ← → "11 1111 1110") of the same device.

Differential linear error (unit : LSB)

It indicates how much the input voltage required to change the output code by 1 LSB deviates from an ideal value.

Total error (unit: LSB)

It indicates the difference between an actual value and a theoretical value. The error can be caused by a zero transition error, a full-scale transition errors, a linearity error, a quantum error, or noise.



$$1\ \text{LSB} = \frac{V_{CC} - V_{SS}}{1024}\ (\text{V})$$

$$\text{Total error of digital output N} = \frac{V_{NT} - \{1\ \text{LSB} \times (N - 1) + 0.5\ \text{LSB}\}}{1\ \text{LSB}}\ [\text{LSB}]$$

N : A/D converter digital output value

V_{NT}: Voltage at which the digital output transits from (N - 1) to N

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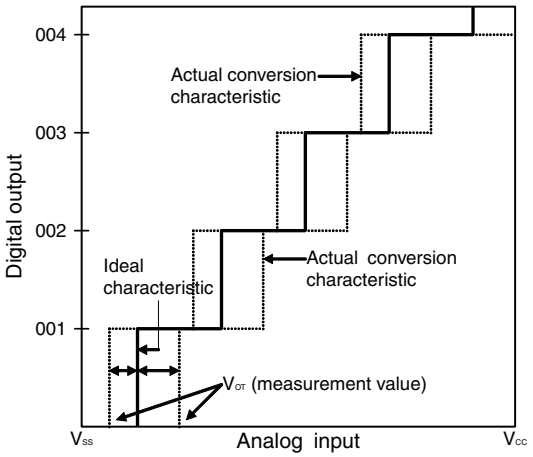
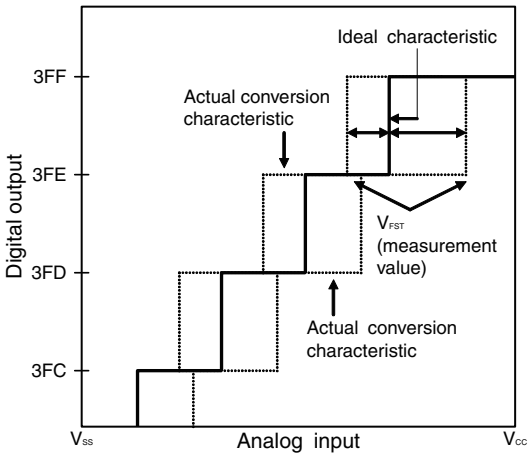
(Continued)

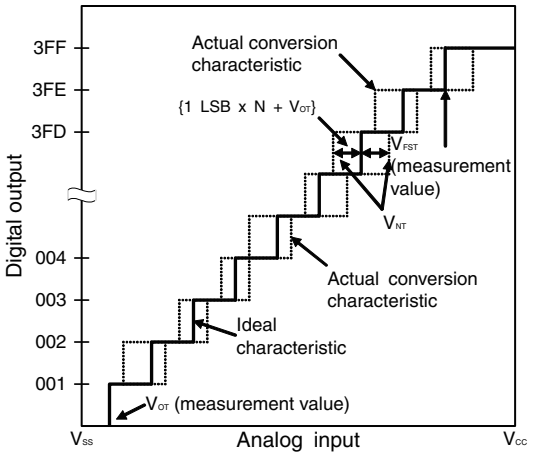
Zero transition error



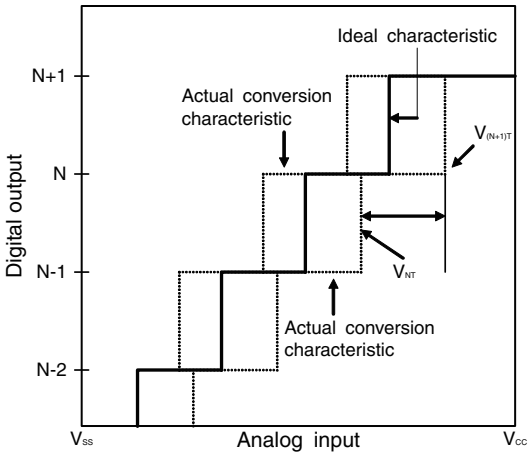
Full-scale transition error



Linearity error



Differential linearity error



$$\text{Linearity error of digital output N} = \frac{V_{NT} - \{1\ \text{LSB} \times N + V_{OT}\}}{1\ \text{LSB}}$$

$$\text{Differential linear error of digital output N} = \frac{V_{(N+1)T} - V_{NT}}{1\ \text{LSB}} - 1$$

N : A/D converter digital output value

V_{NT}: Voltage at which the digital output transits from (N - 1) to N

V_{OT} (ideal value) = V_{SS} + 0.5 LSB [V]

V_{FST} (ideal value) = V_{CC} - 2 LSB [V]

13.6 Flash Memory Program/Erase Characteristics

Parameter	Value			Unit	Remarks
	Min	Typ	Max		
Chip erase time	—	1*1	15*2	s	00_H programming time prior to erasure is excluded.
Byte programming time	—	32	3600	µs	System-level overhead is excluded.
Erase/program voltage	9.5	10	10.5	V	The erase/program voltage must be applied to the PF2 pin in erase/program.
Current drawn on PF2	—	—	5.0	mA	Current consumption of PF2 pin during flash memory program/erase
Erase/program cycle	—	100000	—	cycle	
Power supply voltage at erase/program	3.0	—	5.5	V	
Flash memory data retention time	20*3	—	—	year	Average T_A = +85°C

*1: T_A = +25°C, V_{CC} = 5.0 V, 100000 cycles

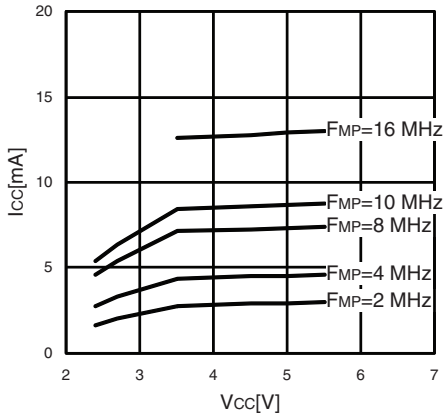
*2: T_A = +85°C, V_{CC} = 4.5 V, 100000 cycles

*3: This value is converted from the result of a technology reliability assessment. (The value is converted from the result of a high temperature accelerated test by using the Arrhenius equation with the average temperature being +85°C) .

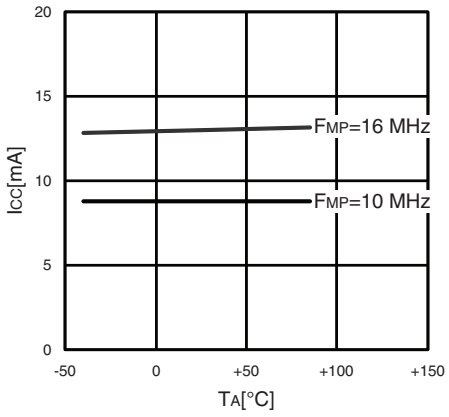
14. Sample Electrical Characteristics

Power supply current•temperature

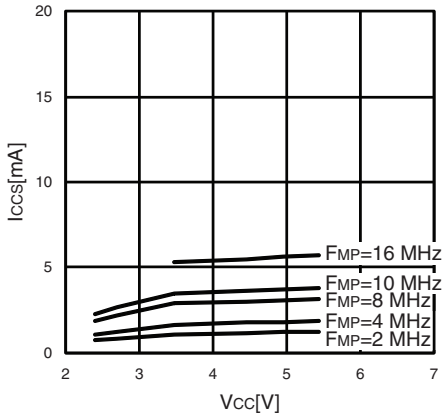
ICC - VCC
TA=+25°C, FMP=2, 4, 8, 10, 16 MHz (divided by 2)
Main clock mode with the external clock operating



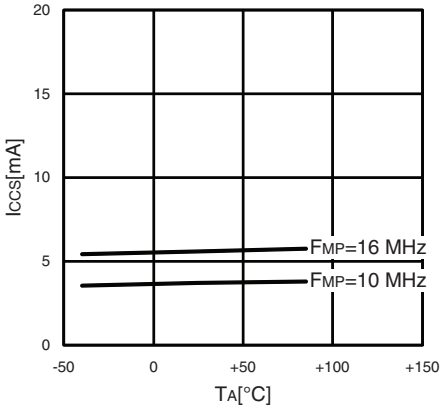
ICC - TA
VCC=5.5 V, FMP=10, 16 MHz (divided by 2)
Main clock mode with the external clock operating



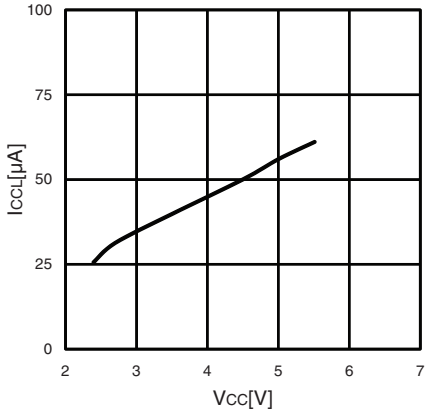
ICCS - VCC
TA=+25°C, FMP=2, 4, 8, 10, 16 MHz (divided by 2)
Main sleep mode with the external clock operating



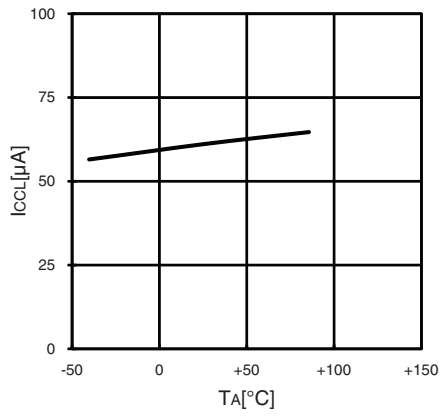
ICCS - TA
VCC=5.5 V, FMP=10, 16 MHz (divided by 2)
Main sleep mode with the external clock operating



ICCL - VCC
TA=+25°C, FMPL=16 kHz (divided by 2)
Subclock mode with the external clock operating



ICCL - TA
VCC=5.5 V, FMPL=16 kHz (divided by 2)
Subclock mode with the external clock operating



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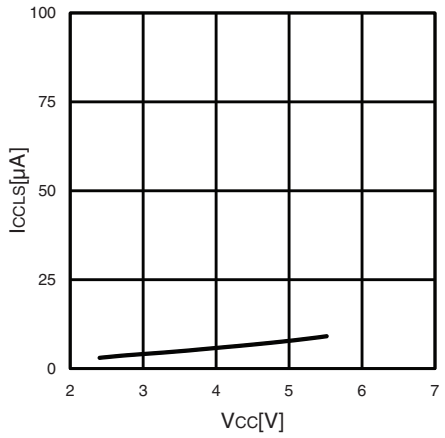
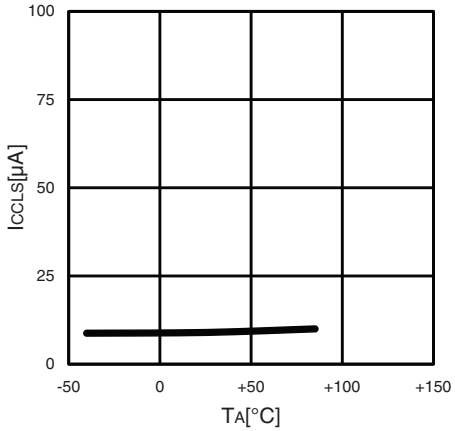
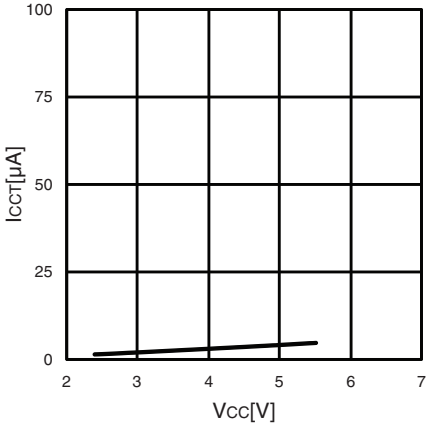
I_{CCLS} - V_{CC}
T_A=+25°C, F_{MPL}=16 kHz (divided by 2)
Subsleep mode with the external clock operating



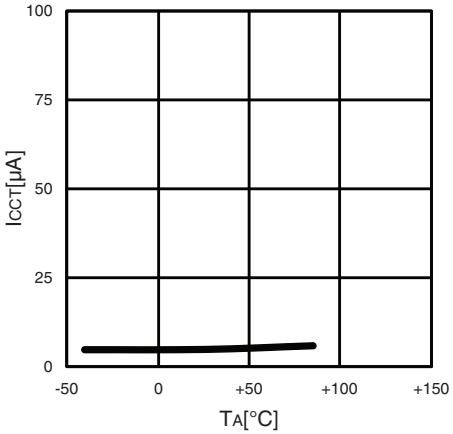
I_{CCLS} - T_A
V_{CC}=5.5 V, F_{MPL}=16 kHz (divided by 2)
Subsleep mode with the external clock operating



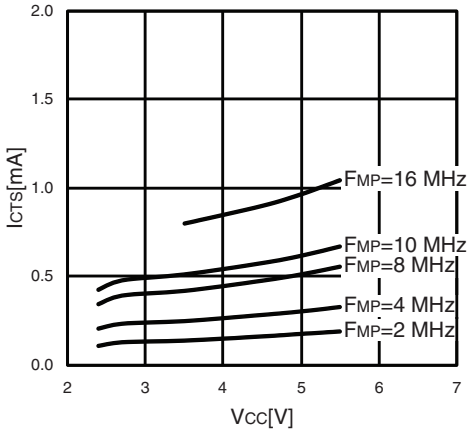
I_{CCT} - V_{CC}
T_A=+25°C, F_{MPL}=16 kHz (divided by 2)
Clock mode with the external clock operating



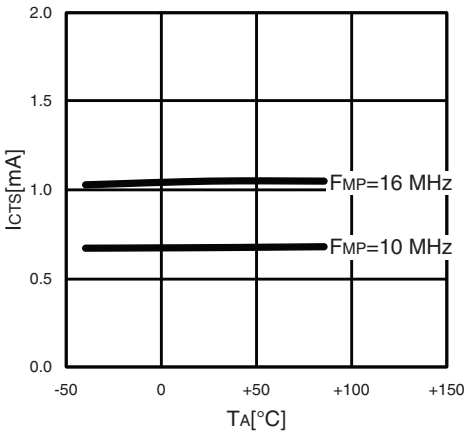
I_{CCT} - T_A
V=5.5 V, F_{MPL}=16 kHz (divided by 2)
Clock mode with the external clock operating



I_{CTS} - V_{CC}
T_A=+25°C, F_{MP}=2, 4, 8, 10, 16 MHz (divided by 2)
Timebase timer mode with the external clock operating



I_{CTS} - T_A
V=5.5 V, F_{MP}=10, 16 MHz (divided by 2)
Timebase timer mode with the external clock operating



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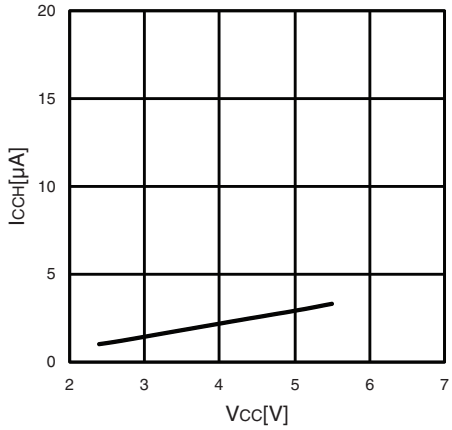
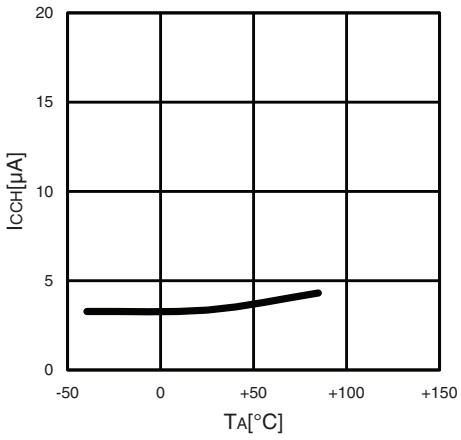
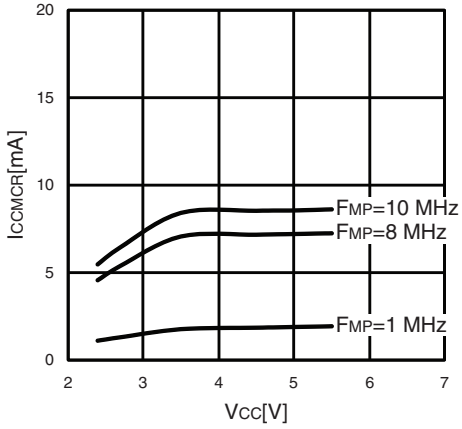
ICCH - VCC
TA=+25°C, FMPL=(stop)
Substop mode wtih the external clock stopping



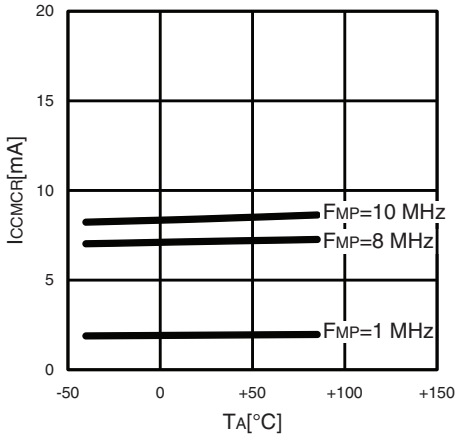
ICCH - TA
V=5.5 V, FMPL=(stop)
Substop mode with the external clock stopping



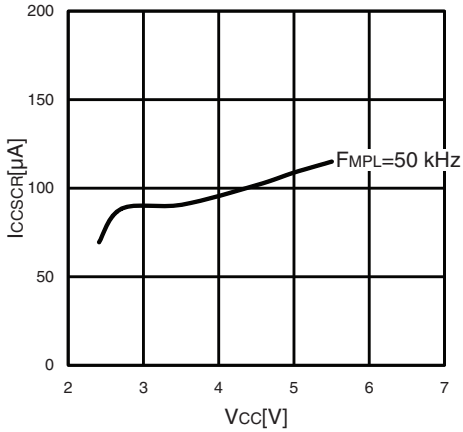
ICCMCR - VCC
TA=+25°C, FMP=1, 8, 10 MHz (no division)
Main clock mode with the internal main CR clock operating



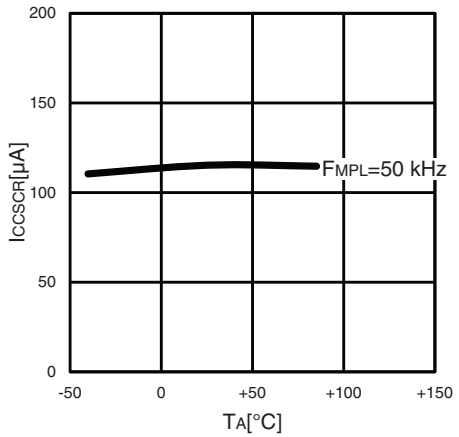
ICCMCR - TA
V=5.5 V, FMPL=1, 8, 10 MHz (no division)
Main clock mode with the internal main CR clock operating



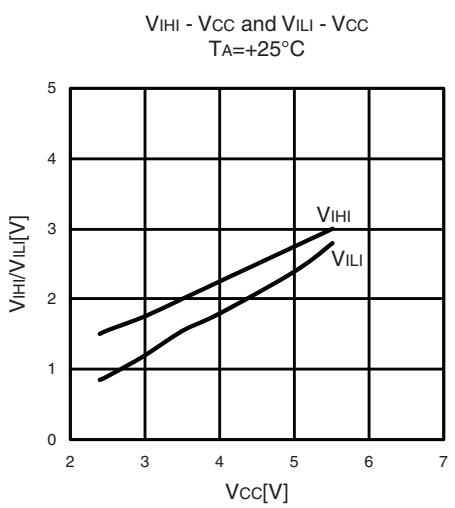
ICCSCR - VCC
TA=+25°C, FMPL=50 kHz (divided by 2)
Subclock mode with the internal sub-CR clock operating

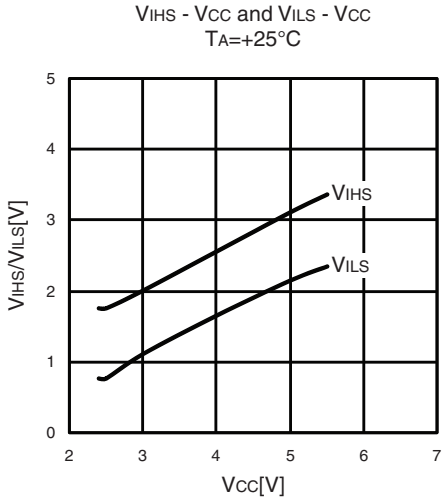


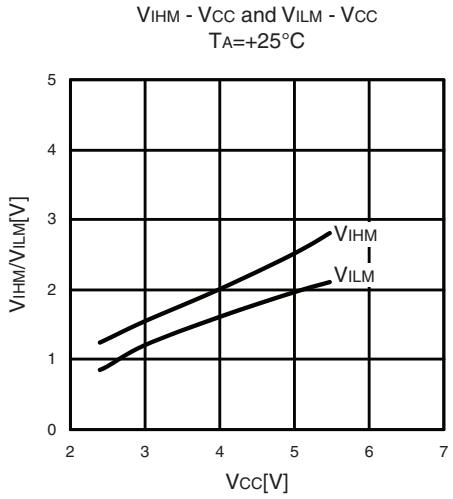
ICCSCR - TA
VCC=5.5 V, FMPL=50 kHz (divided by 2)
Subclock mode with the internal sub-CR clock operating



Input voltage

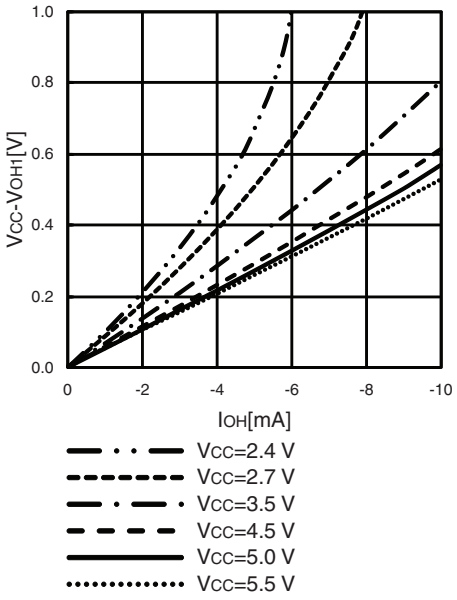




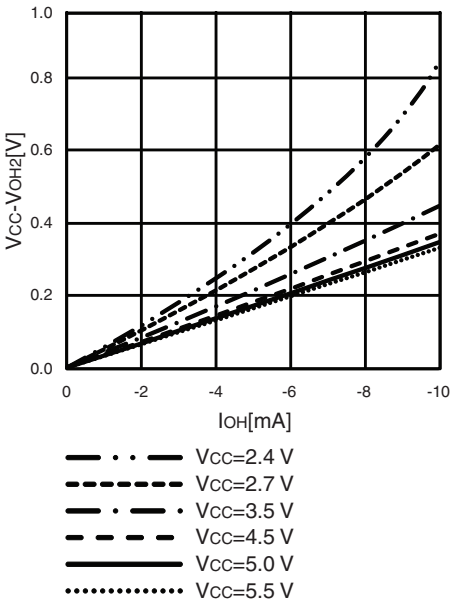


Output voltage

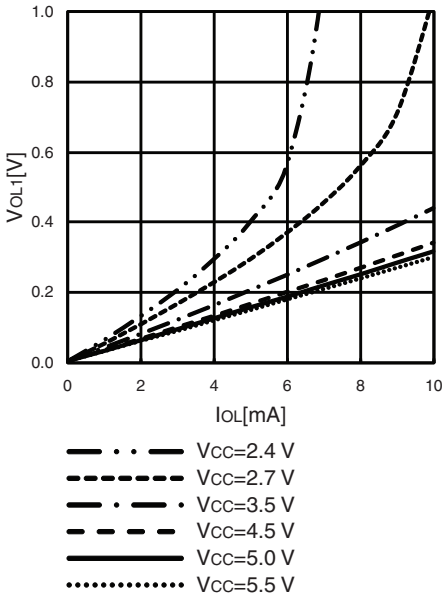
(VCC-VOH1) - IOH
TA=+25°C



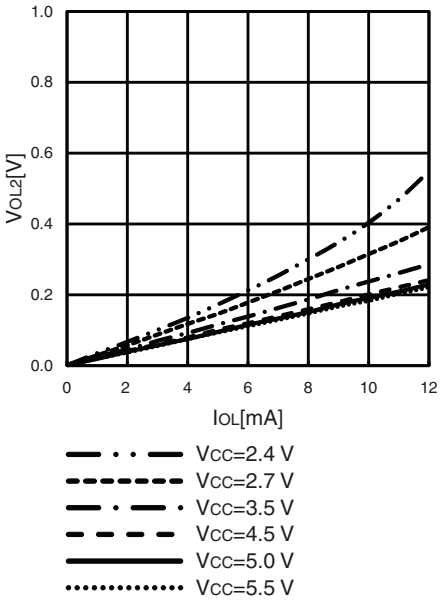
(VCC-VOH2) - IOH
TA=+25°C



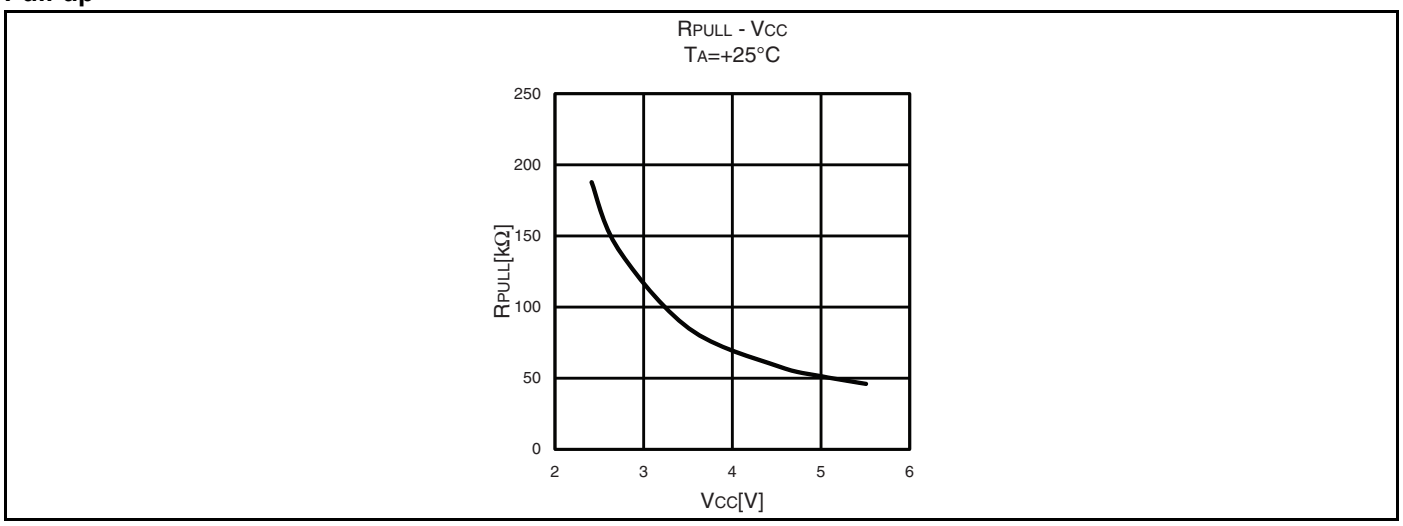
VOL1 - IOL
TA=+25°C



VOL2 - IOL
TA=+25°C



Pull-up



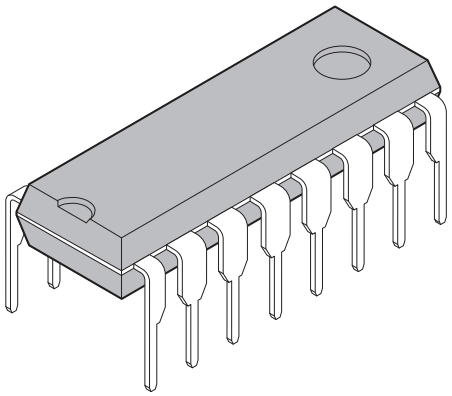
15. Mask Options

No.	Part Number	MB95F222H MB95F223H	MB95F222K MB95F223K
	Selectable/Fixed	Fixed	Fixed
1	Low-voltage detection reset • With low-voltage detection reset • Without low-voltage detection reset	Without low-voltage detection reset	With low-voltage detection reset
2	Reset • With dedicated reset input • Without dedicated reset input	With dedicated reset input	Without dedicated reset input

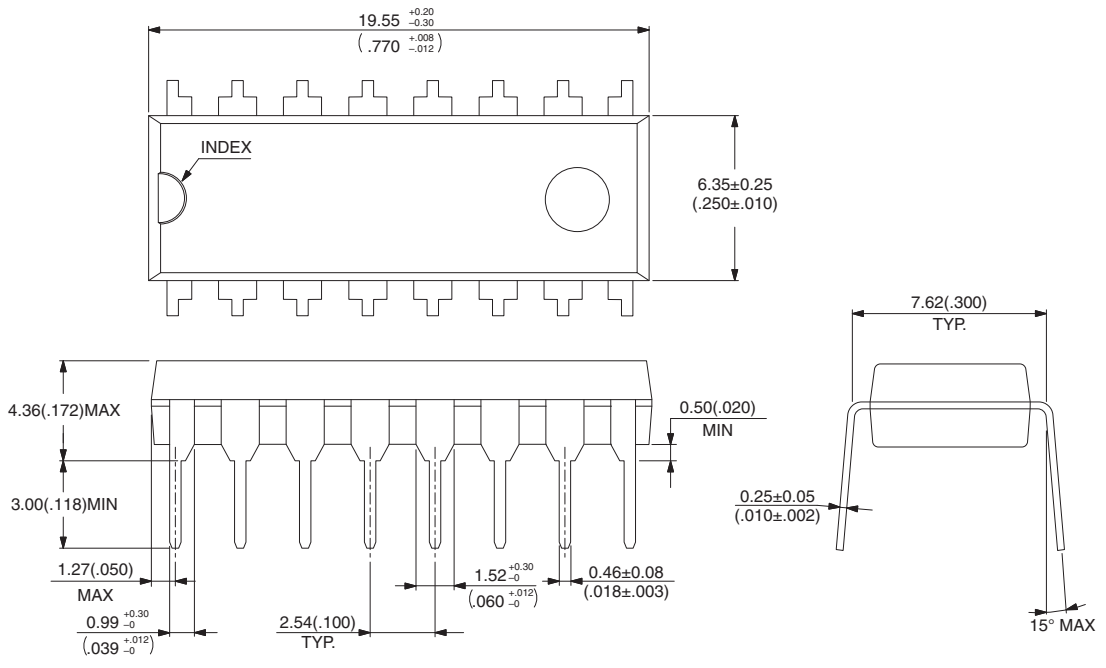
16. Ordering Information

Part Number	Package
MB95F222HPH-G-SNE2 MB95F222KPH-G-SNE2 MB95F223HPH-G-SNE2 MB95F223KPH-G-SNE2	16-pin plastic DIP (DIP-16P-M06)
MB95F222HPF-G-SNE1 MB95F222KPF-G-SNE1 MB95F223HPF-G-SNE1 MB95F223KPF-G-SNE1	16-pin plastic SOP (FPT-16P-M06)

17. Package Dimensions

16-pin plastic DIP		
 (DIP-16P-M06)	Lead pitch	2.54 mm
	Sealing method	Plastic mold

16-pin plastic DIP
(DIP-16P-M06)



Dimensions in mm (inches).
Note: The values in parentheses are reference values

(Continued)

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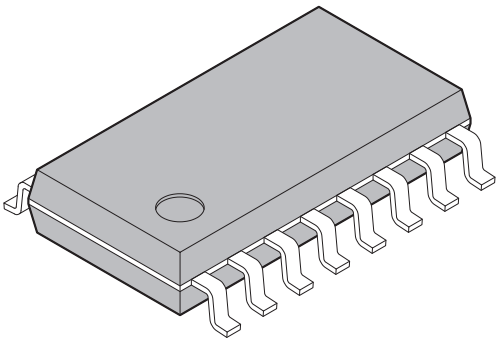
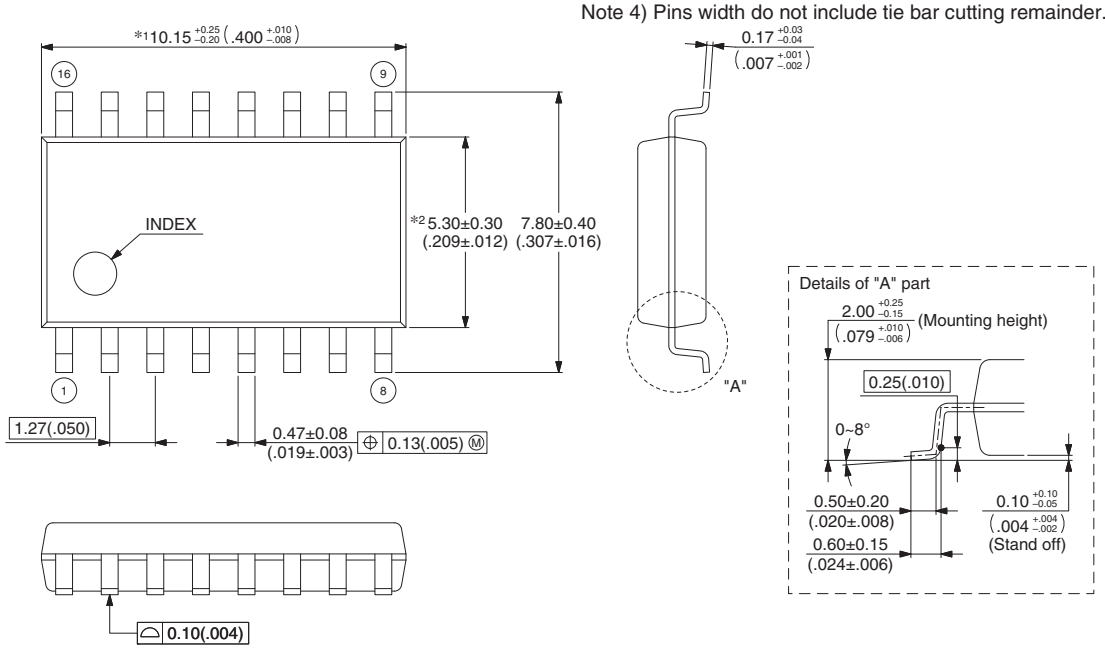
16-pin plastic SOP		
	Lead pitch	1.27 mm
	Package width × package length	5.3 × 10.15 mm
	Lead shape	Gullwing
	Sealing method	Plastic mold
	Mounting height	2.25 mm MAX
	Weight	0.20 g
(FPT-16P-M06)	Code (Reference)	P-SOP16-5.3×10.15-1.27

16-pin plastic SOP
(FPT-16P-M06)

Note 1) *1 : These dimensions include resin protrusion.
Note 2) *2 : These dimensions do not include resin protrusion.
Note 3) Pins width and pins thickness include plating thickness.
Note 4) Pins width do not include tie bar cutting remainder.



Dimensions in mm (inches).
Note: The values in parentheses are reference values.

18. Major Changes

Spansion Publication Number: DS07-12626-3E

Page	Section	Change Results
21	Electrical Characteristics 1. Absolute Maximum Ratings	Changed the characteristics of Input voltage.
24	3. DC Characteristics	Corrected the maximum value of “H” level input voltage for PF2 pin. V_{CC} + 0.3 → 10.5
		Corrected the maximum value of Open-drain output application voltage. 0.2Vcc → Vss + 5.5
26		Added the footnote *3.
29	4. AC Characteristics (1) Clock Timing	Added a figure of HCLK1/HCLK2.
32	(2) Source Clock/Machine Clock	Corrected the graph of Operating voltage - Operating frequency (with the on-chip debug function). (Corrected the pitch)
33	(3) External Reset	Added and power on to the remarks column.
48	6. Flash Memory Program/ Erase Characteristics	Added the row of Current drawn on PF2.
		Corrected the minimum value of Power supply voltage at erase/program. 4.5 → 3.0

NOTE: Please see “Document History” about later revised information.

Document History

Document Title: MB95220H Series F^{2}MC-8FX 8-bit Microcontroller Document Number: 002-07513				
Revision	**ECN**	**Orig. of Change**	**Submission Date**	**Description of Change**
**	—	AKIH	07/26/2010	Migrated to Cypress and assigned document number 002-07513. No change to document contents or format.
*A	5198887	AKIH	03/31/2016	Updated to Cypress format.

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