



**THE DATASHEET OF
DAC8311IDCKR**



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4 Revision History

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

Changes from Revision B (May 2013) to Revision C

Page

- Added ESD Ratings table, Feature Description section, Device Functional Modes, Application and Implementation section, Power Supply Recommendations section, Layout section, Device and Documentation Support section, and Mechanical, Packaging, and Orderable Information section..... **1**

Changes from Revision A (August, 2011) to Revision B

Page

- Changed all 1.8V to 2.0V throughout data sheet..... **1**
- Deleted 1.8-V Typical Characteristics section..... **9**
- Changed X-axis for Figure 35..... **13**
- Changed X-axis for Figure 36..... **13**

Changes from Original (August, 2008) to Revision A

Page

- Changed specifications and test conditions for input low voltage parameter..... **6**
- Changed specifications and test conditions for input high voltage parameter..... **6**

5 Device Comparison

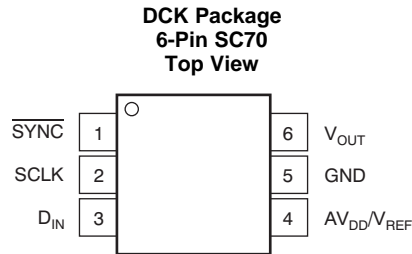
Table 1. Related Devices

RELATED DEVICES	16-BIT	14-BIT	12-BIT	10-BIT	8-BIT
Pin and Function Compatible	DAC8411	DAC8311	DAC7311	DAC6311	DAC5311

Table 2. Package Information

PRODUCT	MAXIMUM RELATIVE ACCURACY (LSB)	MAXIMUM DIFFERENTIAL NONLINEARITY (LSB)
DAC8411	±8	±2
DAC8311	±4	±1

6 Pin Configuration and Functions



Pin Functions

PIN		I/O	DESCRIPTION
NAME	NO.		
AV _{DD} /V _{REF}	4	I	Power Supply Input, +2 V to +5.5 V.
D _{IN}	3	I	Serial Data Input. Data is clocked into the 24-bit (DAC8411) or 16-bit (DAC8311) input shift register on the falling edge of the serial clock input.
GND	5	—	Ground reference point for all circuitry on the part.
SCLK	2	I	Serial Clock Input. Data can be transferred at rates up to 50 MHz.
$\overline{\text{SYNC}}$	1	I	Level-triggered control input (active low). This is the frame synchronization signal for the input data. When $\overline{\text{SYNC}}$ goes low, it enables the input shift register and data are transferred in on the falling edges of the following clocks. The DAC is updated following the 24th (DAC8411) or 16th (DAC8311) clock cycle, unless $\overline{\text{SYNC}}$ is taken high before this edge, in which case the rising edge of $\overline{\text{SYNC}}$ acts as an interrupt and the write sequence is ignored by the DAC8x11. Refer to the DAC8311 and DAC8411 SYNC Interrupt sections for more details.
V _{OUT}	6	O	Analog output voltage from DAC. The output amplifier has rail-to-rail operation.

Timing Requirements: 16-Bit (continued)

All specifications at -40°C to 125°C , and $\text{AV}_{\text{DD}} = 2\text{ V}$ to 5.5 V , unless otherwise noted.^{(1) (2)}

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
t_8 Minimum $\overline{\text{SYNC}}$ high time	$\text{AV}_{\text{DD}} = 2\text{ V}$ to 3.6 V	50			ns
	$\text{AV}_{\text{DD}} = 3.6\text{ V}$ to 5.5 V	20			
t_9 24th SCLK falling edge to $\overline{\text{SYNC}}$ falling edge	$\text{AV}_{\text{DD}} = 2\text{ V}$ to 3.6 V	100			ns
	$\text{AV}_{\text{DD}} = 3.6\text{ V}$ to 5.5 V	100			
t_{10} $\overline{\text{SYNC}}$ rising edge to 24th SCLK falling edge (for successful SYNC interrupt)	$\text{AV}_{\text{DD}} = 2\text{ V}$ to 3.6 V	15			ns
	$\text{AV}_{\text{DD}} = 3.6\text{ V}$ to 5.5 V	15			

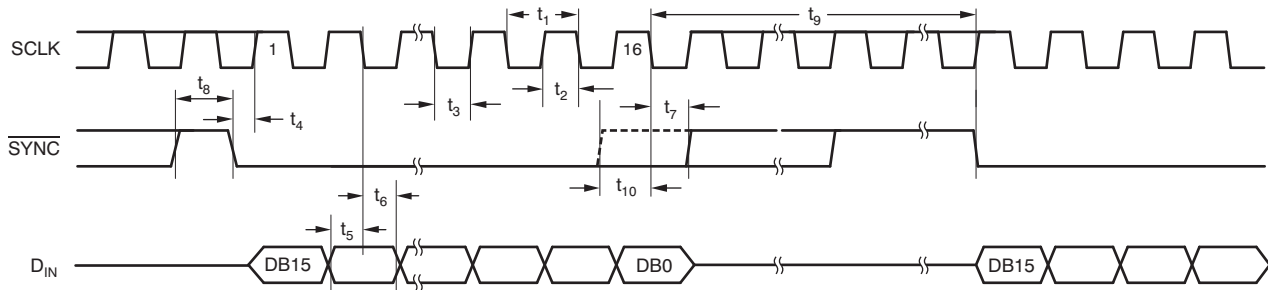


Figure 1. Serial Write Operation: 14-Bit (DAC8311)

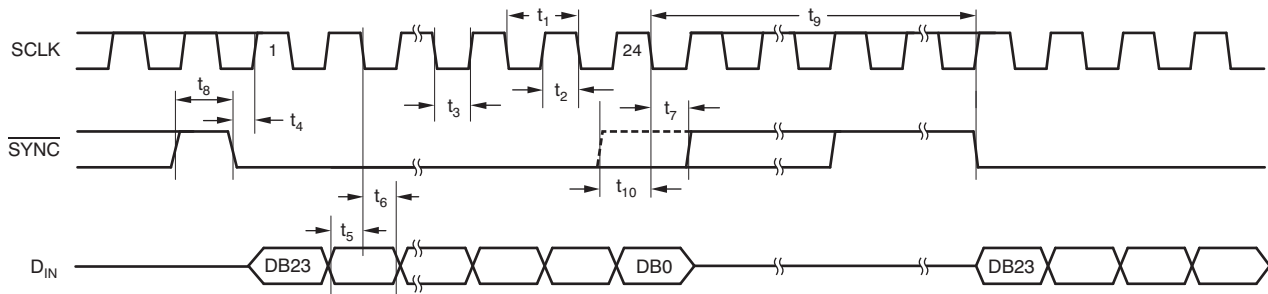


Figure 2. Serial Write Operation: 16-Bit (DAC8411)

7.8 Typical Characteristics

7.8.1 Typical Characteristics: $AV_{DD} = 5\text{ V}$

at $T_A = 25^\circ\text{C}$, $AV_{DD} = 5\text{ V}$, and DAC loaded with mid-scale code, unless otherwise noted.

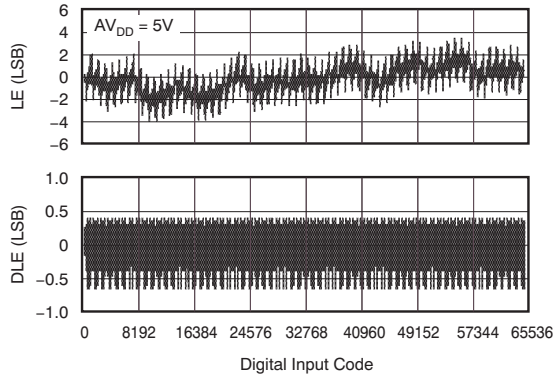


Figure 3. DAC8411 16-Bit Linearity Error and Differential Linearity Error vs Code (-40°C)

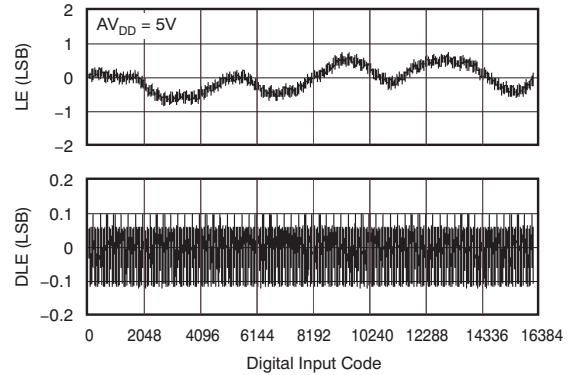


Figure 4. DAC8311 14-Bit Linearity Error and Differential Linearity Error vs Code (-40°C)

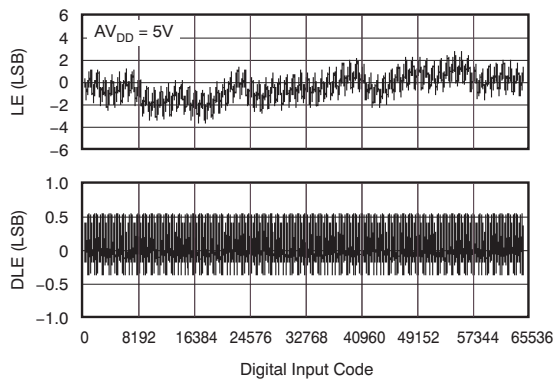


Figure 5. DAC8411 16-Bit Linearity Error and Differential Linearity Error vs Code (25°C)

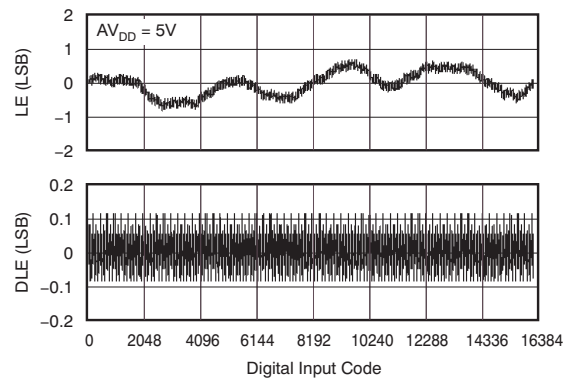


Figure 6. DAC8311 14-Bit Linearity Error and Differential Linearity Error vs Code (25°C)

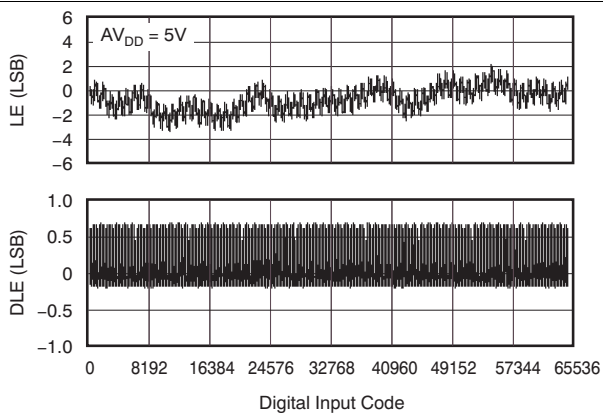


Figure 7. DAC8411 16-Bit Linearity Error and Differential Linearity Error vs Code (125°C)

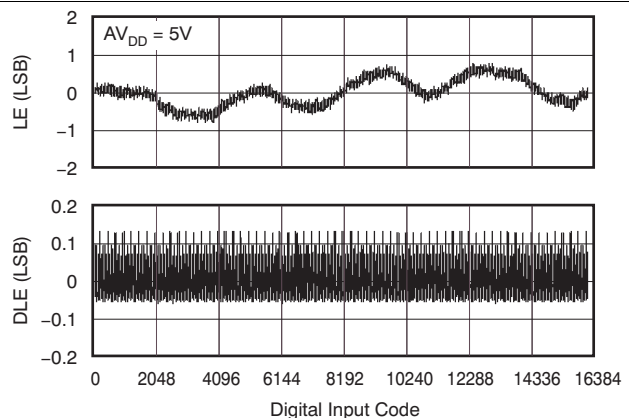


Figure 8. DAC8311 14-Bit Linearity Error and Differential Linearity Error vs Code (125°C)

Typical Characteristics: $AV_{DD} = 5\text{ V}$ (continued)

at $T_A = 25^\circ\text{C}$, $AV_{DD} = 5\text{ V}$, and DAC loaded with mid-scale code, unless otherwise noted.

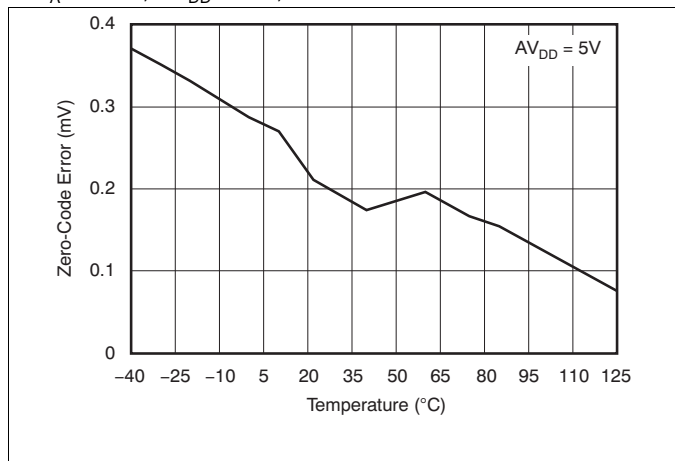


Figure 9. Zero-Code Error vs Temperature

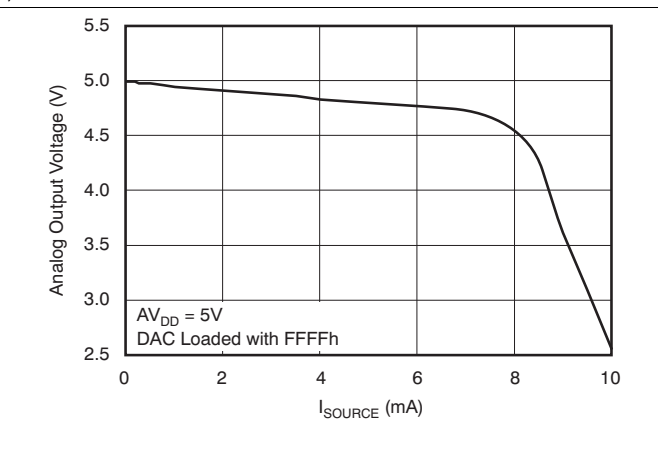


Figure 10. Source Current at Positive Rail

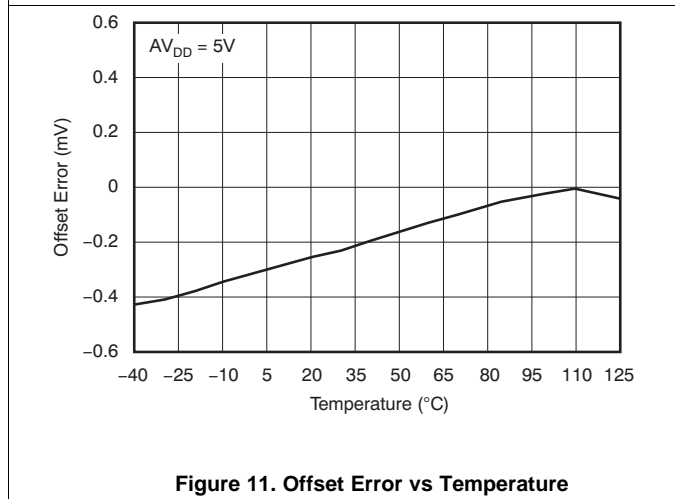


Figure 11. Offset Error vs Temperature

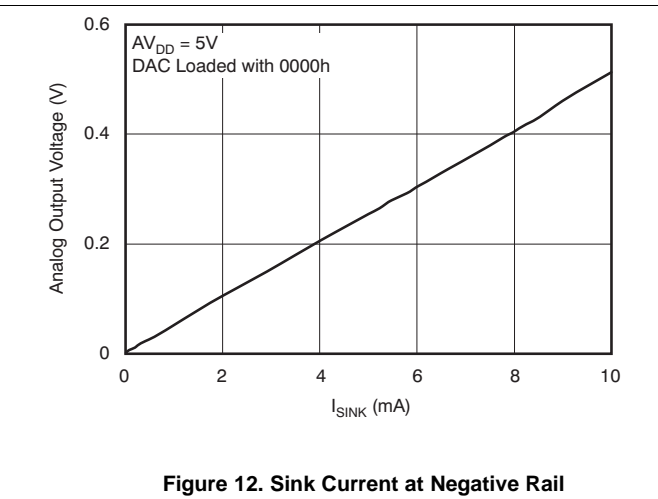


Figure 12. Sink Current at Negative Rail

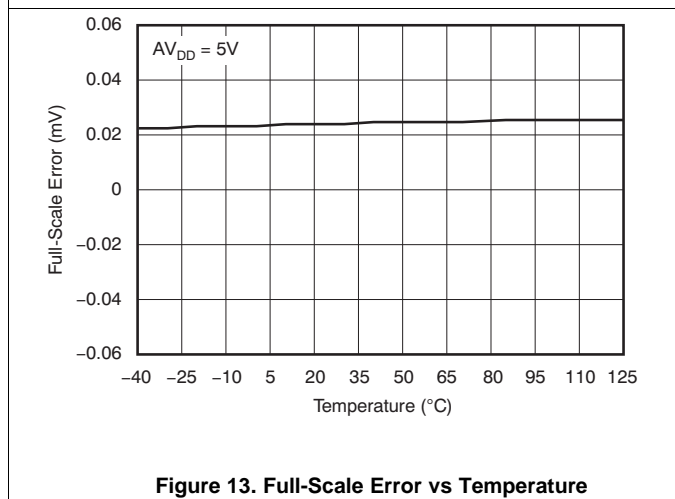


Figure 13. Full-Scale Error vs Temperature

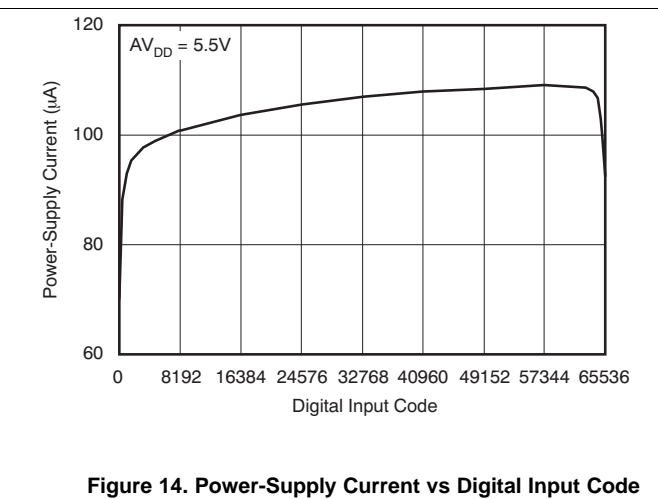


Figure 14. Power-Supply Current vs Digital Input Code

Typical Characteristics: AV_{DD} = 5 V (continued)

at T_A = 25°C, AV_{DD} = 5 V, and DAC loaded with mid-scale code, unless otherwise noted.

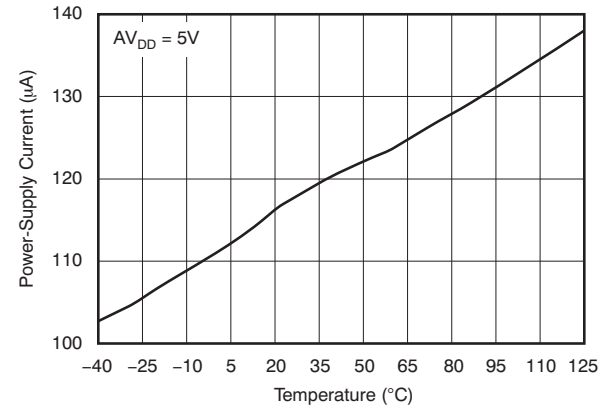


Figure 15. Power-Supply Current vs Temperature

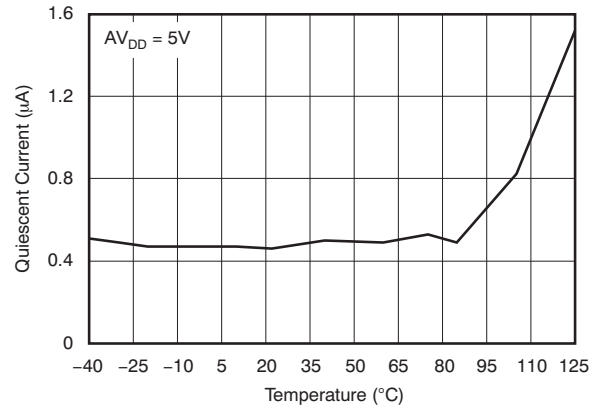


Figure 16. Power-Down Current vs Temperature

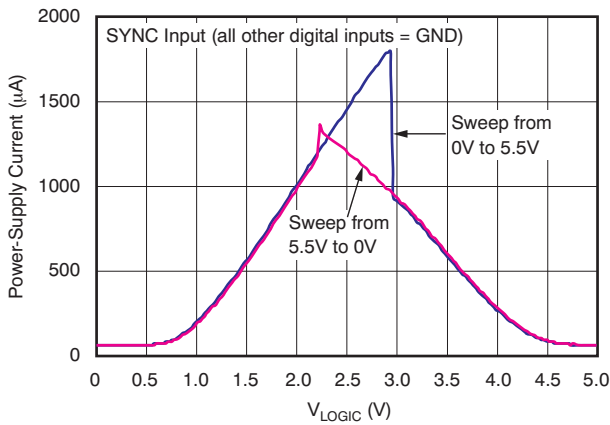


Figure 17. Power-Supply Current vs Logic Input Voltage

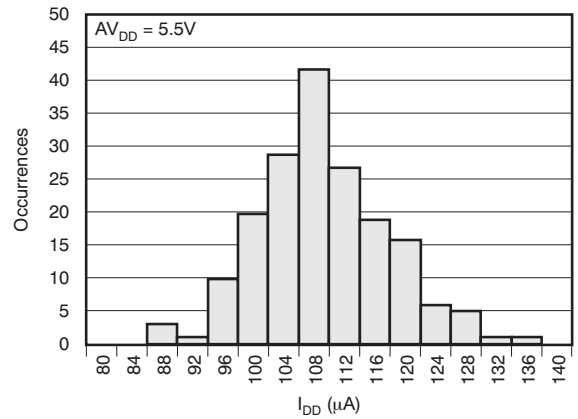


Figure 18. Power-Supply Current Histogram

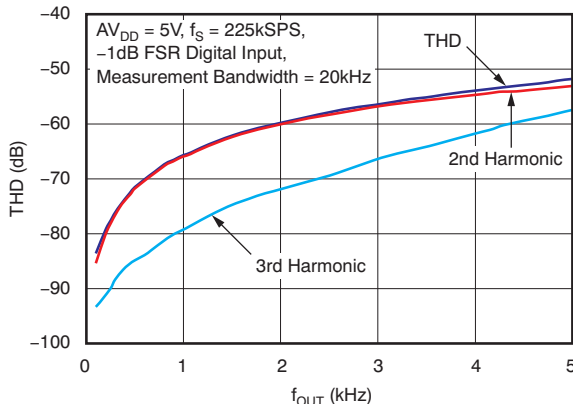


Figure 19. Total Harmonic Distortion vs Output Frequency

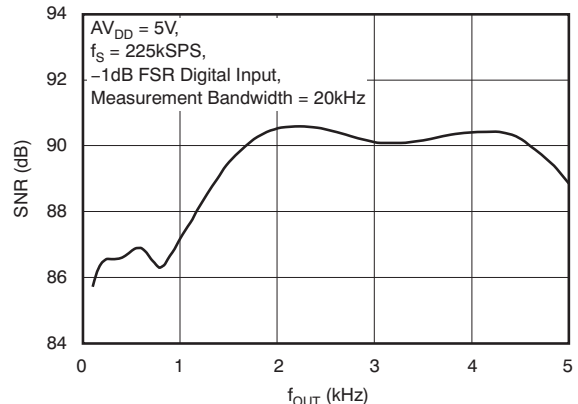


Figure 20. Signal-to-Noise Ratio vs Output Frequency

Typical Characteristics: $AV_{DD} = 5 \text{ V}$ (continued)

at $T_A = 25^\circ\text{C}$, $AV_{DD} = 5 \text{ V}$, and DAC loaded with mid-scale code, unless otherwise noted.

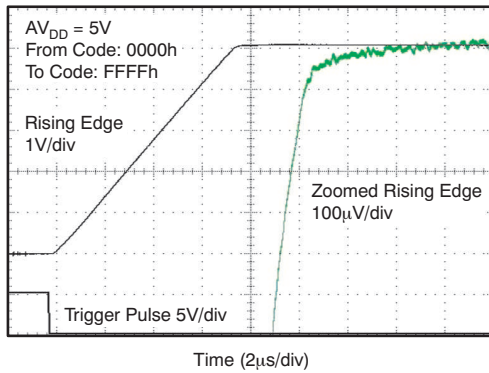


Figure 27. Full-Scale Settling Time 5-V Rising Edge

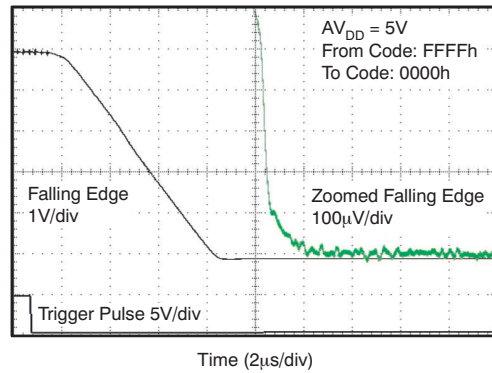


Figure 28. Full-Scale Settling Time 5-V Falling Edge

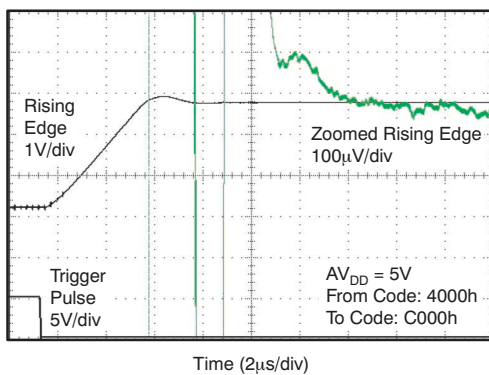


Figure 29. Half-Scale Settling Time 5-V Rising Edge

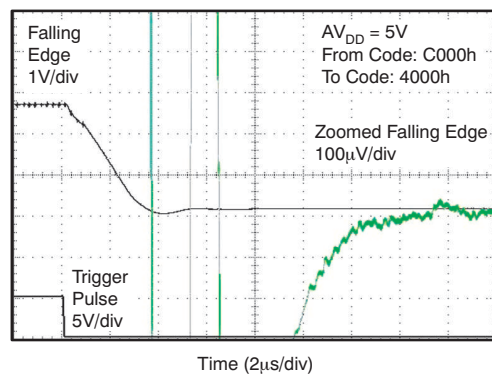


Figure 30. Half-Scale Settling Time 5-V Falling Edge

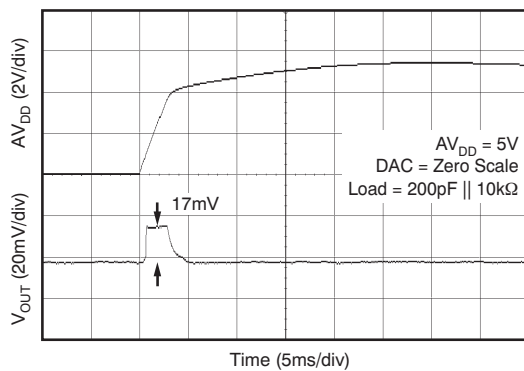


Figure 31. Power-On Reset to 0 V Power-On Glitch

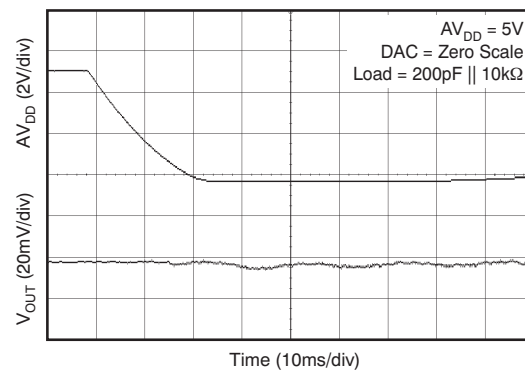


Figure 32. Power-Off Glitch

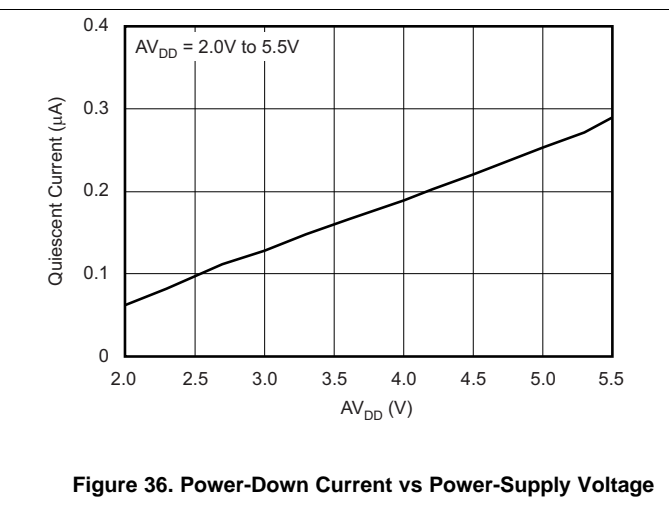
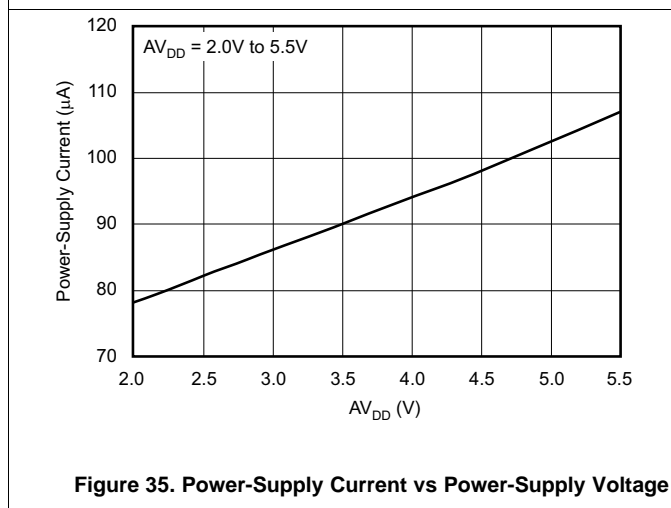
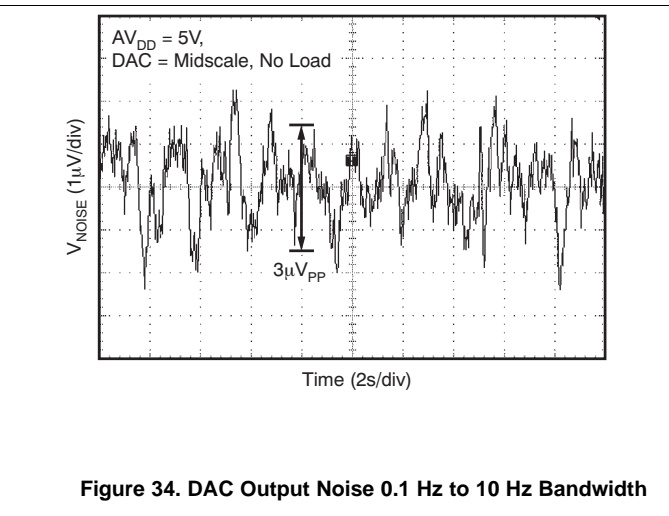
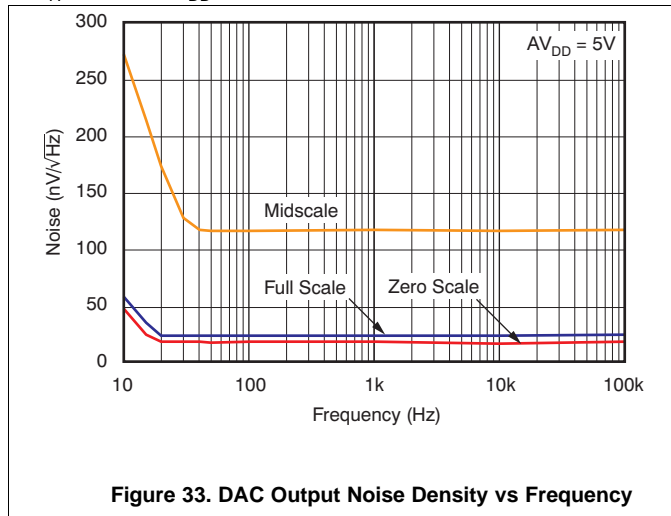
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Typical Characteristics: $AV_{DD} = 5\text{ V}$ (continued)

at $T_A = 25^\circ\text{C}$, $AV_{DD} = 5\text{ V}$, and DAC loaded with mid-scale code, unless otherwise noted.



7.8.2 Typical Characteristics: $AV_{DD} = 3.6V$

at $T_A = 25^\circ C$, and $AV_{DD} = 3.6V$, unless otherwise noted.

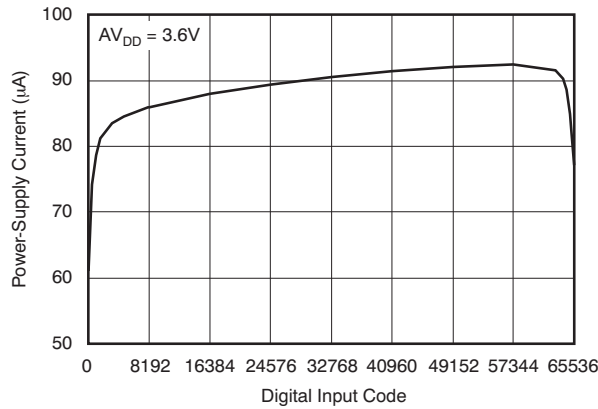


Figure 37. Power-Supply Current vs Digital Input Code

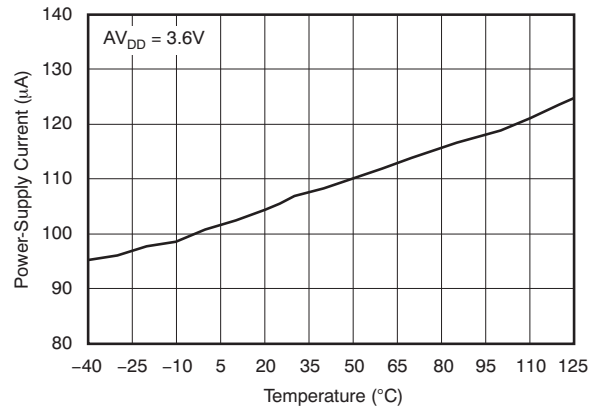


Figure 38. Power-Supply Current vs Temperature

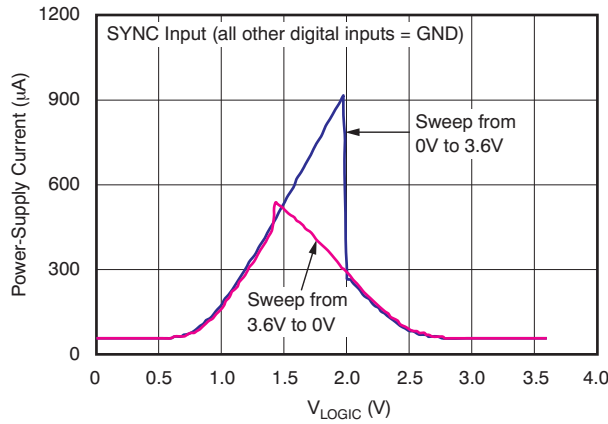


Figure 39. Power-Supply Current vs Logic Input Voltage

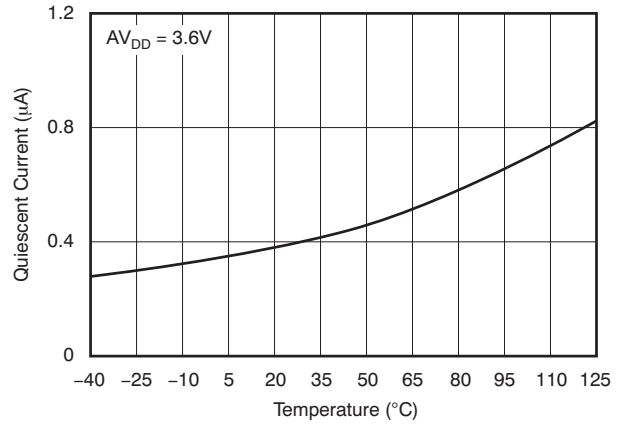


Figure 40. Power-Down Current vs Temperature

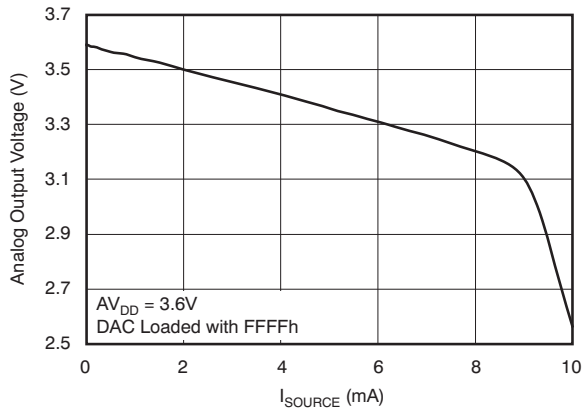


Figure 41. Source Current at Positive Rail

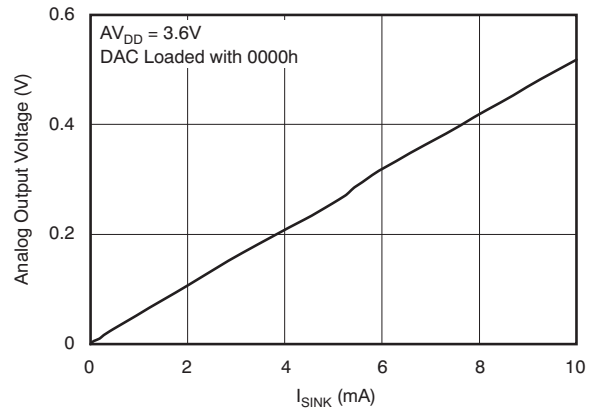
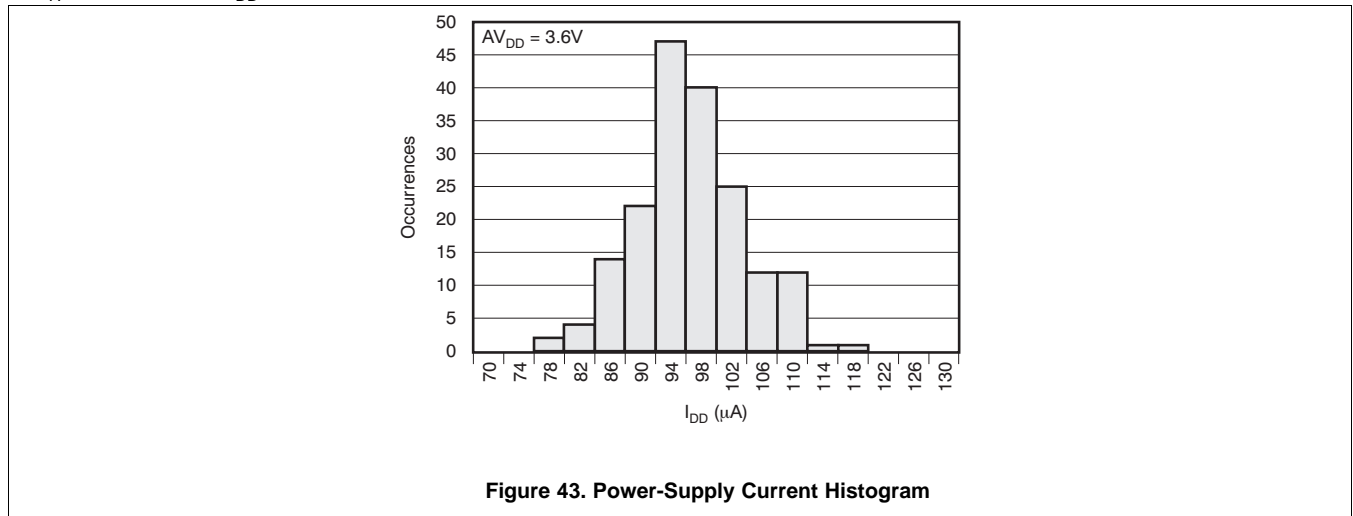


Figure 42. Sink Current at Negative Rail

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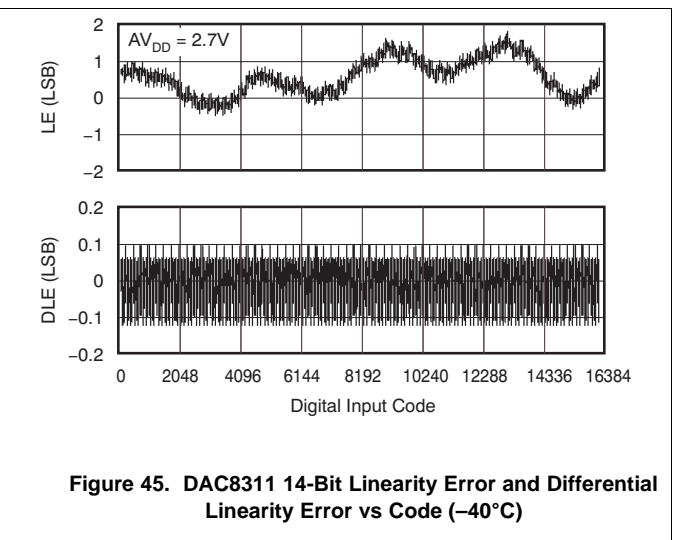
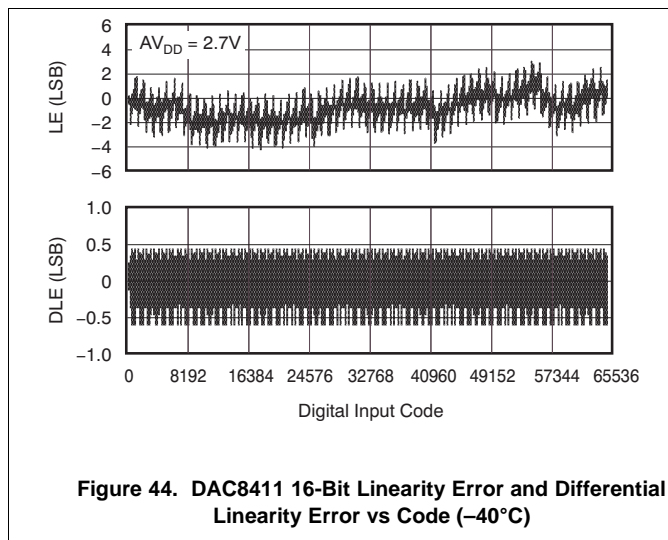
Typical Characteristics: $V_{DD} = 3.6 V$ (continued)

at $T_A = 25^\circ C$, and $V_{DD} = 3.6 V$, unless otherwise noted.



7.8.3 Typical Characteristics: $V_{DD} = 2.7 V$

at $T_A = 25^\circ C$, and $V_{DD} = 2.7 V$, unless otherwise noted.



Typical Characteristics: AV_{DD} = 2.7 V (continued)

at T_A = 25°C, and AV_{DD} = 2.7 V, unless otherwise noted.

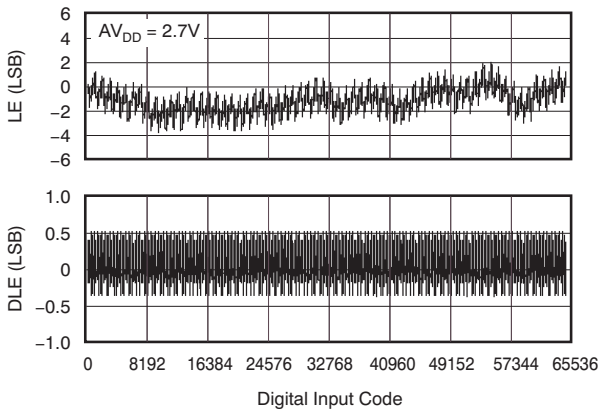


Figure 46. DAC8411 16-Bit Linearity Error and Differential Linearity Error vs Code (25°C)

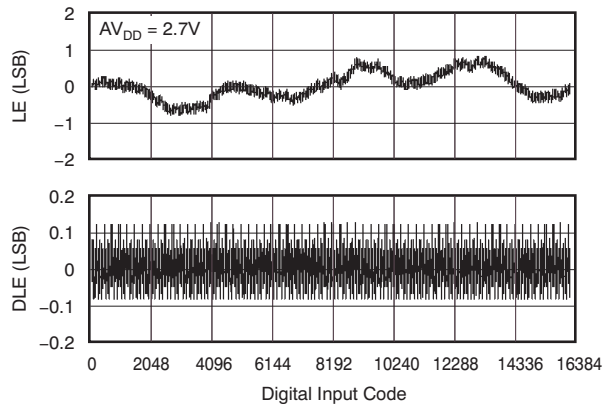


Figure 47. DAC8311 14-Bit Linearity Error and Differential Linearity Error vs Code (25°C)

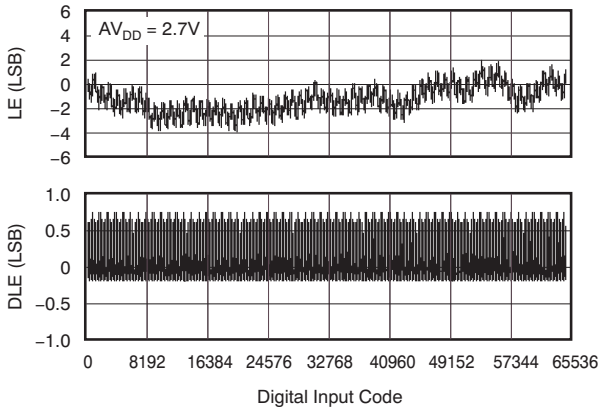


Figure 48. DAC8411 16-Bit Linearity Error and Differential Linearity Error vs Code (125°C)

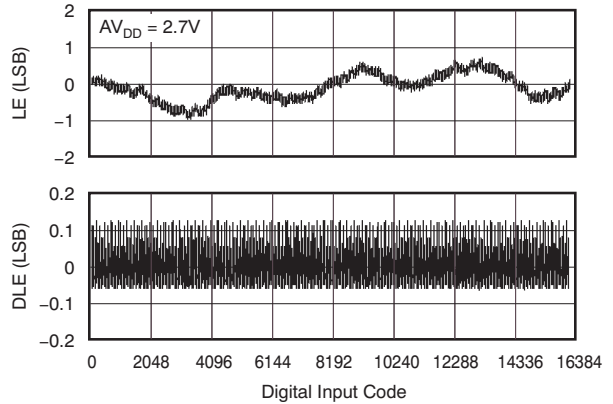


Figure 49. DAC8311 14-Bit Linearity Error and Differential Linearity Error vs Code (125°C)

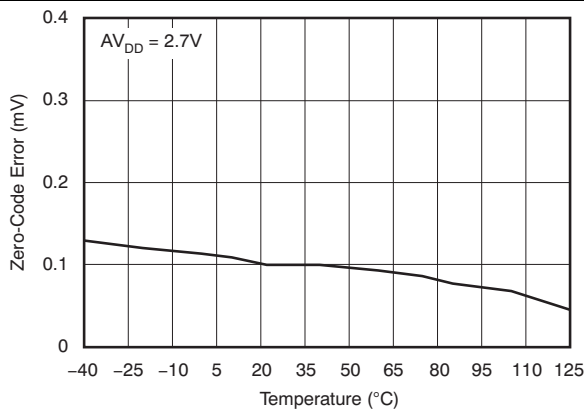


Figure 50. Zero-Code Error vs Temperature

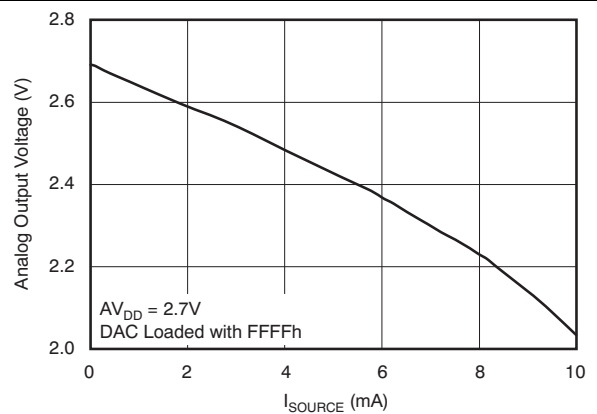


Figure 51. Source Current at Positive Rail

Typical Characteristics: $AV_{DD} = 2.7\text{ V}$ (continued)

at $T_A = 25^\circ\text{C}$, and $AV_{DD} = 2.7\text{ V}$, unless otherwise noted.

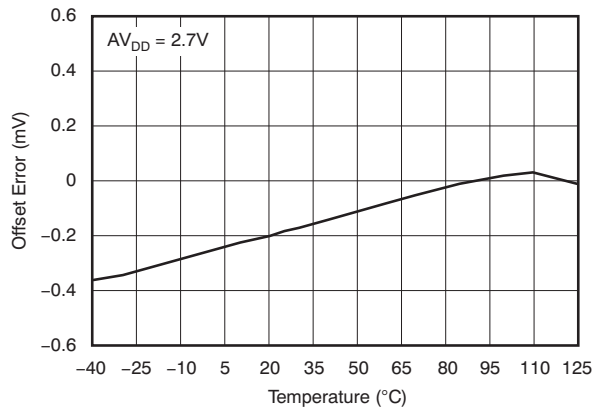


Figure 52. Offset Error vs Temperature

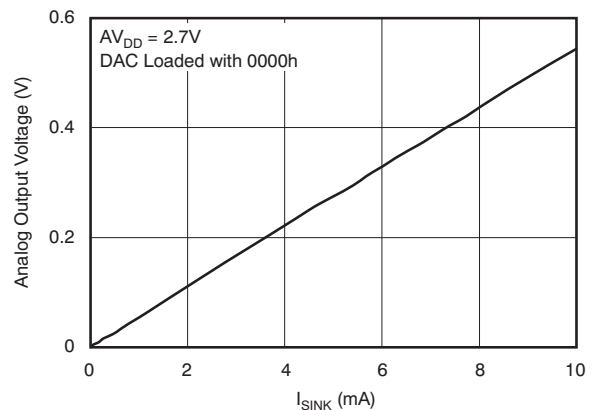


Figure 53. Sink Current at Negative Rail

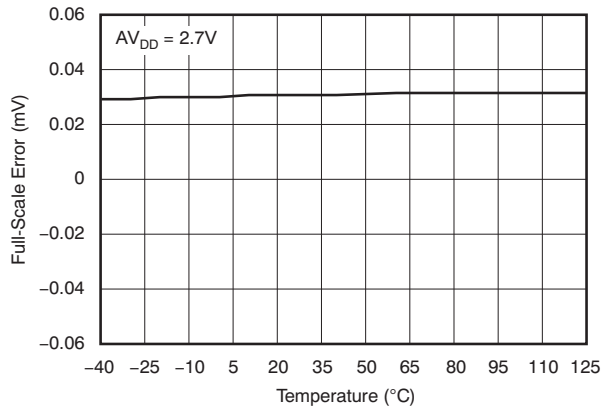


Figure 54. Full-Scale Error vs Temperature

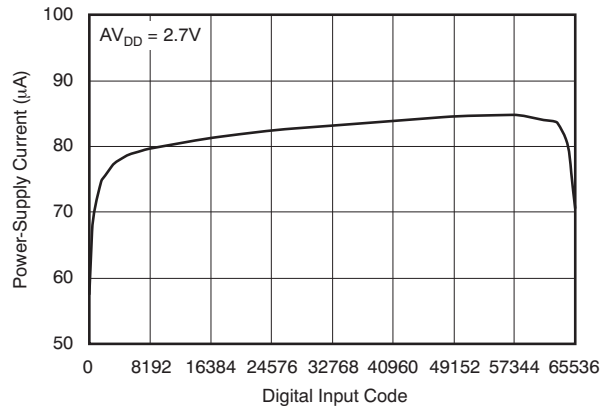


Figure 55. Power-Supply Current vs Digital Input Code

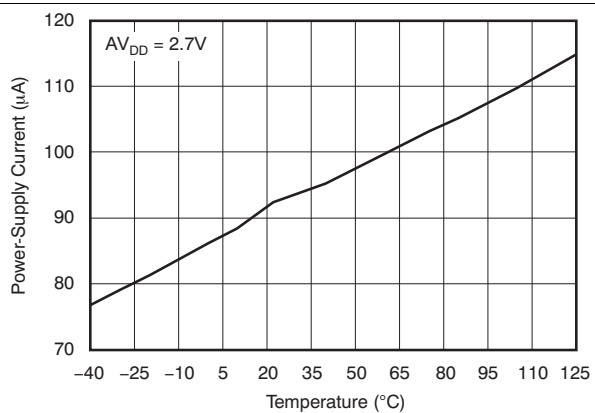


Figure 56. Power-Supply Current vs Temperature

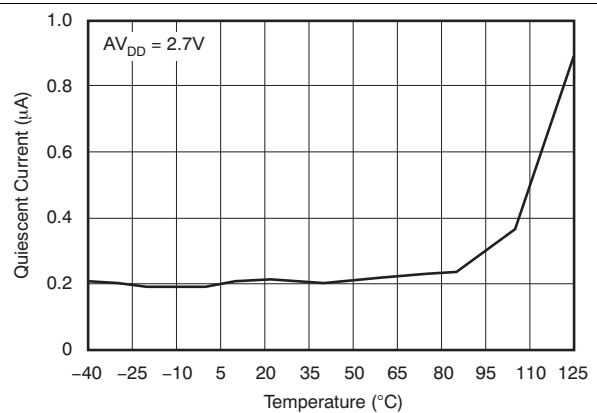
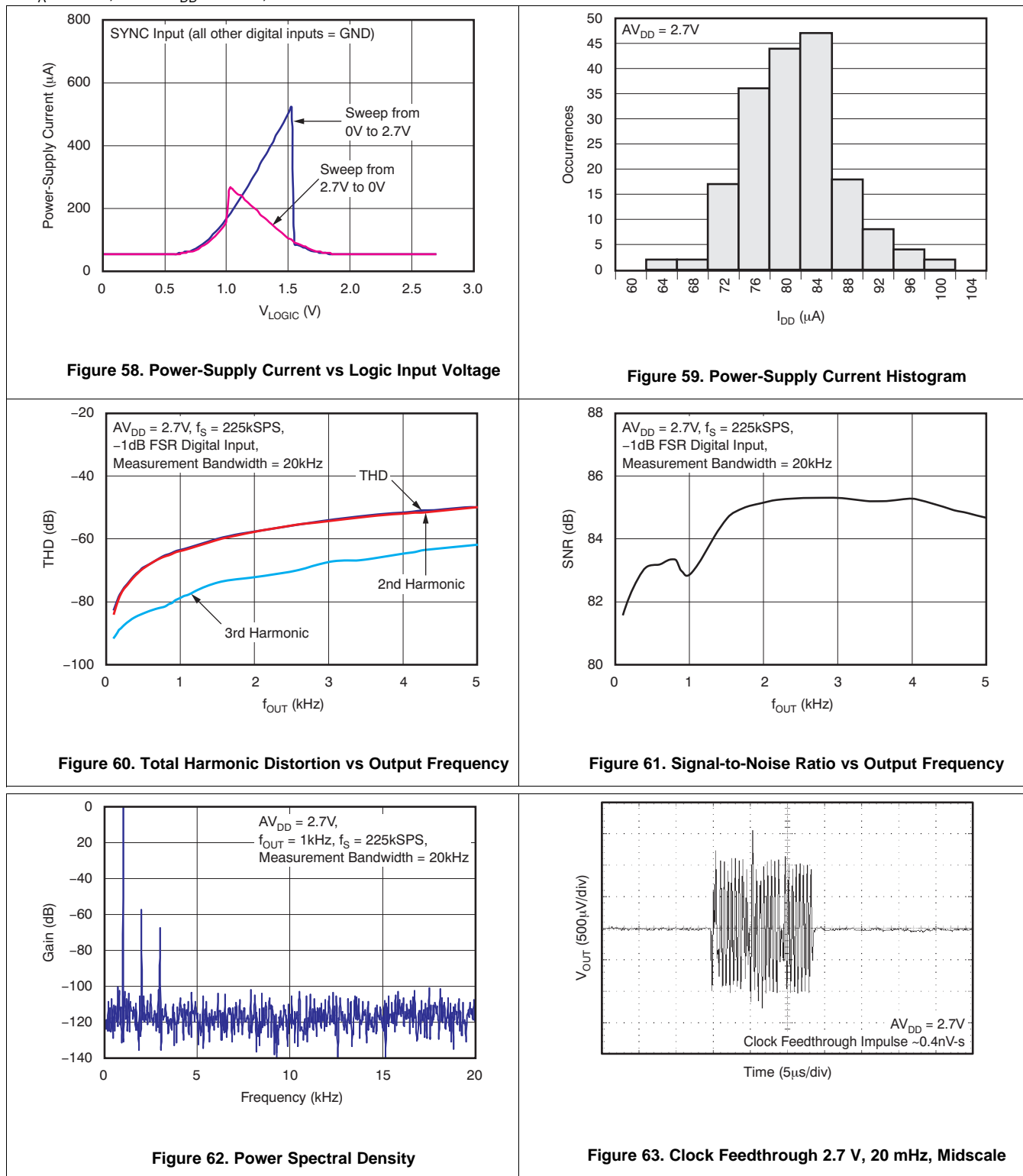


Figure 57. Power-Down Current vs Temperature

Typical Characteristics: $AV_{DD} = 2.7\text{ V}$ (continued)

at $T_A = 25^\circ\text{C}$, and $AV_{DD} = 2.7\text{ V}$, unless otherwise noted.



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Typical Characteristics: $V_{DD} = 2.7 \text{ V}$ (continued)

at $T_A = 25^\circ\text{C}$, and $V_{DD} = 2.7 \text{ V}$, unless otherwise noted.

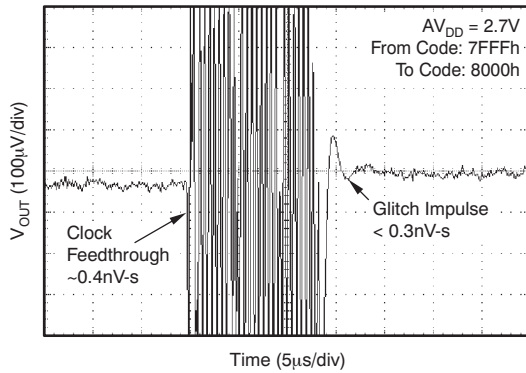


Figure 64. Glitch Energy 2.7 V, 16-Bit, 1LSB Step, Rising Edge

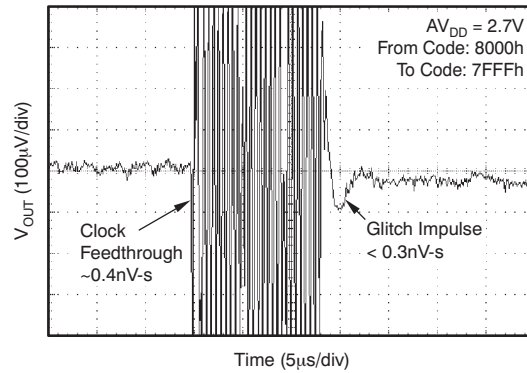


Figure 65. Glitch Energy 2.7 V, 16-Bit, 1LSB Step, Falling Edge

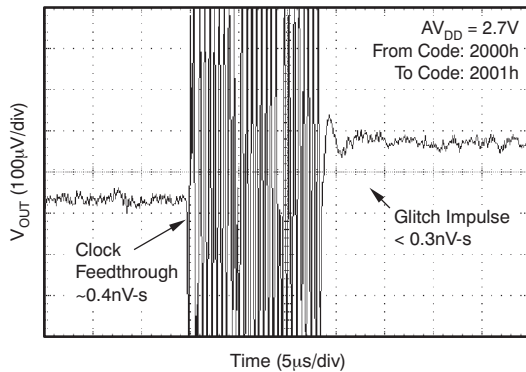


Figure 66. Glitch Energy 2.7 V, 14-Bit, 1LSB Step, Rising Edge

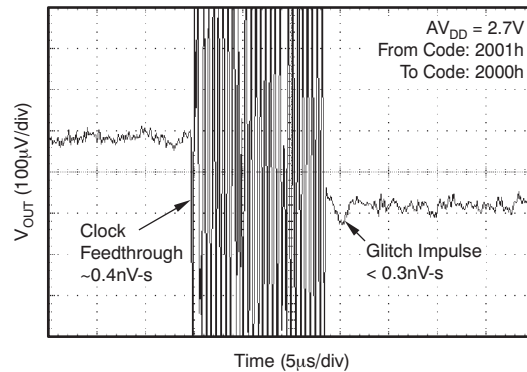


Figure 67. Glitch Energy 2.7 V, 14-Bit, 1LSB Step, Falling Edge

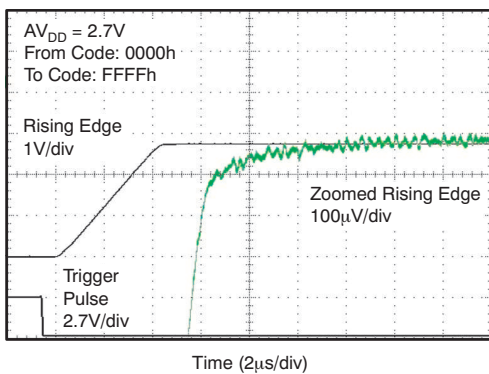


Figure 68. Full-Scale Settling Time 2.7 V Rising Edge

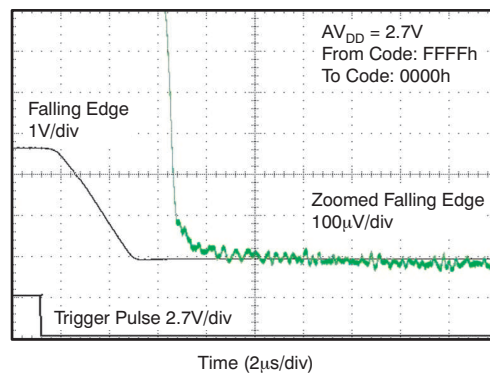


Figure 69. Full-Scale Settling Time 2.7 V Falling Edge

Typical Characteristics: $V_{DD} = 2.7$ V (continued)

at $T_A = 25^\circ\text{C}$, and $V_{DD} = 2.7$ V, unless otherwise noted.

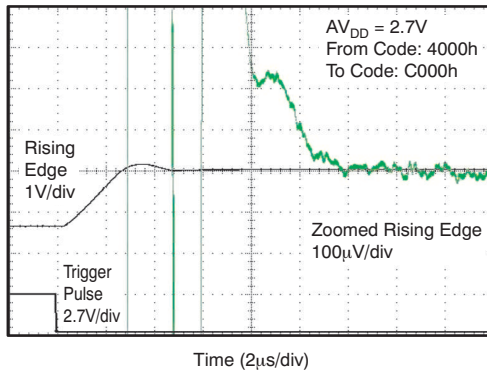


Figure 70. Half-Scale Settling Time 2.7 V Rising Edge

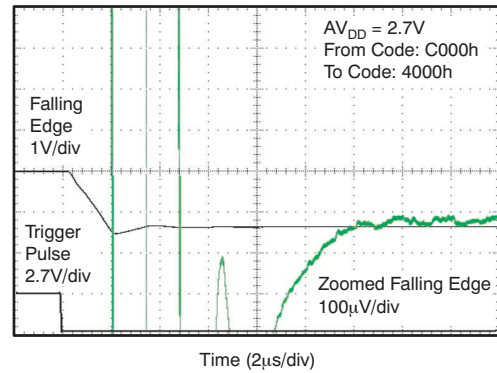


Figure 71. Half-Scale Settling Time 2.7 V Falling Edge

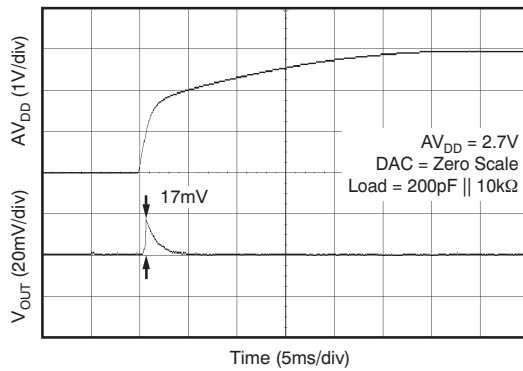


Figure 72. Power-On Reset to 0-V Power-On Glitch

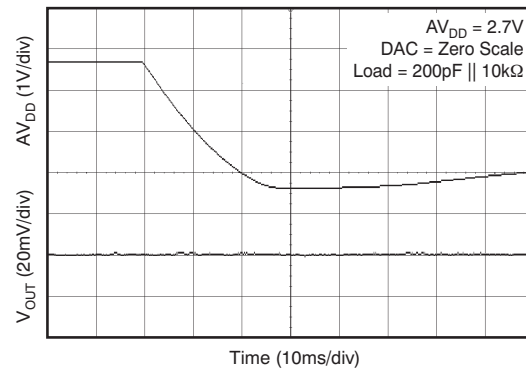


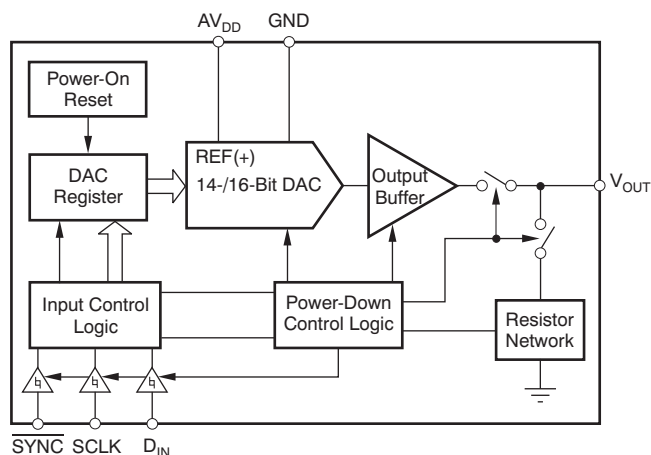
Figure 73. Power-Off Glitch

8 Detailed Description

8.1 Overview

The DAC8x11 family of devices are low-power, single-channel, voltage output DACs. These devices are monotonic by design, provide excellent linearity, and minimize undesired code-to-code transient voltages while offering an easy upgrade path within a pin-compatible family. All devices use a versatile, 3-wire serial interface that operates at clock rates of up to 50 MHz and is compatible with standard SPI, QSPI, Microwire, and digital signal processor (DSP) interfaces.

8.2 Functional Block Diagram



8.3 Feature Description

8.3.1 DAC Section

The DAC8311 and DAC8411 are fabricated using Texas Instruments' proprietary HPA07 process technology. The architecture consists of a string DAC followed by an output buffer amplifier. Because there is no reference input pin, the power supply (AV_{DD}) acts as the reference. Figure 74 shows a block diagram of the DAC architecture.

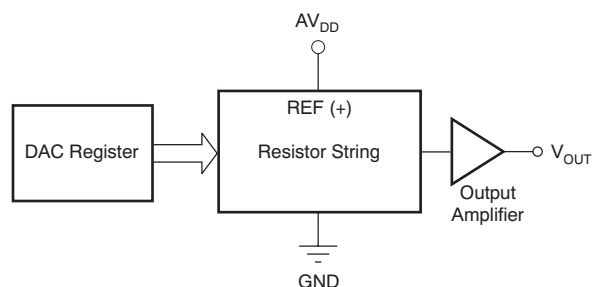


Figure 74. DAC8x11 Architecture

The input coding to the DAC8311 and DAC8411 is straight binary, so the ideal output voltage is given by:

$$V_{OUT} = AV_{DD} \times \frac{D}{2^n}$$

where

- n = resolution in bits; either 14 (DAC8311) or 16 (DAC8411).
- D = decimal equivalent of the binary code that is loaded to the DAC register; it ranges from 0 to 16,383 for the 14-bit DAC8311, or 0 to 65,535 for the 16-bit DAC8411.

Feature Description (continued)

8.3.2 Resistor String

The resistor string section is shown in Figure 75. It is simply a string of resistors, each of value R . The code loaded into the DAC register determines at which node on the string the voltage is tapped off to be fed into the output amplifier by closing one of the switches connecting the string to the amplifier. The resistor string architecture is inherently monotonic.

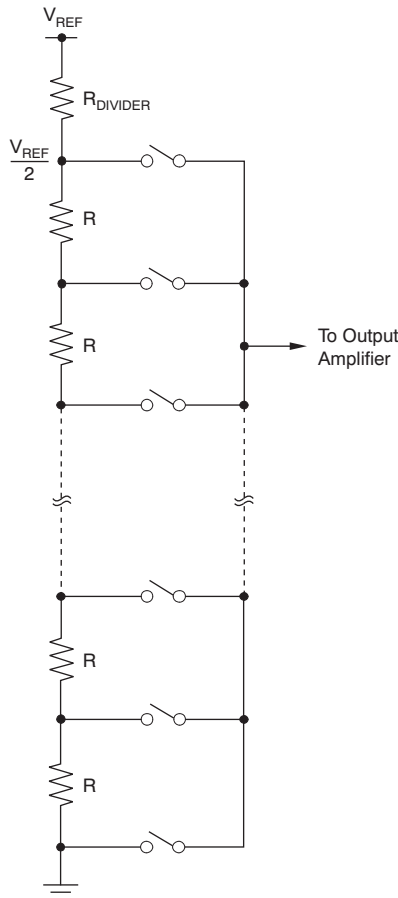


Figure 75. Resistor String

8.3.3 Output Amplifier

The output buffer amplifier is capable of generating rail-to-rail voltages on its output which gives an output range of 0V to AV_{DD} . The output amplifier is capable of driving a load of 2 k Ω in parallel with 1000 pF to GND. The source and sink capabilities of the output amplifier can be seen in the Typical Characteristics section for each device. The slew rate is 0.7 V/ μ s with a half-scale settling time of typically 6 μ s with the output unloaded.

8.3.4 Power-On Reset to Zero-Scale

The DAC8x11 contains a power-on reset circuit that controls the output voltage during power up. On power up, the DAC register is filled with zeros and the output voltage is 0 V. The DAC register remains that way until a valid write sequence is made to the DAC. This design is useful in applications where it is important to know the state of the output of the DAC while it is in the process of powering up.

The occurring power-on glitch impulse is only a few mV (typically, 17 mV; see Figure 31, Figure 72, or Figure 31).

8.4 Device Functional Modes

8.4.1 Power-Down Modes

The DAC8x11 contains four separate modes of operation. These modes are programmable by setting two bits (PD1 and PD0) in the control register. Table 3 shows how the state of the bits corresponds to the mode of operation of the device.

Table 3. Modes of Operation for the DAC8x11

PD1	PD0	OPERATING MODE
NORMAL MODE		
0	0	Normal Operation
POWER-DOWN MODES		
0	1	Output 1 kΩ to GND
1	0	Output 100 kΩ to GND
1	1	High-Z

When both bits are set to 0, the device works normally with a standard power consumption of typically 80 μA at 2 V. However, for the three power-down modes, the typical supply current falls to 0.5 μA at 5 V, 0.4 μA at 3 V, and 0.1 μA at 2.0 V. Not only does the supply current fall, but the output stage is also internally switched from the output of the amplifier to a resistor network of known values. The advantage of this architecture is that the output impedance of the part is known while the part is in power-down mode. There are three different options. The output is connected internally to GND either through a 1-kΩ resistor or a 100-kΩ resistor, or is left open-circuited (High-Z). See Figure 76 for the output stage.

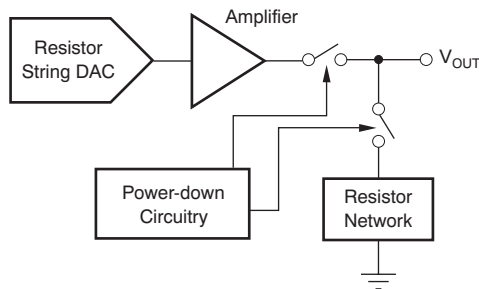


Figure 76. Output Stage During Power-Down

All linear circuitry is shut down when the power-down mode is activated. However, the contents of the DAC register are unaffected when in power-down. The time to exit power-down is typically 50 μs for $A_{V_{DD}} = 5\text{ V}$ and $A_{V_{DD}} = 3\text{ V}$. See the [Typical Characteristics: \$A_{V_{DD}} = 5\text{ V}\$](#) for each device for more information.

DAC8311, DAC8411

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www.ti.com

At this point, the $\overline{\text{SYNC}}$ line may be kept low or brought high. In either case, it must be brought high for a minimum of 20 ns before the next write sequence so that a falling edge of $\overline{\text{SYNC}}$ can initiate the next write sequence. As previously mentioned, it must be brought high again before the next write sequence.

The $\overline{\text{SYNC}}$ line may be brought high after the 18th bit is clocked in because the last six bits are *don't care*.

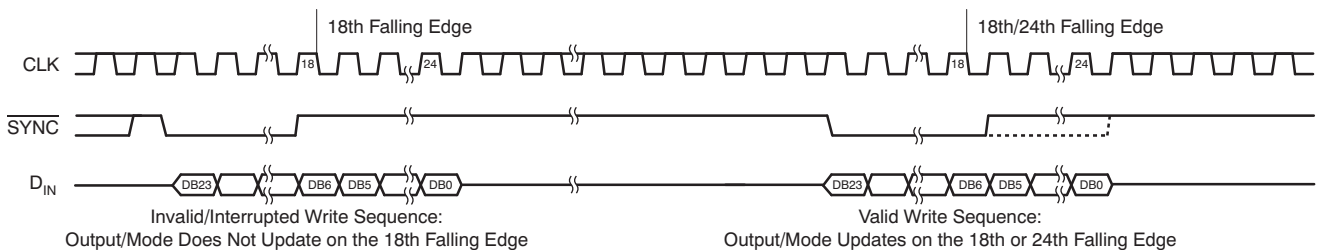
8.5.2.2 DAC8411 $\overline{\text{SYNC}}$ Interrupt

In a normal write sequence, the $\overline{\text{SYNC}}$ line is kept low for 24 falling edges of SCLK and the DAC is updated on the 18th falling edge, ignoring the last six *don't care* bits. However, bringing $\overline{\text{SYNC}}$ high before the 18th falling edge acts as an interrupt to the write sequence. The shift register is reset and the write sequence is seen as invalid. Neither an update of the DAC register contents or a change in the operating mode occurs, as shown in Figure 80.

Figure 79. DAC8411 Data Input Register

DB23							
PD1	PD0	D15	D14	D13	D12	D11	D10
D9	D8	D7	D6	D5	D4	D3	D2
DB7		DB6		DB5			
D1	D0	X	X	X	X	X	X

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

**Figure 80. DAC8411 $\overline{\text{SYNC}}$ Interrupt Facility**

9 Application and Implementation

NOTE

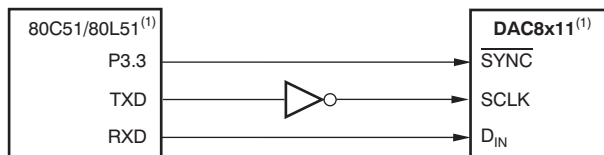
Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

9.1 Application Information

9.1.1 Microprocessor Interfacing

9.1.1.1 DAC8x11 to 8051 Interface

Figure 81 shows a serial interface between the DAC8x11 and a typical 8051-type microcontroller. The setup for the interface is as follows: TXD of the 8051 drives SCLK of the DAC8x11, while RXD drives the serial data line of the part. The SYNC signal is derived from a bit programmable pin on the port. In this case, port line P3.3 is used. When data are to be transmitted to the DAC8x11, P3.3 is taken low. The 8051 transmits data only in 8-bit bytes; thus, only eight falling clock edges occur in the transmit cycle. To load data to the DAC, P3.3 remains low after the first eight bits are transmitted, and a second write cycle is initiated to transmit the second byte of data. P3.3 is taken high following the completion of this cycle. The 8051 outputs the serial data in a format which has the LSB first. The DAC8x11 requires its data with the MSB as the first bit received. Therefore, the 8051 transmit routine must take this requirement into account, and *mirror* the data as needed.

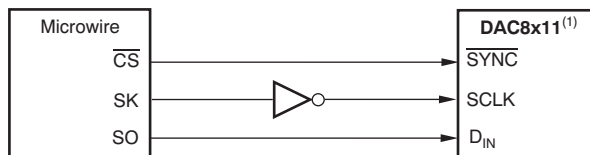


NOTE: (1) Additional pins omitted for clarity.

Figure 81. DAC8x11 to 80C51/80I51 Interfaces

9.1.1.2 DAC8x11 to Microwire Interface

Figure 82 shows an interface between the DAC8x11 and any Microwire-compatible device. Serial data are shifted out on the falling edge of the serial clock and are clocked into the DAC8x11 on the rising edge of the SK signal.



NOTE: (1) Additional pins omitted for clarity.

Figure 82. DAC8x11 to Microwire Interface

Typical Applications (continued)

The complete design of this circuit is outlined in [TIPD158, Low Cost Loop-Powered 4-20mA Transmitter EMC/EMI Tested Reference Design](#). The design is expected to be low-cost and deliver immunity to the IEC61000-4 suite of tests with minimum impact on the accuracy of the system. Reference design [TIPD158](#) includes the design goals, simulated results, and measured performance.

9.2.1.2 Detailed Design Procedure

Amplifier U1 uses negative feedback to make sure that the potentials at the inverting (V–) and noninverting (V+) input terminals are equal. In this configuration, V– is directly tied to the local GND; therefore, the potential at the noninverting input terminal is driven to local ground. Thus, the voltage difference across R₂ is the DAC output voltage (V_{OUT}), and the voltage difference across R₅ is the regulator voltage (V_{REG}). These voltage differences cause currents to flow through R₂ and R₅, as illustrated in [Figure 85](#).

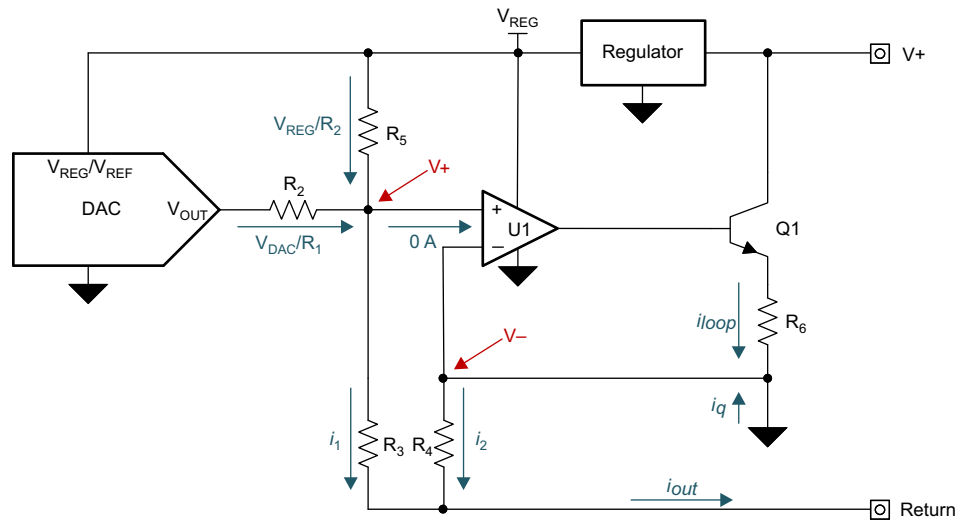


Figure 85. Voltage to Current Conversion

The currents from R₂ and R₅ sum into i₁ (defined in [Equation 1](#)), and i₁ flows through R₃.

$$i_1 = \frac{V_{DAC}}{R_2} + \frac{V_{REG}}{R_5} \tag{1}$$

Amplifier U2 drives the base of Q1, the NPN bipolar junction transistor (BJT), to allow current to flow through R₄ so that the voltage drops across R₃ and R₄ remain equal. This design keeps the inverting and noninverting terminals at the same potential. A small part of the current through R₄ is sourced by the quiescent current of all of the components used in the transmitter design (regulator, amplifier, and DAC). The voltage drops across R₃ and R₄ are equal; therefore, different-sized resistors cause different current flow through each resistor. Use these different-sized resistors to apply gain to the current flow through R₄ by controlling the ratio of resistor R₃ to R₄, as shown in [Equation 2](#):

$$\begin{aligned} V_+ &= i_1 \cdot R_3 \\ V_- &= i_2 \cdot R_4 \Rightarrow i_2 = \frac{i_1 \cdot R_3}{R_4} \\ V_+ &= V_- \end{aligned} \tag{2}$$

The current gain in the circuit helps allow a majority of the output current to come directly from the loop through Q1 instead of from the voltage-to-current converter. This current gain, in addition to the low-power components, keeps the current consumption of the voltage-to-current converter low. Currents i₁ and i₂ sum to form output current i_{out}, as shown in [Equation 3](#):

$$i_{out} = i_1 + i_2 = \frac{V_{DAC}}{R_2} + \frac{V_{REG}}{R_5} + \frac{R_3}{R_4} \cdot \left(\frac{V_{DAC}}{R_2} + \frac{V_{REG}}{R_5} \right) = \left(\frac{V_{DAC}}{R_2} + \frac{V_{REG}}{R_5} \right) \cdot \left(1 + \frac{R_3}{R_4} \right) \tag{3}$$

Typical Applications (continued)

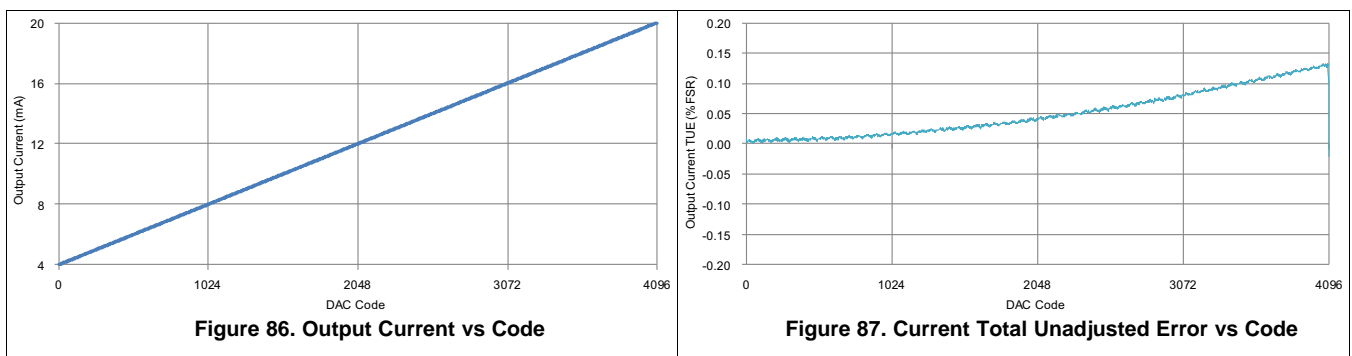
The complete transfer function, arranged as a function of input code, is shown in Equation 4. The remaining sections divide this circuit into blocks for simplified discussion.

$$i_{out}(\text{Code}) = \left(\frac{V_{REG} \cdot \text{Code}}{2^{R_{Resolution}} \cdot R_2} + \frac{V_{REG}}{R_5} \right) \cdot \left(1 + \frac{R_3}{R_4} \right) \quad (4)$$

Resistor R₆ is included to reduce the gain of transistor Q1, and therefore, reduce the closed-loop gain of the voltage-to-current converter for a stable design. Size resistors R₂, R₃, R₄, and R₅ based on the full-scale range of the DAC, regulator voltage, and the desired current output range of the design.

9.2.1.3 Application Curves

Figure 86 shows the measured transfer function of the circuit. Figure 87 shows the total unadjusted error (TUE) of the circuit, staying below 0.15 %FSR.



9.2.2 Using the REF5050 as a Power Supply for the DAC8x11

As a result of the extremely low supply current required by the DAC8x11, an alternative option is to use a REF5050 5 V precision voltage reference to supply the required voltage to the part, as shown in Figure 88. This option is especially useful if the power supply is too noisy or if the system supply voltages are at some value other than 5 V. The REF5050 outputs a steady supply voltage for the DAC8x11. If the REF5050 is used, the current needed to supply DAC8x11 is typically 110 μA at 5V, with no load on the output of the DAC. When the DAC output is loaded, the REF5050 also needs to supply the current to the load. The total current required (with a 5-kΩ load on the DAC output) is:

$$110 \mu\text{A} + (5 \text{ V} / 5 \text{ k}\Omega) = 1.11 \text{ mA}$$

The load regulation of the REF5050 is typically 0.002%/mA, resulting in an error of 90 μV for the 1.1 -mA current drawn from it. This value corresponds to a 1.1 LSB error at 16bit (DAC8411).

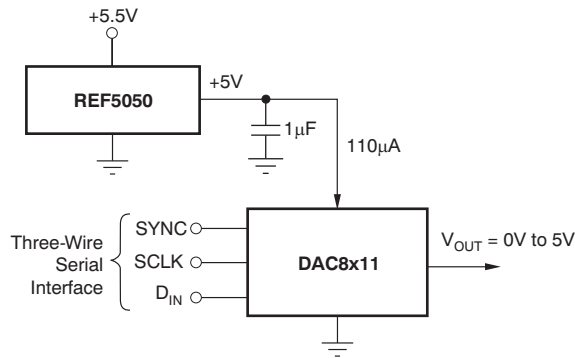


Figure 88. REF5050 as Power Supply to DAC8x11

Typical Applications (continued)

For other power-supply voltages, alternative references such as the REF3030 (3 V), REF3033 (3.3 V), or REF3220 (2.048 V) are recommended. For a full list of available voltage references from TI, see TI web site at www.ti.com.

9.2.3 Bipolar Operation Using the DAC8x11

The DAC8x11 has been designed for single-supply operation but a bipolar output range is also possible using the circuit in Figure 89. The circuit shown gives an output voltage range of ±5V. Rail-to-rail operation at the amplifier output is achievable using an OPA211, OPA340, or OPA703 as the output amplifier. For a full list of available operational amplifiers from TI, see TI web site at www.ti.com

The output voltage for any input code can be calculated as follows:

$$V_O = \left[AV_{DD} \times \left(\frac{D}{2^n} \right) \times \left(\frac{R_1 + R_2}{R_1} \right) - AV_{DD} \times \left(\frac{R_2}{R_1} \right) \right]$$

where

- n = resolution in bits; either 14 (DAC8311) or 16 (DAC8411).
 - D = the input code in decimal; either 0 to 16,383 (DAC8311) or 0 to 65,535 (DAC8411).
- (5)

With $AV_{DD} = 5\text{ V}$, $R_1 = R_2 = 10\text{ k}\Omega$:

$$V_O = \left(\frac{10 \times D}{2^n} \right) - 5V$$
(6)

The resulting output voltage range is ±5V. Code 000h corresponds to a –5-V output and FFFFh (16-bit level) corresponding to a 5-V output.

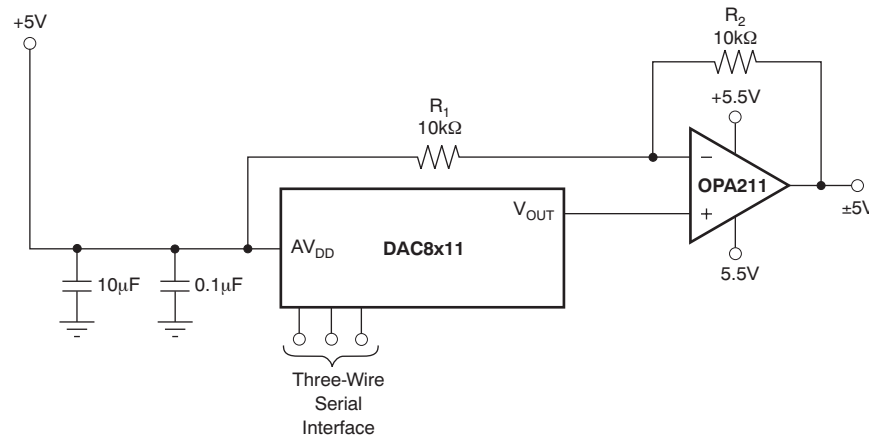


Figure 89. Bipolar Operation With the DAC8x11

10 Power Supply Recommendations

The DAC8x11 is designed to operate with a unipolar analog power supply ranging from 2 V to 5.5 V on the AV_{DD} pin. The AV_{DD} pin supplies power to the digital and analog circuits (including the resistor string) inside the DAC. The current consumption of this pin is specified in the [Electrical Characteristics](#) table. Use a 1-µF to 10-µF capacitor in parallel with a 0.1-µF bypass capacitor on this pin to remove high-frequency noise.

11 Layout

11.1 Layout Guidelines

A precision analog component requires careful layout, adequate bypassing, and clean, well-regulated power supplies.

The DAC8x11 offers single-supply operation; it will often be used in close proximity with digital logic, microcontrollers, microprocessors, and digital signal processors. The more digital logic present in the design and the higher the switching speed, the more difficult it will be to achieve good performance from the converter.

Because of the single ground pin of the DAC8x11, all return currents, including digital and analog return currents, must flow through the GND pin. Ideally, GND would be connected directly to an analog ground plane. This plane would be separate from the ground connection for the digital components until they were connected at the power entry point of the system.

The power applied to AV_{DD} should be well-regulated and low-noise. Switching power supplies and dc/dc converters often have high-frequency glitches or spikes riding on the output voltage. In addition, digital components can create similar high-frequency spikes as the internal logic switches state. This noise can easily couple into the DAC output voltage through various paths between the power connections and analog output. This condition is particularly true for the DAC8x11, as the power supply is also the reference voltage for the DAC.

As with the GND connection, AV_{DD} should be connected to a 5 V power supply plane or trace that is separate from the connection for digital logic until they are connected at the power entry point. In addition, TI strongly recommends the 1 μF to 1 μF and 0.1 μF bypass capacitors. In some situations, additional bypassing may be required, such as a 100 μF electrolytic capacitor or even a π filter made up of inductors and capacitors—all designed to essentially low-pass filter the 5 V supply, removing the high-frequency noise.

11.2 Layout Example

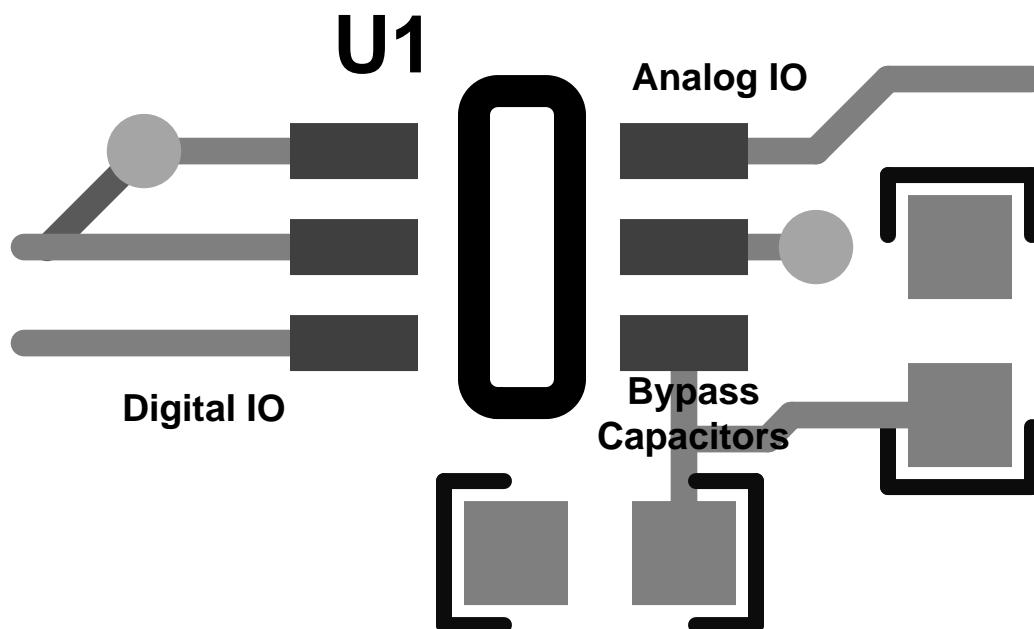


Figure 90. Recommended Layout

12 Device and Documentation Support

12.1 Related Links

The table below lists quick access links. Categories include technical documents, support and community resources, tools and software, and quick access to sample or buy.

Table 4. Related Links

PARTS	PRODUCT FOLDER	SAMPLE & BUY	TECHNICAL DOCUMENTS	TOOLS & SOFTWARE	SUPPORT & COMMUNITY
DAC8311	Click here	Click here	Click here	Click here	Click here
DAC8411	Click here	Click here	Click here	Click here	Click here

12.2 Community Resources

The following links connect to TI community resources. Linked contents are provided "AS IS" by the respective contributors. They do not constitute TI specifications and do not necessarily reflect TI's views; see TI's [Terms of Use](#).

TI E2E™ Online Community *TI's Engineer-to-Engineer (E2E) Community*. Created to foster collaboration among engineers. At e2e.ti.com, you can ask questions, share knowledge, explore ideas and help solve problems with fellow engineers.

Design Support *TI's Design Support* Quickly find helpful E2E forums along with design support tools and contact information for technical support.

12.3 Trademarks

E2E is a trademark of Texas Instruments.
SPI, QSPI are trademarks of Motorola, Inc.
All other trademarks are the property of their respective owners.

12.4 Electrostatic Discharge Caution



These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

12.5 Glossary

SLYZ022 — *TI Glossary*.

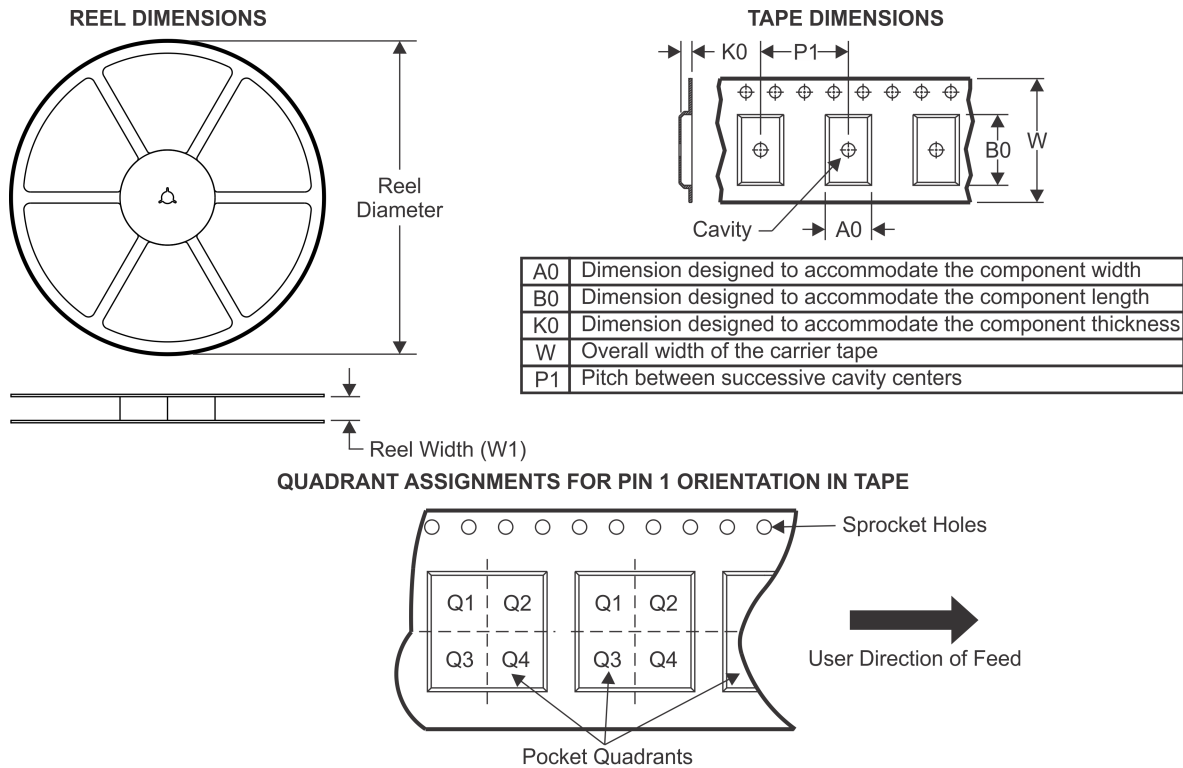
This glossary lists and explains terms, acronyms, and definitions.

13 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

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TAPE AND REEL INFORMATION


*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
DAC8311IDCKR	SC70	DCK	6	3000	177.8	9.7	2.3	2.52	1.2	4.0	8.0	Q3
DAC8311IDCKT	SC70	DCK	6	250	177.8	9.7	2.3	2.52	1.2	4.0	8.0	Q3
DAC8411IDCKR	SC70	DCK	6	3000	177.8	9.7	2.3	2.52	1.2	4.0	8.0	Q3
DAC8411IDCKT	SC70	DCK	6	250	177.8	9.7	2.3	2.52	1.2	4.0	8.0	Q3

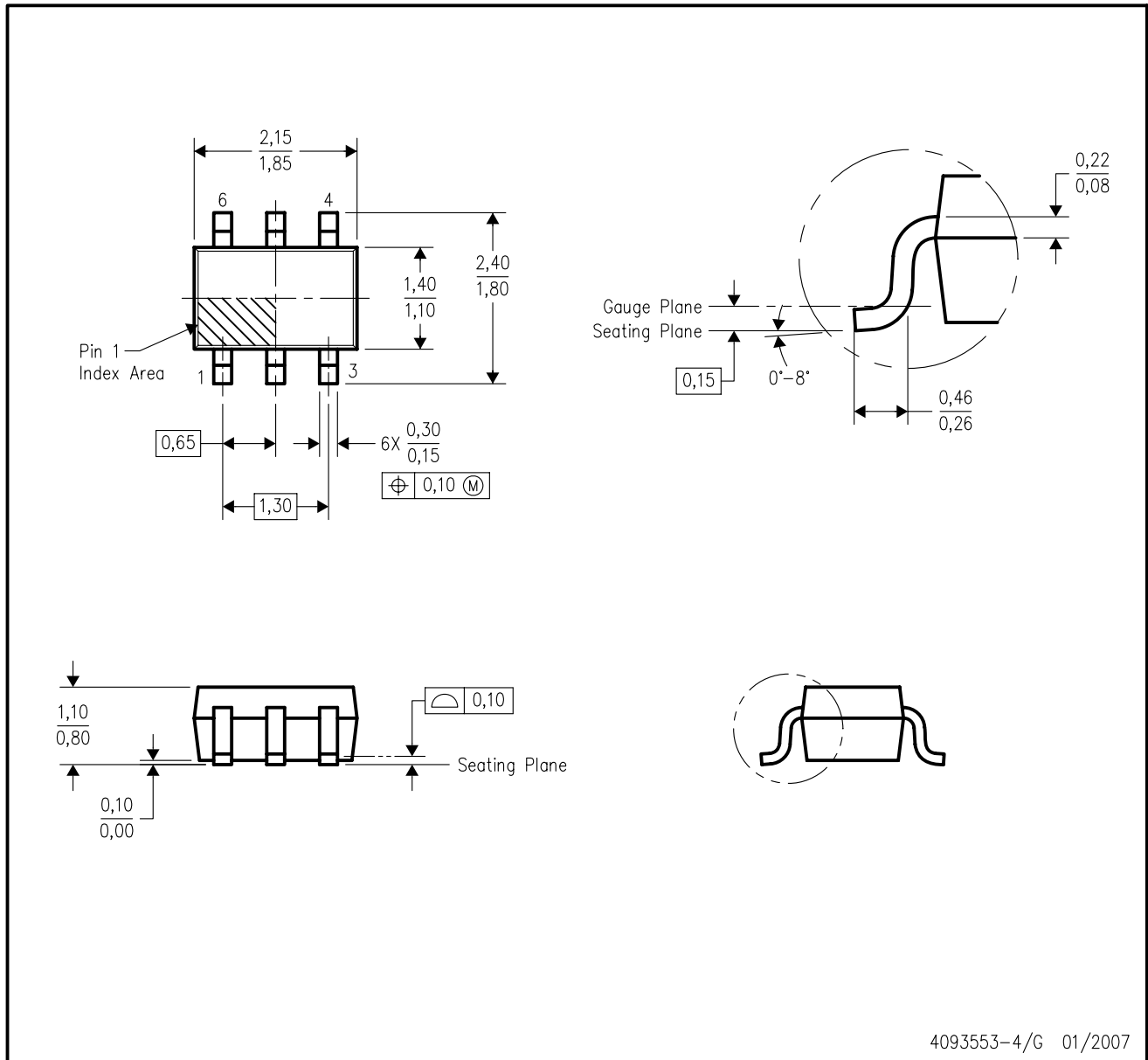
TAPE AND REEL BOX DIMENSIONS


*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
DAC8311IDCKR	SC70	DCK	6	3000	184.0	184.0	50.0
DAC8311IDCKT	SC70	DCK	6	250	184.0	184.0	50.0
DAC8411IDCKR	SC70	DCK	6	3000	184.0	184.0	50.0
DAC8411IDCKT	SC70	DCK	6	250	184.0	184.0	50.0

DCK (R-PDSO-G6)

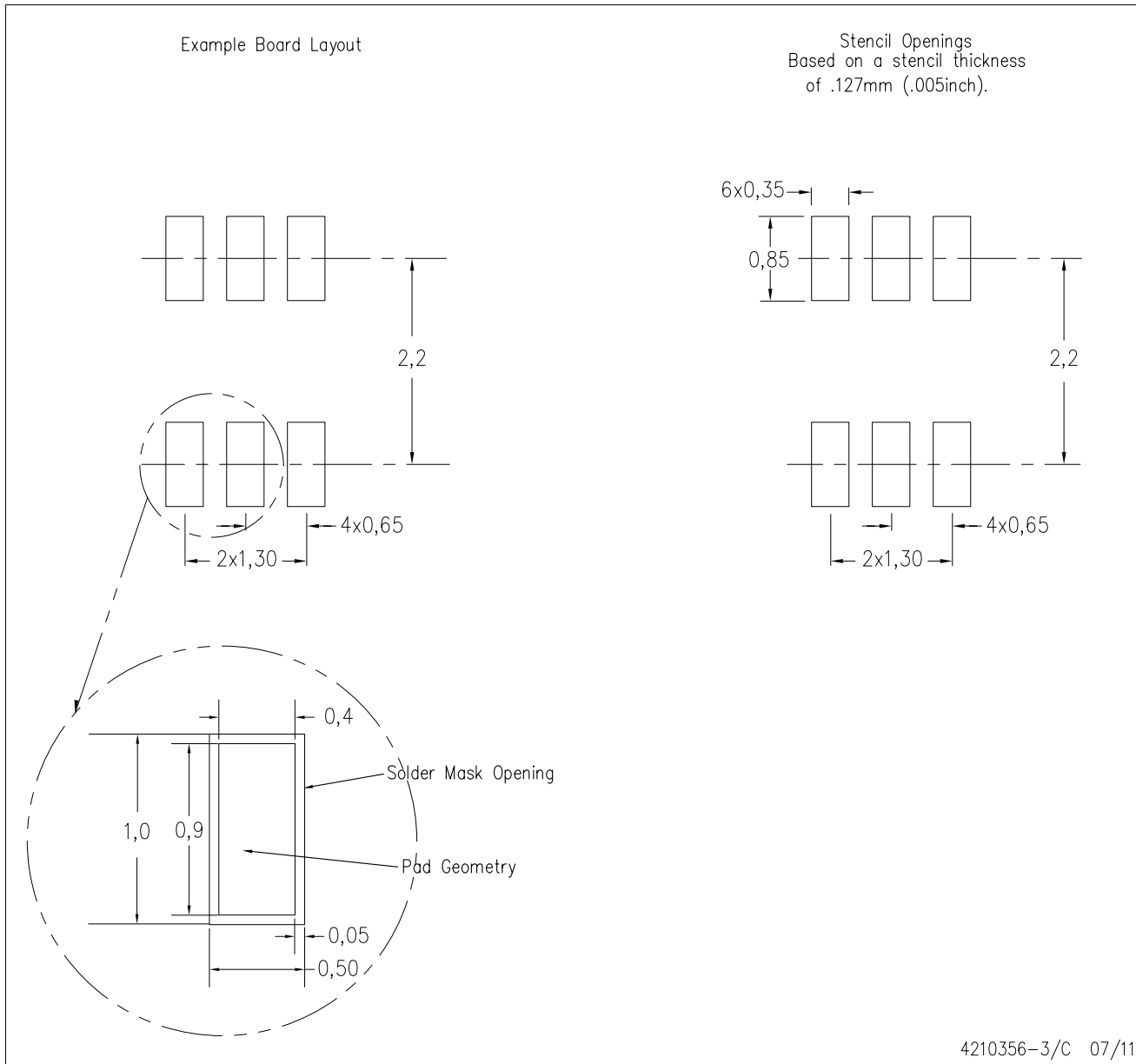
PLASTIC SMALL-OUTLINE PACKAGE



- NOTES:
- A. All linear dimensions are in millimeters.
 - B. This drawing is subject to change without notice.
 - C. Body dimensions do not include mold flash or protrusion. Mold flash and protrusion shall not exceed 0.15 per side.
 - D. Falls within JEDEC MO-203 variation AB.

DCK (R-PDSO-G6)

PLASTIC SMALL OUTLINE



- NOTES:
- A. All linear dimensions are in millimeters.
 - B. This drawing is subject to change without notice.
 - C. Customers should place a note on the circuit board fabrication drawing not to alter the center solder mask defined pad.
 - D. Publication IPC-7351 is recommended for alternate designs.
 - E. Laser cutting apertures with trapezoidal walls and also rounding corners will offer better paste release. Customers should contact their board assembly site for stencil design recommendations. Example stencil design based on a 50% volumetric metal load solder paste. Refer to IPC-7525 for other stencil recommendations.

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-  Excess Inventory Management